

A minor improvement of Heapsort.

Heapsort is an efficient algorithm for sorting in situ the elements of a linear array $M(i: 0 \leq i < N)$. When sorting the elements in ascending order, the algorithm maintains $H(p)$, defined by

$$H(p): (\forall i, j: p \leq i < j < q \wedge 2 \cdot i < j \leq 2 \cdot (i+1): M(i) \geq M(j))$$

which enjoys the useful property

$$H(0) \Rightarrow (\forall j: 0 \leq j < q: M(0) \geq M(j)) \quad (0)$$

The algorithm has the following form:

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 $p, q := N \text{ div } 2, N; \{H(p)\}$ 
do  $p \neq 0 \rightarrow p := p - 1; \{H(p+1)\}$  sift  $\{H(p)\}$  od;
do  $q > 1 \rightarrow \{H(0)\} q := q - 1; M: \text{swap}(0, q);$ 
     $\{H(p+1)\}$  sift  $\{H(p)\}$ 
od

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Since $p=0$ is a further invariant of the second repetition, property (0) ensures that the sorted sequence is built up "from right to left."

The routine sift establishes - by $w := p$ - and maintains SH, defined by

$$SH: (\forall i, j: p \leq i < j < q \wedge 2 \cdot i < j \leq 2 \cdot (i+1): M(i) \geq M(j) \vee i = w),$$

which enjoys the useful property

$$SH \wedge 2 \cdot w + 1 \geq q \Rightarrow H(p)$$

Routine sift can repeatedly perform under invariance of SH either $w := 2 \cdot w + 1$ or $w := 2 \cdot w + 2$; sift compares each time $M(w)$ with the maximum of $M(2 \cdot w + 1)$ and $M(2 \cdot w + 2)$. If $M(w)$ is large enough, $H(p)$ holds and sift terminates; otherwise w can be "doubled" at the price of 2 comparisons and 1 swap in array M . For further details we refer the reader to [0].

We can do better (in terms of numbers of comparisons and swaps needed) by replacing $H(p)$ by $H_3(p)$ — and, similarly, SH by SH_3 —

$$H_3(p): (\forall i, j: p \leq i < j < q \wedge 3 \cdot i < j \leq 3 \cdot (i+1): M(i) \geq M(j)).$$

Firstly, we can then start with a smaller p , viz. $(N+1) \text{ div } 3$; secondly, sift can then "triple" w at the cost of 3 comparisons and 1 swap in array M . Thus 6 comparisons and 2 swaps multiply w by 9, whereas originally 6 comparisons and 3 swaps were needed for a factor of 8. (With the analogous $H_4(p)$, the gain in comparisons needed is lost again: $2^3 < 3^2$, but $2^4 = 4^2$. Since $2^5 > 5^2$, $H_5(p)$ is expected to lead to more comparisons in sift.)

A worst-case sift is one that terminates with $2 \cdot w + 1 \geq q$ or $3 \cdot w + 1 \geq q$ respectively. A sort in which all sifts are worst-case sifts would clearly be a worst-case sort. Since such sorts can occur — see below — and our modification improves worst-case sifts, the worst-case performance of Heapsort has, indeed, been improved.

The crucial observation is that, when upon completion of a call of sift the final value of w is not destroyed, the effect of that call can be undone: sift itself has a unique inverse sift^{-1} (ending with $w=p$). Starting with an increasing array M , we can play Heapsort backwards, supplying each time sift with a "proper" initial value for w such that $2 \cdot w + 1 \geq q$ or $3 \cdot w + 1 \geq q$, respectively — for a detailed discussion of the notion "proper", see below. Our backwards game ends with an M that would lead to a sort with worst-case sifts only.

Now a detailing of the notion "proper". Our backwards game starts increasing q repeatedly by

$$\{H(p)\} \text{ sift}^{-1} \{H(p+1)\}; \\ M: \text{swap}(q, 0); q := q + 1 \{H(0)\} \quad (2)$$

Independently of our choice of w , $H(0)$ holds after the swap, because the new $M(0)$ satisfies ($\forall j: 0 \leq j < q: M(0) \geq M(j)$). But does $H(0)$ hold after

$q:=q+1$? It does if $M(q-1)$ is then small enough.
 We can achieve this, for instance, by initializing
 for sift^{-1} $w=q-1$; program section (2) then
 maintains $(\forall i: p \leq i < q : M(i) \geq M(q-1))$. Our
 backwards game continues increasing p repeatedly
 by by

$$\{H(p)\} \text{sift}^{-1} \{H(p+1)\}; p := p+1 .$$

Since $p=0$ is now not an invariant, we must take precautions to ensure that sift^{-1} can end with $w=p$; here "proper" means that the initial value of w is such that $\underline{\text{do }} w \neq p \rightarrow w := (w-1) \underline{\text{div}} 2 \underline{\text{ od}}$ (or $\underline{\text{do }} w \neq p \rightarrow w := (w-1) \underline{\text{div}} 3 \underline{\text{ od}}$) terminates.

Compared to the above worst-case analysis, the analysis of the average case seems too difficult and insufficiently rewarding.

Acknowledgements. I am indebted to Ross A. Honsberger who sent me a series of combinatorial problems, one of which used $2^3 < 3^2$. (The problem was how to partition a given positive integer into positive integer parts such that the product of the parts is maximal. The solution is to take as many parts = 3 as is possible without introducing a remaining part = 1. The preponderance of 3's is not amazing: 3 is the nearest integer approximation of e.)

I am also indebted to R.W.Bulterman, who spotted an error in my original form of $H_3(p)$, which failed to satisfy the analogue of (0); in the literature, Heapsort traditionally sorts $M(c: 1 \leq c \leq N)$ and unthinkingly I had adopted that unfortunate convention, which was responsible for my error.

Finally I am indebted to Eric C.R. Hehner and the members of the Tuesday Afternoon Club, who helped me with the worst-case analysis, in which we clearly benefitted from our earlier work on program inversion (see [1]).

[0] Wirth, Niklaus, Algorithms + Data Structures = Programs, Englewood Cliffs, NJ, USA, Prentice-Hall Inc, 1976, pp. 72-76

[1] Bauer, F.L. and Broy, M (Ed.), Program Construction, Lecture Notes in Computer Science 69, Berlin Heidelberg New York, Springer Verlag, 1979, pp. 54-57.

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