Pixels

- *Pixel:* Intensity or color sample.
- Raster Image: Rectangular grid of pixels.
- *Rasterization:* Conversion of a primitive's geometric representation into
 - A set of pixels.
 - An intensity or color for each pixel (*shading*, *antialiasing*).
- For now, we will assume that the background is white and we need only change the color of selected pixels to black.

Pixel Grids

- *Pixel Centers:* Address pixels by integer coordinates (i, j)
- *Pixel Center Grid:* Set of lines passing through pixel centers.
- *Pixel Domains:* Rectangular semi-open areas surrounding each pixel center:

 $P_{i,j} = (i - 1/2, i + 1/2) \times (j - 1/2, j + 1/2)$

• *Pixel Domain Grid:* Set of lines formed by domain boundaries.



Specifications and Representations

Each rendering primitive (point, line segment, polygon, etc.) needs both

- A geometric specification, usually "calligraphic."
- A pixel (rasterized) representation.

Standard device-level geometric specifications include:

Point: $A = (x_A, y_A) \in \mathbf{R}^2$.

Line Segment: $\ell(AB)$ specified with two points, A and B. The line segment $\ell(AB)$ is the set of all collinear points between point A and point B.

Polygon: Polygon $\mathcal{P}(A_1A_2...A_n)$ specified with an ordered list of points $A_1A_2...A_n$. A polygon is a region of the plane with a piecewise linear boundary; we connect A_n to A_1 .

This "list of points" specification is flawed... a more precise definition will be given later.

Line Segments

- Let $\ell(AB) = \{P \in \mathbb{R}^2 | P = (1 t)A + tB, t \in [0, 1]\}$
- Problem: Given a line segment $\ell(AB)$ specified by two points A and B,
- Decide: Which pixels to illuminate to represent $\ell(AB)$.
- Desired properties: Rasterization of line segment should
 - 1. Appear as straight as possible;
 - 2. Include pixels whose domains contain A and B;
 - 3. Have relatively constant intensity (i.e., all parts should be the same brightness);
 - 4. Have an intensity per unit length that is independent of slope;
 - 5. Be symmetric;
 - 6. Be generated efficiently.

Line Segment Representations

1. Given AB, choose a set of pixels $L_1(AB)$ given by

 $L_1(AB) = \{(i,j) \in \mathbb{Z}^2 | \ell(AB) \cap P_{i,j}\}$



Unfortunately, this results in a very blotchy, uneven looking line.

2. Given AB, choose a set of pixels $L_2(AB)$ given by

$$L_{2}(AB) = \begin{cases} |x_{B} - x_{A}| \geq |y_{B} - y_{A}| \longrightarrow \\ \{(i, j) \in \mathbb{Z}^{2} | (i, j) = (i, [y]), (i, y) \in \ell(AB), y \in \mathbb{R} \} \\ \cup ([x_{A}], [y_{A}]) \cup ([x_{B}], [y_{B}]). \\ |x_{B} - x_{A}| < |y_{B} - y_{A}| \longrightarrow \\ \{(i, j) \in \mathbb{Z}^{2} | (i, j) = ([x], j), (x, j), \in \ell(AB), x \in \mathbb{R} \} \\ \cup ([x_{A}], [y_{A}]) \cup ([x_{B}], [y_{B}]). \end{cases}$$



Line Equation Algorithm

```
Based on the line equation y = mx + b, we can derive:
```

endfor

Problems:

• One pixel per column so lines of slope > 1 have gaps

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• Vertical lines cause divide by zero

To fix these problems, we need to use $x = m^{-1}(y - b)$ when m > 1.

Discrete Differential Analyzer

Observation: Roles of x and y are symmetric...

• Change roles of x and y if $|y_B - y_A| > |x_B - x_A|$

Observation: Multiplication of m inside loop...

- The value of m is constant for all iterations.
- Can reduce computations inside loop: y_{i+1} and be computed incrementally from y_i

$$y_{i+1} = m(x_i + 1) + b = y_i + m$$

```
DDA (int xA, yA, xB, yB)
    int length, dx, dy, i;
    float x,y,xinc,yinc;
    dx = xB - xA;
    dy = yB - yA;
    length = max (|dx| > |dy|);
    xinc = dx/length; # either xinc or yinc is -1 or 1
    yinc = dy/length;
    x = xA; y = yA;
    for i=0 to length do
        WritePixel( [x], [y] );
        x += xinc;
        y += yinc;
    endfor
```

Bresenham's Algorithm

- Completely integer;
- Will assume (at first) that x_A, y_A, x_B, y_B are also integer.
- Only addition, subtraction, and shift in inner loop.
- Originally for a pen plotter.
- "Optimal" in that it picks pixels closest to line, i.e., $L_2(AB)$.
- Assumes $0 \le (y_B y_A) \le (x_B x_A) \le 1$ (i.e., slopes between 0 and 1).
- Use reflections and endpoint reversal to get other slopes: 8 cases.



- Suppose we know at step i 1 that pixel $(x_i, y_i) = P_{i-1}$ was chosen. Thus, the line passed between points A and B.
- Slope between 0 and 1 ⇒
 line must pass between points C and D at next step ⇒
 E_i = (x_i + 1, y_i) and N E_i = (x_i + 1, y_i + 1) are only choices for next pixel.
- If M_i above line, choose E_i ;

• If M_i below line, choose $N E_i$.

• Implicit representations for line:

$$F(x,y) = \underbrace{(2\Delta y)}_{Q} x + \underbrace{(-2\Delta x)}_{R} y + \underbrace{(\Delta x b)}_{S} = 0$$

where

Note that

- 1. $F(x, y) < 0 \Rightarrow (x, y)$ above line. 2. $F(x, y) > 0 \Rightarrow (x, y)$ below line. 3. Q, R, S are all integers.
- The mystery factor of 2 will be explained later.

- Look at $F(M_i)$. Remember, F is 0 if the point is on the line:
 - $F(M_i) < 0 \Rightarrow M_i$ above line \Rightarrow choose $P_i = E_i$.
 - $F(M_i) > 0 \Rightarrow M_i$ below line \Rightarrow choose $P_i = N E_i$.
 - $F(M_i) = 0 \Rightarrow$ arbitrary choice, consider choice of pixel domains...
- We'll use $d_i = F(M_i)$ as an decision variable.
- Can compute d_i incrementally with integer arithmetic.

- At each step of algorithm, we know P_{i-1} and d_{i} ...
- Want to choose P_i and compute d_{i+1}
- Note that

$$d_{i} = F(M_{i}) = F(x_{i-1} + 1, y_{i-1} + 1/2)$$
$$= Q \cdot (x_{i-1} + 1) + R \cdot (y_{i-1} + 1/2) + S$$

• If E_i is chosen then

$$d_{i+1} = F(x_{i-1} + 2, y_{i-1} + 1/2)$$

= $Q \cdot (x_{i-1} + 2) + R \cdot (y_{i-1} + 1/2) + S$
= $d_i + Q$

• If $N E_i$ is chosen then

$$d_{i+1} = F(x_{i-1} + 2, y_{i-1} + 1/2 + 1)$$

= $Q \cdot (x_{i-1} + 2) + R \cdot (y_{i-1} + 1/2 + 1) + S$
= $d_i + Q + R$

• Initially, we have

$$d_{1} = F(x_{A} + 1, y_{A} + 1/2)$$

= $Q_{x_{A}} + R_{y_{A}} + S + Q + R/2$
= $F(x_{A}, y_{A}) + Q + R/2$
= $Q + R/2$

- Note that $F(x_A, y_A) = 0$ since $(x_A, y_A) \in \ell(AB)$.
- Why the mysterious factor of 2? It makes everything integer.

```
Bresenham (int xA, yA, xB, yB)
    int d, dx, dy, xi, yi
    int incE, incNE
   dx = xB - xA
   dy = yB - yA
    incE = dy << 1
                           /* Q */
    incNE = incE - dx<<1; /* Q + R */
                               /* Q + R/2 */
   d = incE - dx
   xi = xA; yi = yA
    WritePixel( xi, yi )
    while ( xi < xB )
       xi++
        if ( d < 0 ) then /* choose E */
            d += incE
       else /* choose NE */
            d += incNE
            yi++
        endif
```

WritePixel(xi, yi) endwhile

- Some asymmetries (choice when ==).
- Did we meet our goals?
 - 1. Straight as possible: yes, but depends on metric.
 - 2. Correct termination.
 - 3. Even distribution of intensity: yes, more or less, but:
 - 4. Intensity varies as function of slope.
 - Can't do better without gray scale.
 - Worst case: diagonal compared to horizontal (same number of pixels, but $\sqrt{2}$ longer line).
 - 5. Careful coding required to achieve some form of symmetry.
 - 6. Fast! (if integer math fast ...)
- Interaction with clipping?
- Subpixel positioning of endpoints?
- Variations that look ahead more than one pixel at once...
- Variations that compute from both end of the line at once...
- Similar algorithms for circles, ellipses, ...
 - (8 fold symmetry for circles)

Reading Assignment and News

Chapter 8 pages 379 - 399, of Recommended Text.

(Recommended Text: Interactive Computer Graphics, by Edward Angel, 4th edition, Addison-Wesley)

Please also track the News section of the Course Web Pages for the most recent Announcements related to this course.

(http://www.cs.utexas.edu/users/bajaj/graphics24/cs354/)