

# Linear Programming

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CS 331H

# Class Outline

- 1 Introduction to Linear Programming
- 2 How to Solve a Linear Program
- 3 Reducing Problems to Linear Programs

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- General way of writing problems: maximize linear function subject to linear constraints.

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- Mathematically:

$$\begin{aligned} \text{maximize:} & \quad C + 2T \\ \text{subject to:} & \quad 2C + 3T \leq 12 \\ & \quad C + 5T \leq 15 \\ & \quad C, T \geq 0 \end{aligned}$$

## Solving small cases by hand

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  - ▶ Find all vertices, and for each:
  - ▶ Check if feasible (satisfy the constraints)
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- Geometrically:
  - ▶ Draw the picture of all feasible points
  - ▶ Slide in the direction of the objective until you get stuck.

# General Linear Programming (LP)

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Optimize (maximize or minimize) a *linear objective* in many variables, subject to *linear constraints* on them ( $=, \leq, \geq$ ).



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$$\text{maximize: } x_1 + 3x_2 - 345x_3 + x_4$$

$$\text{subject to: } x_1 - 17x_2 \leq x_4 + 12$$

$$x_4 - x_3 \geq x_2$$

$$67x_2 - 3x_1 = 83$$

$$x_3 \leq 0$$

# Formulations of LP

## Standard form (or “symmetric”)

For  $m$  constraints on  $n$  variables, given  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ ,  $c \in \mathbb{R}^n$ :

$$\text{maximize: } c \cdot x$$

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## Common alternative forms

“Alternative form”

$$\begin{aligned} &\text{maximize:} && c \cdot x \\ &\text{subject to:} && Ax \leq b \end{aligned} \quad \text{or}$$

“Slack form”

$$\begin{aligned} &\text{maximize:} && c \cdot x \\ &\text{subject to:} && Ax = b \\ & && x \geq 0 \end{aligned}$$

## The forms are reducible to each other

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- ▶ Best theoretical result:  $O(n^{2.38}L)$  time (Cohen, Lee, Song '19).

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    - ▶ Number of iterations depends on problem instance & rule for choosing next vertex, but could be exponential.

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- Simplex works, eventually, once you have a feasible vertex.
- Doesn't seem so useful:

### Problem

If you can solve “does this polytope have any feasible point” you can also solve linear programming (= optimize over polytopes).



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### Proof.

We want to determine  $OPT = \max c \cdot x$  s.t.  $Ax \leq b$ . Then  $OPT \geq \tau$  if and only if the polytope

$$\begin{aligned} Ax &\leq b \\ c \cdot x &\geq \tau \end{aligned}$$

has any solution. So if we can solve this, we binary search on  $\tau$  to solve LP. □

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We want to find a point  $x$  such that  $Ax \leq b, x \geq 0$ . Introduce a new variable  $z \in \mathbb{R}$ , and solve:

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- So simplex can get started on NEW and solve it.



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We want to find a point  $x$  such that  $Ax \leq b, x \geq 0$ . Introduce a new variable  $z \in \mathbb{R}$ , and solve:

$$\begin{array}{ll} \text{minimize:} & z \\ \text{subject to:} & Ax - z \leq b \\ & x, z \geq 0 \end{array} \quad (\text{NEW})$$

- Simplex can get started on NEW and solve it.

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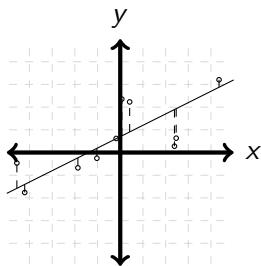
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- Hence the solution  $\hat{x}$  is a vertex of the original LP.

# Class Outline

- 1 Introduction to Linear Programming
- 2 How to Solve a Linear Program
- 3 Reducing Problems to Linear Programs

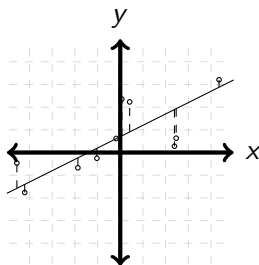
# L1 linear regression



Given  $n$  points on plane:  $(x_1, y_1), \dots, (x_n, y_n)$ . Find the line  $mx + b$  minimizing the average error:

$$\text{Err} = \frac{1}{n} \sum_{i=1}^n |y_i - (mx_i + b)|$$

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Part (2): Now, minimize the *maximum* error.

# Writing old problems as linear programs

- Write network flow as a linear program
- Write shortest paths as a linear program
- Write minimum cut as a linear program





