

Lecture 14 — October 26, 2015

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1 Overview

In this lecture, we study the problem of finding shortest paths. Let \mathbb{G} be a graph of m edges and n vertices. First let's look at some algorithms.

Algorithm	Sources	Negative Weight	Time
Dijkstra	Single	No	$O(m + n \log n)$
Floyd-Warshall	All Pairs	Yes	$O(n^3)$
Bellman-Ford	Single	Yes	$O(mn)$

Table 1: Comparison of some shortest path algorithms.

The Floyd-Warshall algorithm is very simple:

Data: Distance matrix D

Result: Shortest path matrix D

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for  $k$  in  $[n]$  do
  | for  $i$  in  $[n]$  do
  | | for  $j$  in  $[n]$  do
  | | |  $D_{ij} = \min(D_{ij}, D_{ik} + D_{kj})$ 
  | | end
  | end
end

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Algorithm 1: Floyd-Warshall algorithm

2 Faster algorithm using matrix multiplication

We can have faster algorithms for all pair shortest paths in $O(MM(n))$ time for unweighted and undirected graph, where $MM(n)$ is the time to multiply two $n \times n$ matrices. Some history of the matrix multiplication problem:

- Naive: $O(n^3)$.
- Strassen '69: $O(n^{2.8074})$.
- Coppersmith & Winograd '89: $O(n^{2.375477})$.
- Strothers '10: $O(n^{2.374})$.
- Vassilevska-Williams '11: $O(n^{2.372873})$.

- Note that the lower bound for MM is still an open problem. ($O(n^2)$??)

The notation n^ω is often used in papers since ω is being continuously improved. In this lecture, $MM(n)$ is referred to as n^ω .

First we observe the similarity between matrix multiplication and FloydWarshal. In fact, matrix multiplication is FloydWarshal where $(\min, +)$ is replaced by $(+, \times)$.

Let A be the adjacency matrix, we have that A_{ij}^2 is the number of length 2 path from i to j . More generally, A_{ij}^l is the number of length l path from i to j . If we add the identity matrix to A , which is equivalent to adding all self-loop in the graph, we have that A_{ij}^l number of paths of length $\leq l$.

A naive way of using matrix multiplication to compute shortest paths is to compute: A, A^2, \dots, A^n then let $D_{ij} = \min_l A_{ij}^l > 0$. Two problems are $O(n^{\omega+1})$ time and big number (which can be easily solve by just storing $A^l > 0$). Suppose we want a 2-approximation to D_{ij} , which is X_{ij} such that $D_{ij} \in [\frac{X_{ij}}{2}, X_{ij}]$. We can compute $A, A^2, A^4 \dots$ in $O(MM(n) \log n)$ by repeated squaring.

Now let D' be the distance on A^2 , that is the graph with all length 2 paths added as new edges. D' can be computed recursively. Our goal is to find D from D' and A in $O(MM(n))$ time. There are two cases:

- If D_{ij} is even then $D'_{ij} = D_{ij}/2$.
- If D_{ij} is odd then $D'_{ij} = (D_{ij} + 1)/2$.

So all we need to do is to find $D \pmod 2$ (from D' and A). Consider again two cases:

- If D_{ij} is even then $\forall u \in N(i), D'_{uj} \in \{D'_{ij}, D'_{ij} + 1\}$.
- If D_{ij} is odd then $\forall u \in N(i), D'_{uj} \in \{D'_{ij}, D'_{ij} - 1\}$ and $\exists u \in N(i)$ s.t. $D'_{uj} = D'_{ij} - 1$.

That is because if the distance from i to j in A is even ($2l$) then for a neighbor u of i the distance from u to j can only be $2l - 1, 2l$ or $2l + 1$. In A^2 , the distance from i to j is l and from u to j is l or $l + 1$ (if $D_{uj} = 2l - 1$ in A then it still takes l steps from u to j in A^2). By a similar argument, we have the case for D_{ij} odd. By summing over the neighbors, we have:

- If D_{ij} is even then $\sum_{u \in N(i)} D'_{uj} \geq D'_{ij} |N(i)|$.
- If D_{ij} is odd then $\sum_{u \in N(i)} D'_{uj} < D'_{ij} |N(i)|$.

Also, these sums can be expressed as matrix multiplication:

$$\sum_{u \in N(i)} D'_{uj} = \sum_{u \in [n]} A_{iu} D'_{uj} \tag{1}$$

$$= (AD')_{ij} \tag{2}$$

So we compare AD' to $D' |N(i)|$ to get $D_{ij} \pmod 2$ and set $D = 2D' - (D \pmod 2)$. Each round takes n^ω time and total time is $O(n^\omega \log n)$.

3 Identifying shortest paths

Now, given D and A , we want to give an efficient algorithm for finding the shortest paths. For this lecture, we look at the case of a tripartite graph (Figure 1), with edges going from left to right. Let A, B be the adjacency matrix for $\{V_1, V_2\}$ and $\{V_2, V_3\}$ respectively, then we're interested in finding $P_{ij} = k$ such that $A_{ik} \cap B_{kj} = 1$ in $O(n^\omega)$ time.

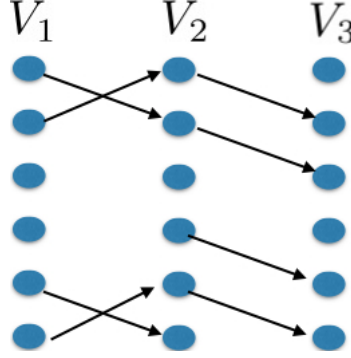


Figure 1: Tripartite Graph, $|V_i| = n \forall i$

Easy Case. Suppose there exists exactly one k^* such that $A_{ik^*} \cap B_{k^*j} = 1$, then:

- Define A' such that $A'_{ij} = A_{ij} \cdot j$
- Then $(A'B)_{ij} = \sum_k k A_{ik} B_{kj} = k^*$.
- So, we can identify the witness k^* for a path in $O(n^\omega)$ time.

Medium Case. Suppose there exist r witnesses $\{k_1, \dots, k_r\}$ such that $A_{ik_d} \cap B_{k_dj} = 1$ for all $d \in [r]$, then:

- Define A' such that $A'_{ij} = A_{ij} \cdot j \cdot \delta_j$, where δ_j is a Bernoulli r.v. such that $P[\delta_j = 1] = 1/r$.
- Now, if exactly one of the r $\delta_{k_t} = 1$, then $(A'B)_{ij} = k_t$, so, we would have identified a witness.
- Now, $P[\sum_t \delta_{k_t} = 1] = r \cdot \frac{1}{r} \cdot (1 - \frac{1}{r})^{r-1} \approx 1/e > 1/4$.
- So, repeat $O(\log n)$ times and each time check result $A_{ik_t} \cap B_{k_tj} = 1$. Hence, the total runtime is $O(n^\omega \log(n))$.

Hard Case. If we don't know the number of witnesses r , then:

- **Naive Strategy.** Run medium-case strategy for all $r = 1, \dots, n$. However, then runtime is $O(n^\omega \cdot \log(n) \cdot n)$.
- Run medium-case strategy for all $r = 1, 2, 4, \dots, n$. For this strategy, runtime is $O(n^\omega \cdot \log(n) \cdot \log(n))$.

- To analyse it's correctness: Suppose r :true number of witnesses, and let r' be our guess such that $r'/2 \leq r \leq r'$:

$$P[\text{exactly one of true witness } \delta_{k_i} = 1] = r \cdot \frac{1}{r'} \cdot \left(1 - \frac{1}{r'}\right)^{r-1} \\ \geq 1/2e$$

- Since, we have a constant probability of success, running for $O(\log(n))$ iterations at r' such that $r'/2 \leq r \leq r'$, suffices.
- Hence, an overall runtime of $O(n^\omega \cdot \log(n) \cdot \log(n))$ is sufficient for find a witness.

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