

## Lecture 19: Markov Chains I

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**NOTE: THESE NOTES HAVE NOT BEEN EDITED OR CHECKED FOR CORRECTNESS**

## 1 Overview

In this lecture, we are going to talk about Markov Chains. A Markov chain is a (discrete) memory-less stochastic process. For example, a random walk on  $n$  states, the distribution of position at time  $t + 1$  depends only on time  $t$ , not further history is needed.

## 2 Math things

Defining the transition matrix  $P$  as follows,

$$P_{i,j} = Pr[X_{t+1} = j | X_t = i] \quad (1)$$

Let  $q^{(t)}$  be the distribution of  $X_t$ ,

$$q^{(t+1)} = q^{(t)} \cdot P \quad (2)$$

$\Pi$  is a stationary distribution, if  $\Pi \cdot P = \Pi$ . Markov Chain is "ergodic" if:

- $\Pi$  is unique
- $\forall q^{(0)}, q^{(t)} = q^{(0)} \cdot P^t$  as  $t \leftarrow \infty$

### 2.1 Fundamental Theorem of Markov Chains

A chain is ergodic when:

- Finite  $n$
- Aperiodic:  $\forall$  states,  $\gcd(\text{loops from that state}) = 1$
- Irreducible:  $\exists i \rightarrow j$  path  $\forall i, j$

$h_{uv}$ : hitting time from  $u$  to  $v$  starting at  $u$ ,  $\mathbf{E}[\text{time to reach } V]$

$C_{uv}$ : commute time, expected time to go from  $u$  to  $v$  and then back to  $u = h_{uv} + h_{vu}$

Random walks in undirected graphs

$$P_{uv} = \begin{cases} \frac{1}{d(u)} & \text{if } (u,v) \in E \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

Connected, no-bipartite  $\Rightarrow$  ergodic.

$$\Pi_v = \frac{d(v)}{2m} \quad (4)$$

Check:  $\sum_v \Pi_v = \frac{\sum d(v)}{2m} = 1$ ,

$$(\Pi P)_v = \sum_{(u,v) \in E} \Pi_u \cdot \frac{1}{d(u)} = \sum_{(u,v) \in E} \frac{1}{2m} = \frac{d(v)}{2m} = \Pi_v \Rightarrow \Pi P = \Pi \Rightarrow \Pi \text{ is stationary} \quad (5)$$

with  $\Pi_i > 0 \forall i$   $N(i, t) := \#$  times reach state  $i$  before time  $t$ ,

$$\lim_{t \rightarrow \infty} \frac{N(i, t)}{t} = \Pi_i \quad (6)$$

Hitting time  $h_{ii} = \frac{1}{\Pi_i}$  and  $h_{ii} = \mathbf{E}[\text{time to return to } i \text{ after leaving it}]$