



Today

- Course logistics
- Overview
- Volunteers, prep for next week

Administration

- **Class:** Tues / Thurs 12:30-2 PM
- **Instructor:** Kristen Grauman
grauman at cs.utexas.edu
TAY 4.118
- **Office hours:** Tues / Thurs 3-4 PM
link from
- **Class page:** <http://www.cs.utexas.edu/~grauman>
** Check for updates to schedule.

Course content

- Focus on current research in visual category and object recognition
- High-level vision and learning problems

We will *not* spend much time on low-level image processing, video-based techniques, particular vision systems, human vision system.

Expectations

- **Discussions** will center on recent papers in the field
 - Paper reviews, prepared discussion points
- **Student presentations**
 - Paper content, demos (extra credit)
- **Projects**
 - Research-oriented

Paper reviews

- For each class, choose **one** of the 2-3 papers we are covering to review
- Reviews due via email to me **before class**
- Posted for our class (anonymously)

Also, prepare (write down) a few discussion points to have on hand in class about all of the papers you read.

Paper review guidelines

- Brief (2-3 sentences) summary
- Main contribution
- Strengths? Weaknesses?
- How convincing are the experiments?
Suggestions to improve them?
- Extensions?
- Additional comments.

More is not necessarily more.

Presentation guidelines

- Approx. 25 minutes
- Clear overview of the paper
- Consider:
 - Main problem, motivation
 - Assumptions
 - Technical approach: high level and intuition
 - Important technical details
 - Experiments
 - Connections to other papers

Demo guidelines

Implement/download code for a main idea in the paper and show us toy example(s):

- Experiment with different types of (mini) training/testing data sets
- Evaluate sensitivity to parameter settings
- Show (on a small scale) an example in practice that highlights a strength/weakness of the approach
- ...

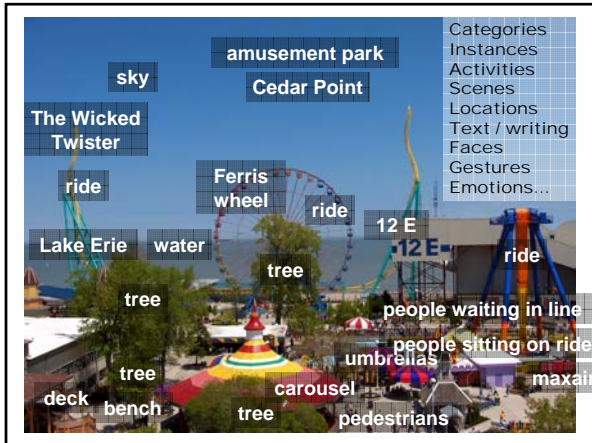
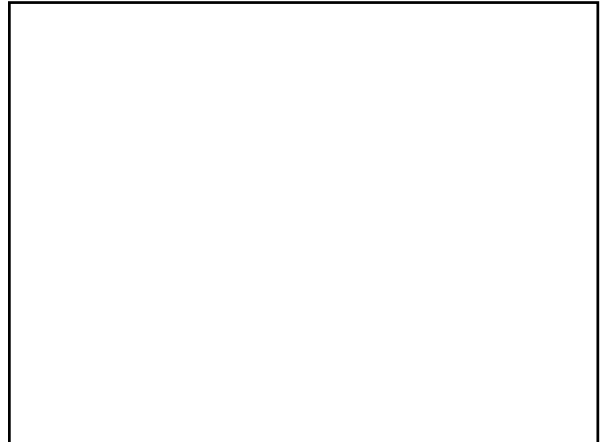
Projects

Possibilities:





- Extend a technique studied in class
- Empirical evaluation and analysis of a few related techniques
- Design and evaluate a novel approach
- May be possible to tie it into your research
- Work in pairs
- Proposal due at midterm (March 8)
- Short presentation at end of term, paper



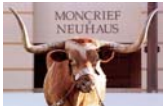
What is visual recognition?

- Perception of familiar objects
- Given image data, determine what's in it, and where
- Detection, categorization, identification



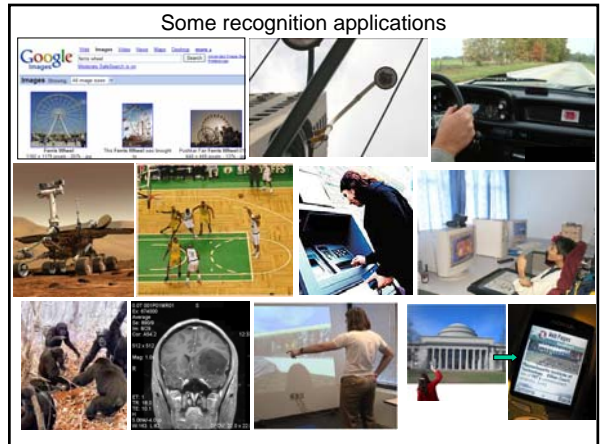
Our focus in this class (primarily)

				Categories
butterfly	butterfly	building	building	

			Specific
Wild card	Tower Bridge	Bevo	

Why recognition?

- Fundamental problem in computer vision
- Area is rich with very challenging questions
- Applications ...



Key challenges: robustness



Key challenges: efficiency

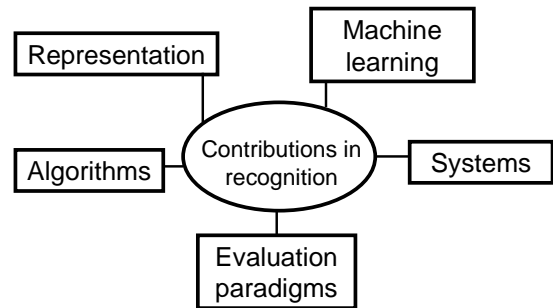
- Thousands to millions of pixels in an image
- 3,000-30,000 human recognizable object categories
- 30+ degrees of freedom in the pose of articulated objects (humans)
- Billions of images indexed by Google Image Search
- 18 billion+ prints produced from digital camera images in 2004
- 295.5 million camera phones sold in 2005

Disciplines

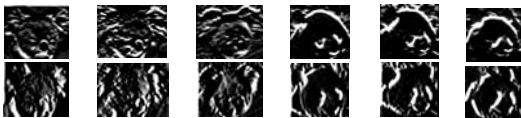
Recognition (and vision in general) draws from

- Machine learning
- Probability
- Geometry, physics
- AI
- Algorithms
- Image processing
- Cognitive science

Recognition research



Global image representations

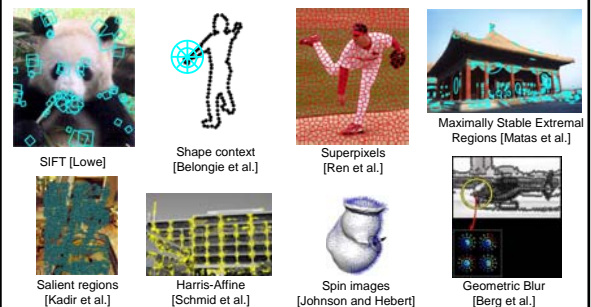


Map image to a single vector based on overall characteristics

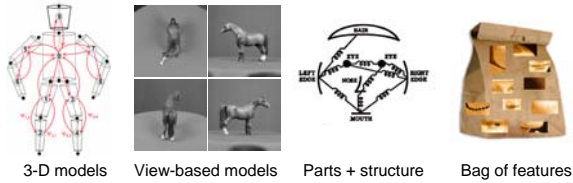
- vector of pixel intensities
- grayscale / color histogram
- bank of filter responses ...

Local image representations

Describe component regions or patches separately



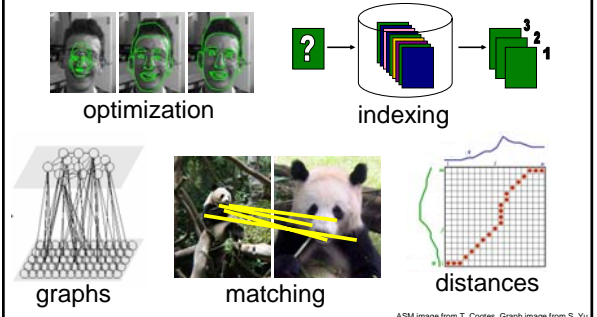
Representing object shape, geometry



3-D models View-based models Parts + structure Bag of features

Image from Sigal et al. Images from ETH-80 Image from Fischler and Elschlager Image from ICCV short course

Algorithms



ASM image from T. Cootes, Graph image from S. Yu

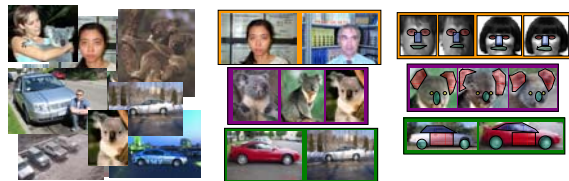
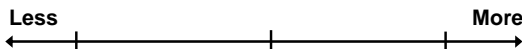
Learning

- What defines a category/class?
- What distinguishes classes from one another?
- How to understand the connection between the real world and what we observe?
- What features are most informative?
- What can we do without human intervention?
- Does previous learning experience help learn the next category?

Inputs/outputs/assumptions

- What **input** is available?
 - Static grayscale image
 - 3D range data
 - Video sequence
 - Multiple calibrated cameras
 - Segmented data, unsegmented data
 - Labeled data, unlabeled data, partially labeled data
- What is the **goal**?
 - Say yes/no as to whether an object present in image
 - Categorize all objects
 - Forced choice from pool of categories
 - Bounding box on object
 - Full segmentation
 - Build a model of an object category

Spectrum of supervision



Category recognition: state-of-the-art

What's possible now?
What's difficult now?

One way to measure: benchmark data sets.

Category recognition: state-of-the-art

PASCAL Visual Object Classes Challenge 2006

- 10 categories
- Unsegmented, realistic images
- Supervised setup
- Classification task: For each class, predict presence/absence of an example of that class in the test image.
- 26 teams/methods competed

Bicycles

- Highest ranked class images



Images thanks to Mark Everingham

- Lowest ranked class images



- Highest ranked non-class images



Images thanks to Mark Everingham

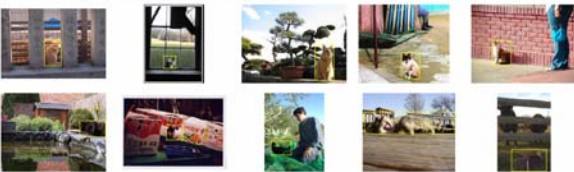
Cats

- Highest ranked class images



Images thanks to Mark Everingham

- Lowest ranked class images

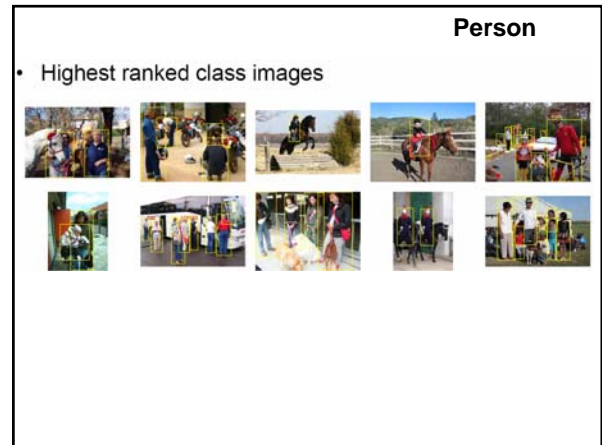
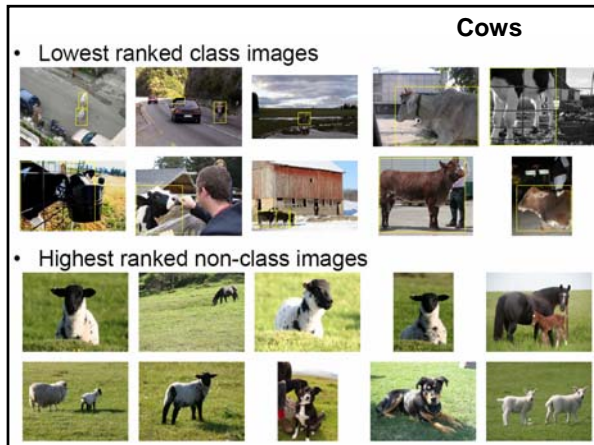
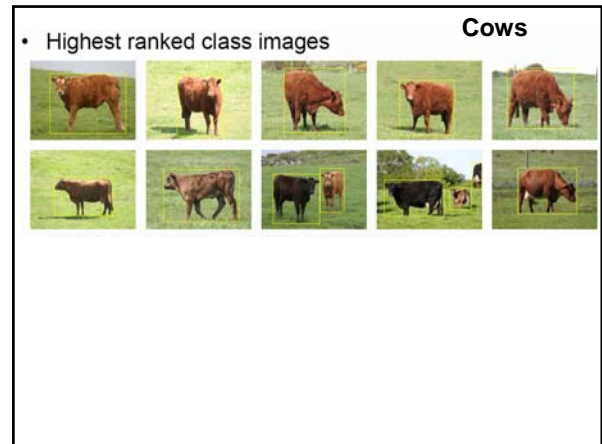
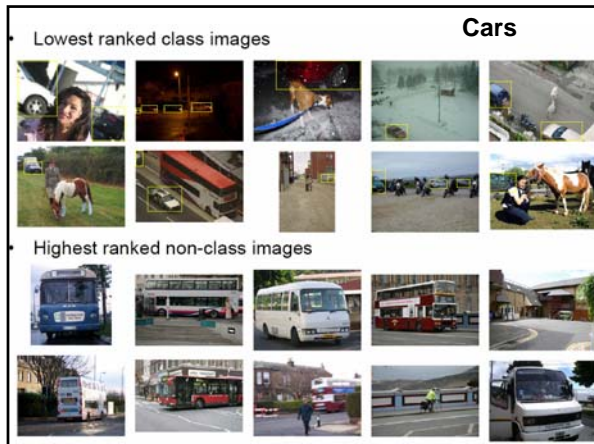


- Highest ranked non-class images



- Highest ranked class images

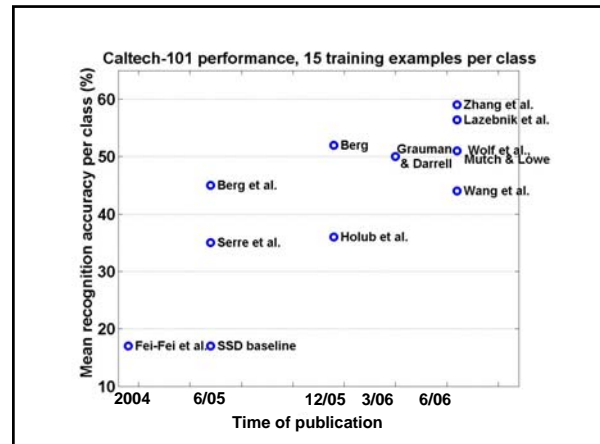
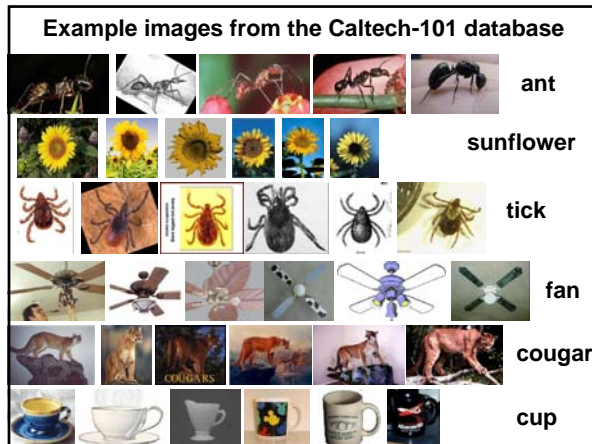




**Category recognition:
state-of-the-art**

Caltech-101 Database

- 101 categories
- Wide appearance variation
- Images fairly centered and scaled similarly
- Supervised setup
- Classification task: predict class for test images
- Around 12 methods tested in literature



Topics

Through readings in recent vision literature...

- part-based models for recognition
- invariant local features
- bags of features and feature vocabularies
- spatial constraints and geometry
- shape descriptors and matching
- learning similarity measures
- fast indexing methods
- recognition with text and images
- the role of context in recognition
- unsupervised category discovery

Goals of this course

- Understand current approaches
- Analyze
- Identify interesting research questions

Coming up

- For tomorrow:
 - Send me 4-5 paper preferences for presentations up to spring break
- For Tuesday Jan 23
 - *Face Recognition Using Eigenfaces* by Turk and Pentland
 - *Face Recognition Using Active Appearance Models* by Edwards et al.
 - Bring discussion points
 - Review one of the papers (email to grauman@cs by Tuesday 12:30)
 - Demos preferences
- For Thursday Jan 25
 - *Rapid Object Detection Using a Boosted Cascade of Simple Features* by Viola and Jones
 - *Face Recognition by Humans* by Sinha et al.
 - Bring discussion points
 - Review on Viola and Jones

Coming up

- Presentation volunteers
- Quick survey