Social Interactions: A First-Person Perspective.

> A. Fathi, J. Hodgins, J. Rehg Presented by Jacob Menashe

> > November 16, 2012

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Objective: Detect social interactions from video footage.

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Consider faces and attention

Objective: Detect social interactions from video footage.

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- Consider faces and attention
- Account for temporal context

Objective: Detect social interactions from video footage.

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- Consider faces and attention
- Account for temporal context
- Analyze first-person movements cues

Introduction

Overview Features

Temporal Context

Experiments

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Video Example

Red	Dialogue
Yellow	Walking Dialogue
Green	Discussion
Light Blue	Walking Discussion
Dark Blue	Monologue
None	Background

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Link

Features are constructed based on first- and third-person information.

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1. Dense optical flow (first-person movement).

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- 2. Face locations (relative to first person)

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- 2. Face locations (relative to first person)
- 3. Attention and Roles. For each person *x*:

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 - Faces looking at x

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- 1. Dense optical flow (first-person movement).
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 - Whether first person looks at x

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- 1. Dense optical flow (first-person movement).
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- 3. Attention and Roles. For each person *x*:
 - Faces looking at x
 - Whether first person looks at x
 - Mutual attention between x and first person
 - Number of faces looking at where x is looking

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Feature Example







(b)















(e)

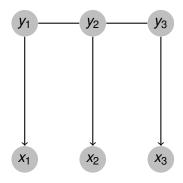


(f)

CRFs are described in Lafferty et al. [2001].

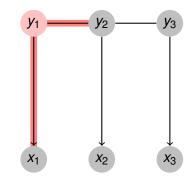
CRFs are described in Lafferty et al. [2001].

- Observations and labels form a Markov chain.
- Nodes pend on neighbors.



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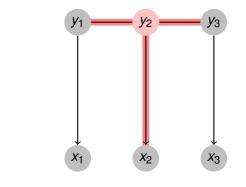


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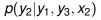
 $p(y_1|x_1,y_2)$

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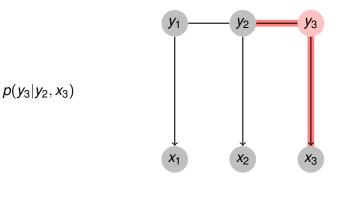


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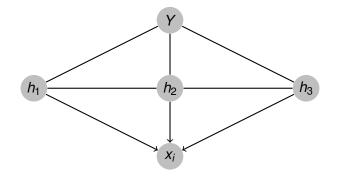
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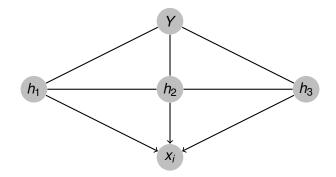
A micro view of the HCRF model as described in Quattoni et al. [2007].



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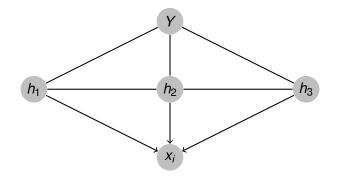
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> Y is a label for the whole sequence.



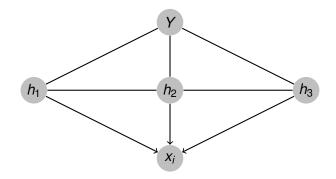
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- > Y is a label for the whole sequence.
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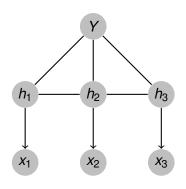


A micro view of the HCRF model as described in Quattoni et al. [2007].

- > Y is a label for the whole sequence.
- x_i is a single observation in the sequence.
- Each h_i is a possible hidden state.

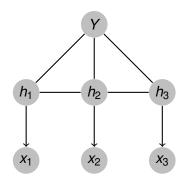


A macro view of the HCRF model as described in Quattoni et al. [2007].



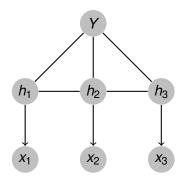
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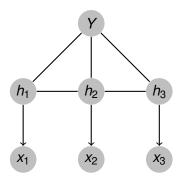
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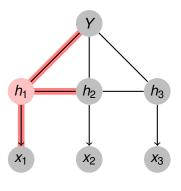
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- > Y is a label for the whole sequence.
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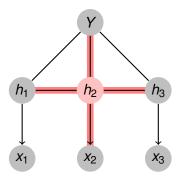


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 $p(h_1|Y, h_2, x_1)$

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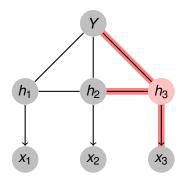


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 $p(h_2|Y, h_1, h_3, x_2)$

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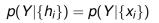


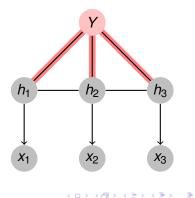
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 $p(h_3|Y, h_2, x_3)$

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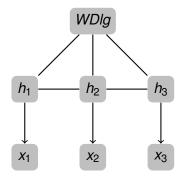
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HCRF Example

Suppose we want to find the likelihood of "walking dialogue" (*WDlg*) vs "walking discussion" (*WDisc*).

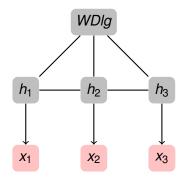


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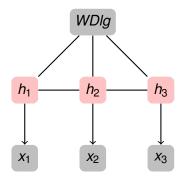


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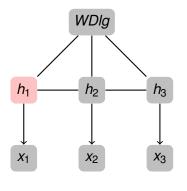
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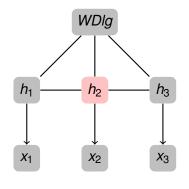
Suppose we want to find the likelihood of "walking dialogue" (*WDlg*) vs "walking discussion" (*WDisc*).

- Each x_i is now a feature extracted from video frames.
- Each h_i is determined from training:
 - h_1 : John wants to hear about my weekend.



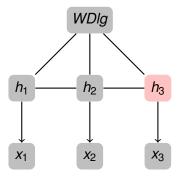
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 - ► *h*₂: I'm feeling talkative.



Suppose we want to find the likelihood of "walking dialogue" (*WDlg*) vs "walking discussion" (*WDisc*).

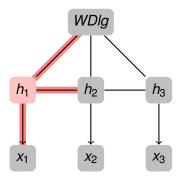
- Each x_i is now a feature extracted from video frames.
- Each h_i is determined from training:
 - h_3 : Mary wants to listen to her iPod.



Suppose we want to find the likelihood of "walking dialogue" (*WDlg*) vs "walking discussion" (*WDisc*).

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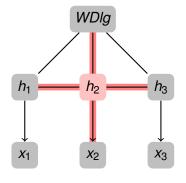
 $p(h_1|Y, h_2, x_1)$



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$$p(h_2|Y, h_1, h_3, x_2)$$

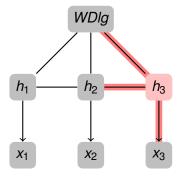


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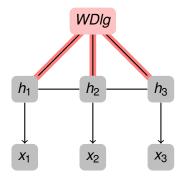
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 - h_1 : John wants to hear about my weekend.
 - h₂: I'm feeling talkative.
 - h_3 : Mary wants to listen to her iPod.

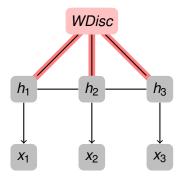
$$p(WDlg|\{h_i\}) = p(WDlg|\{x_i\})$$



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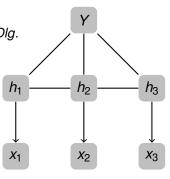
- Each x_i is now a feature extracted from video frames.
- Each h_i is determined from training:
 - h_1 : John wants to hear about my weekend.
 - h₂: I'm feeling talkative.
 - h₃: Mary wants to listen to her iPod.

$$p(WDisc|\{h_i\}) = p(WDisc|\{x_i\})$$



Suppose we want to find the likelihood of "walking dialogue" (*WDlg*) vs "walking discussion" (*WDisc*).

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- Each h_i is determined from training:
 - h₁: John wants to hear about my weekend.
 - h_2 : I'm feeling talkative.
 - h₃: Mary wants to listen to her iPod.
 - If p(WDlg) > p(WDisc), assign Y = WDlg.



Introduction

Overview

Temporal Context Conditional Random Fields Hidden Conditional Random Fields HCRF Example

Experiments



Introduction

Overview

Temporal Context

Experiments Experiment Outline Experiment 1: Video Processing Experiment 2: Caltech Dataset Conclusion

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The following experiments are presented:

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Video Processing

The following experiments are presented:

- Video Processing
- Caltech image dataset

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- Adjusted parameters:

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- Video Processing
- Caltech image dataset
- Adjusted parameters:
 - Iterations

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- Video Processing
- Caltech image dataset
- Adjusted parameters:
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 - Hidden States

The following experiments are presented:

- Video Processing
- Caltech image dataset
- Adjusted parameters:
 - Iterations
 - Hidden States
 - Optimization Function

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The following experiments are presented:

- Video Processing
- Caltech image dataset
- Adjusted parameters:
 - Iterations
 - Hidden States
 - Optimization Function

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Clusters

The following experiments are presented:

- Video Processing
- Caltech image dataset
- Adjusted parameters:
 - Iterations
 - Hidden States
 - Optimization Function
 - Clusters
- Compared with linear SVM baseline

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Experiment 1: Video Processing

Mine	Theirs
40 training intervals	4,000 training intervals
40 testing intervals	[unspecified]
Dialogue vs Discussion	One vs. All
All Features	Location First-Person Motion Attention All Features

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Experiment 1: Video Processing

Mine	Theirs
40 training intervals	4,000 training intervals
40 testing intervals	[unspecified]
Dialogue vs Discussion	One vs. All
All Features	Location First-Person Motion Attention All Features

~42 hours = 11,340 intervals 11,340 intervals @ 24 hours per 20 intervals > 18 months

Experiment 1: Video Processing (cont.)

My Results Their Results DET - different features for detecting dialogue 1 n HCRF Dialogue vs Discussion Detection 0.9 0.9 0.8 0.8 0.7 0.7 Inue positive rate 0.6 물 0.6 0.5 True positive r 70 0.4 0.3 0.3 0.2 Location Features (0.64) 0.2 First-Person Motion Features (0.72) ٥. Attention Features (0.73) 0.1 Al Features (0.82 O. 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.8 False positive rate False positive rate

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Experiment 2 focuses on the Caltech image dataset.

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Multi-class HCRF evaluated

Experiment 2 focuses on the Caltech image dataset.

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- Multi-class HCRF evaluated
- Classes are evaluated in isolation.

Experiment 2 focuses on the Caltech image dataset.

- Multi-class HCRF evaluated
- Classes are evaluated in isolation.
- Temporal context is simulated with clustering

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Experiment 2 focuses on the Caltech image dataset.

- Multi-class HCRF evaluated
- Classes are evaluated in isolation.
- Temporal context is simulated with clustering
- Initial parameters are based on Fathi et al. [2012]:

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Experiment 2 focuses on the Caltech image dataset.

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Hidden States: 5

Experiment 2 focuses on the Caltech image dataset.

- Multi-class HCRF evaluated
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- Hidden States: 5
- Window Size: 5

Experiment 2 focuses on the Caltech image dataset.

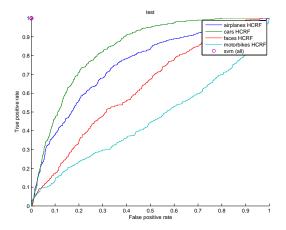
- Multi-class HCRF evaluated
- Classes are evaluated in isolation.
- Temporal context is simulated with clustering
- Initial parameters are based on Fathi et al. [2012]:

- Hidden States: 5
- Window Size: 5
- Max Iterations: 100

Experiment 2 focuses on the Caltech image dataset.

- Multi-class HCRF evaluated
- Classes are evaluated in isolation.
- Temporal context is simulated with clustering
- Initial parameters are based on Fathi et al. [2012]:
 - Hidden States: 5
 - Window Size: 5
 - Max Iterations: 100
 - Optimizer: Broyden–Fletcher-Goldfarb-Shanno (BFGS)

Exp. 2a: Initial Settings



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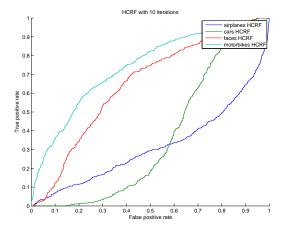
Processing: ~18 minutes, 1 MB

Exp. 2a: Initial Settings (cont.)



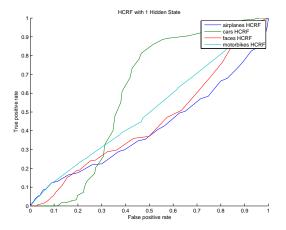
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Exp. 2b: Low Iterations



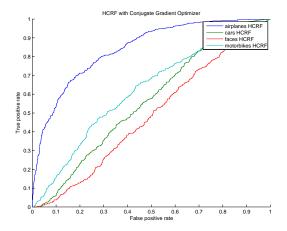
Processing: ~3 minutes, 1 MB

Exp. 2c: Low Hidden States



Processing: ~2 minutes, 1 MB

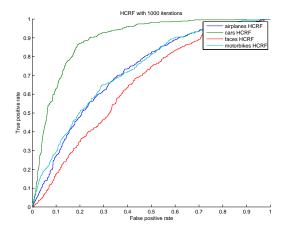
Exp. 2d: CG Optimizer



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Processing: ~11 minutes, 1 MB

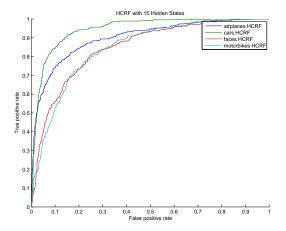
Exp. 2e: Increased Iterations



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Processing: ~30 minutes, 1 MB

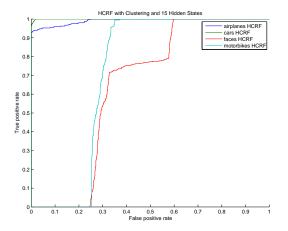
Exp. 2f: Increased Hidden States



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Processing: ~1 hour, 3 GB

Exp. 2g: Clustering + 15 Hidden States



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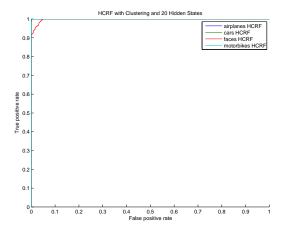
Processing: ~1 hour 10 minutes, 3 GB

Exp. 2g: Clustering + 15 Hidden States (cont.)



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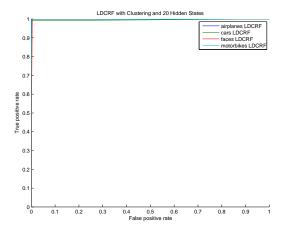
Exp. 2h: Clustering + 20 Hidden States



Processing: ~1 hour 40 minutes, 5 GB

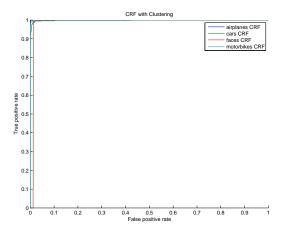
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Exp. 2i: LDCRF with 20 Hidden States



Processing: ~5 hours 20 minutes, 5 GB

Exp. 2j: CRF with Initial Parameters



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Processing: ~21 seconds, 1 MB

Exp. 2j: CRF with Initial Parameters (cont.)



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Overall Results

SVM, CRF, and LDCRF perform best

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- SVM, CRF, and LDCRF perform best
- CRF almost outperforms all with negligible memory and processing requirements

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Overall Results

- SVM, CRF, and LDCRF perform best
- CRF almost outperforms all with negligible memory and processing requirements
- Hidden states increase accuracy but at significant memory cost

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Conclusion

HCRF is accurate, but has a heavy performance cost.

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May be optimal for particular domains.

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