

null pointer, as required by the C standard. The order ensures that `argv[0]` is at the lowest virtual address. Word-aligned accesses are faster than unaligned accesses, so for best performance round the stack pointer down to a multiple of 4 before the first push.

Then, push `argv` (the address of `argv[0]`) and `argc`, in that order. Finally, push a fake "return address": although the entry function will never return, its stack frame must have the same structure as any other.

The table below shows the state of the stack and the relevant registers right before the beginning of the user program, assuming `PHYS_BASE` is `0xc0000000`:

Address	Name	Data	Type
0xbffffffc	argv[3][...]	"bar\0"	char[4]
0xbffffff8	argv[2][...]	"foo\0"	char[4]
0xbffffff5	argv[1][...]	"-l\0"	char[3]
0xbffffffed	argv[0][...]	"/bin/ls\0"	char[8]
0xbfffffec	word-align	0	uint8_t
0xbfffffe8	argv[4]	0	char *
0xbfffffe4	argv[3]	0xbffffffc	char *
0xbffffe0	argv[2]	0xbffffff8	char *
0xbffffdc	argv[1]	0xbffffff5	char *
0xbffffd8	argv[0]	0xbffffffed	char *
0xbffffd4	argv	0xbffffd8	char **
0xbffffd0	argc	4	int
0xbffffcc	return address	0	void (*) ()

In this example, the stack pointer would be initialized to `0xbffffcc`.

As shown above, your code should start the stack at the very top of the user virtual address space, in the page just below virtual address `PHYS_BASE` (defined in "threads/vaddr.h").

You may find the non-standard `hex_dump()` function, declared in "<stdio.h>", useful for debugging your argument passing code. Here's what it would show in the above example:

```

bffffffc  04 00 00 00  db ff ff bf  ed ff ff bf  15 ff ff bf  .....
bffffffd  18 ff ff bf  fc ff ff bf  00 00 00 00  00 2f 62 69  ...../bi
bffffffe  6e 2f 6c 73  00 2d 6c 00  00 6f 6f 00  62 61 72 00  n/ls.-l.foo.bar
bffffff0
  
```

Addresses of argv are (left) to (right)

last thing you pushed

address at left side of line

indicates halfway through the line

here is another PHYS_BASE

indicates null

3.5.2 System Call Details

The first project already dealt with one way that the operating system can regain control from a user program: interrupts from timers and I/O devices. These are "external" interrupts, because they are caused by entities outside the CPU (see section A.4.3 External Interrupt Handling).