Gaussian Elimination Algorithm with Partial Pivoting and Elimination Separated from Solving

Forward Elimination Applied to Matrix

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for k = 1:n .......The outer loop - this eliminates variable k
     choose ip_k such that |A_{ip_k,k}| = \max\{|A_{i,k}|: i \ge k\}.....Find the largest of the candidate pivots
     if A_{in,k} = 0.....if the largest is zero, no possible pivot
          warning ('Pivot in Gaussian Elimination is zero').....and maybe get out of here
     end
     swap A_{k,k},...,A_{k,n} with A_{ip_k,k},...,A_{ip_k,n}......swap the rows to get the pivot into position
     A_{ik} = A_{ik}/A_{kk}.....get the multiplier for the row i
                for j = k+1:n.....loop on the columns – innermost loop
                A_{i,j} = A_{i,j} - A_{i,k} A_{k,j} ......update the i,j element
          end
     end
end
This results in the upper triangle of the eliminated system in the upper triangle of A, the multipliers in the strict
lower triangle of A, and the swapping information in the ip array.
Solving ......notice no appearance of b until now
for k = 1:n ......here is where we apply the swapping and elimination to b
     swap b_{_k} with b_{_{\!i\!p_{_k}}}...... here iss where we need to remember the swapping information
     for i = k+1:n.....
           b_i = b_i - A_{i,k} b_k .........compare the k-loop to the one above – it's just like b was an extra column
     end.....
end.....
for i = n:-1:1......here is where we solve the upper triangular system
     for j = i+1:n.....
          b_i = b_i - A_{i,j}x_j .....this loop stores b(i) minus the summation A(i,j)*x(j) into b(i)
     end.....
     x_i = b_i / A_{i,i} ......and divide by A(i,i) to get x(i)
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and the output is the solution x.

end