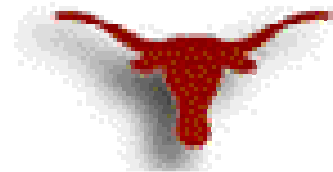

Getting Started in Programming Language Design Research

Object-Oriented and Imperative Languages



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More about Me

- **I've lived in nine states**
 - MI, PA, IL, MA, FL, LA, RI, CA, TX
- **Worked many jobs**
 - HP, Apple, BAM!, Net-It, Allegis, UT
 - (ask about the \$60M in venture capital)
- **Married w/8-year old son Miles**
 - My wife Robin is a user-interface designer
- **Research interests**
 - Programming languages & databases
 - Structured concurrency/workflow
 - Model-driven & feature-oriented programming

Picking Topics

- **Train your “spider senses”**
 - As undergraduates, we work around problems
 - Also true of most programming tasks
 - As grad students, focus on the problems
- **Do *something***
 - ... **even if it doesn't seem big enough**
 - In the doing, you may bump into a bigger problem
- **Solve someone else's problem**
 - Someone else = person outside PL
 - Learn about other areas in CS, and outside CS

Picking Topics

- **Best: direct contact with problem area**
 - *Get your hands dirty*
- **Theory**
 - Theory does not tell you what to do
 - It helps guide/constraint/analyze
- **Learn 2 or 3 things deeply**
 - Opportunities are found at the interfaces
- **Find problem and solution together**

Criteria Different by Topic

- **Types**
 - Proof of soundness (mechanically checked!)
- **Language runtime (systems)**
 - Implementation, performance
- **Language design papers**
 - Good motivation, examples
- **Analysis papers**
 - Proof, implementation, complexity, performance
- **Garbage Collection**
 - careful experiment design and measurement

Use the Tools

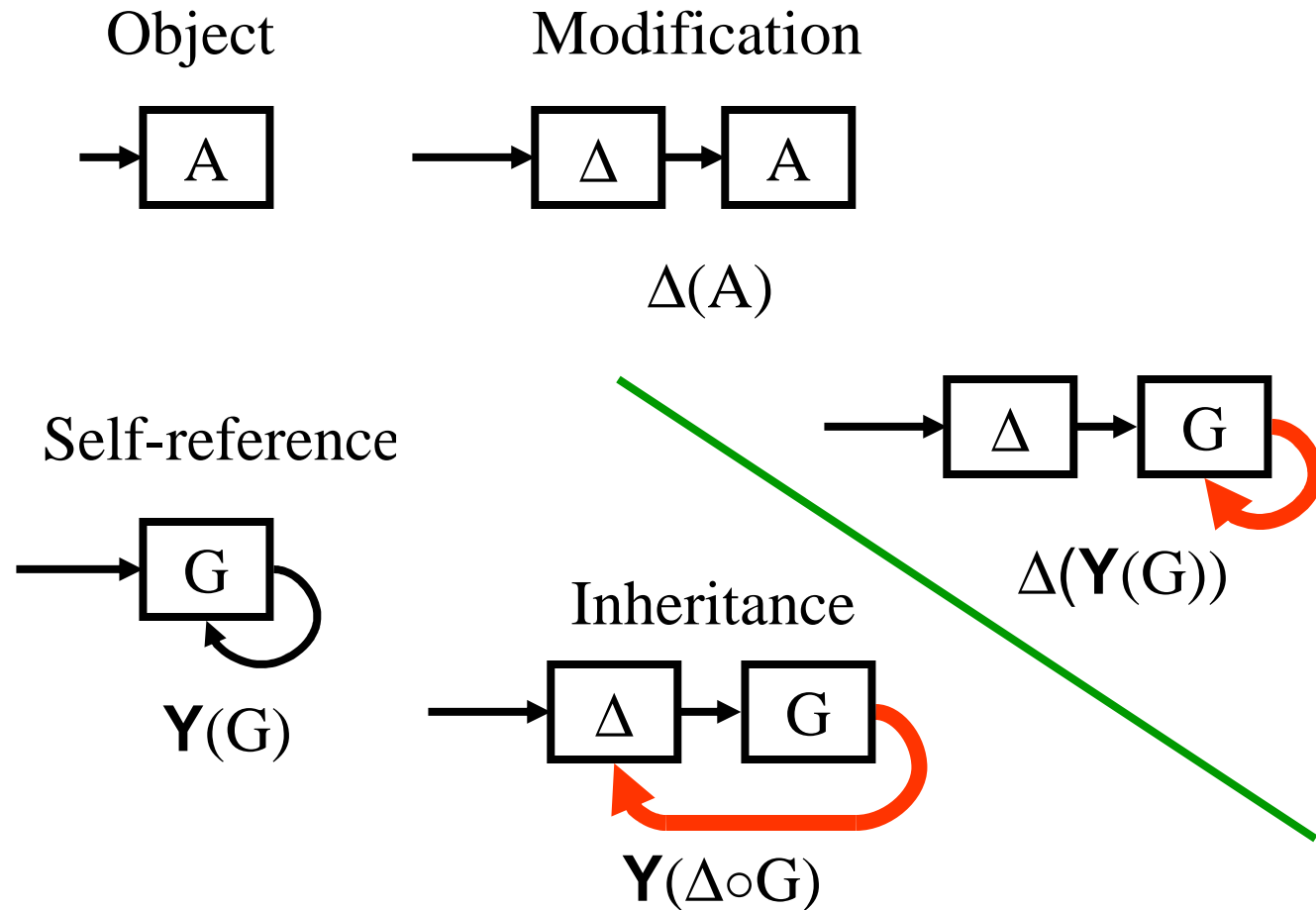
- **Semantics and Analysis**
- **Language Theory Substrates**
- **Implementation Substrates**
- **Verification and mechanization**
- **(Runtimes... in another talk)**
- **Practical Tools**
- **Evaluation + Packaging**

Foundation

- **Denotational Semantics**
 - good for intuition
 - λ -calculus
- **Operational Semantics**
 - Small-step
 - good for proofs
 - Large-step
 - natural, easy interpreters
 - recent proof techniques

Combination of Two Areas

- Denotational Semantics + Objects



The Tools

- **Abstract Interpretation**
 - compute over abstract values - types, properties, states
- **Static analysis**
 - lightweight formal methods
 - typing
 - shape analysis
 - ownership
- **Model checking**
- **Partial evaluation**

Language Substrates

- **Featherweight Java (Pierce's book)**
 - functional subset of java
- **Lightweight Java**
 - <http://www.cl.cam.ac.uk/~rs456/lj/>
 - imperative, true subset of java
 - comes with formalization in Isabelle/HOL
- **ClassicJava**
 - imperative
 - also support for mixins

Implementing Java Extensions

- **Polyglot**
 - Widely used
 - Complex plug-in model
- **JastAdd**
 - Newer
 - Based on declarative attribute grammars

Thought Tools

- **Galois connections**
 - loose isomorphism between ordered sets
- **Fixed points**
 - recursion and induction
- **Linear Types**
 - control over resources
- **Abstract data types and algebra**
 - Contrast with objects
- **Bisimulation**
 - equivalence of processes
- **Datalog**
 - data query/transformation
- **Attribute grammars**
 - declarative static analysis
- **Category theory**
 - theory of structure (some say: "content-free")

Language Environments

- **Implementations are convincing**
- **Ott tool**
 - Generates Isabelle/HOL specs (an Latex)
 - Includes formalization of Lightweight Java
- **PLT Redex**
 - Based on PLT Scheme
 - domain-specific language (DLS)
 - specifying and debugging operational semantics
- **Eclipse**
 - For refactoring/Development tools

$$\frac{\Gamma \vdash_{\mathbf{k}} M : \Pi^{\text{par}} s : \sigma. \rho \rightsquigarrow \Gamma_0 \vdash \bar{M} : \exists \vec{t}_0 :: \hat{k}_0. \Pi \bar{\Gamma}. \exists \vec{t}_1 :: \hat{k}_1. \forall \vec{s} :: \hat{\sigma}. \bar{\sigma} \vec{s} \rightarrow \exists \bar{\rho}}{\Gamma \vdash_{\mathbf{p}} N : \sigma \rightsquigarrow \Gamma_0 \vdash \bar{N} : \Pi \bar{\Gamma}. \bar{\sigma} \vec{t}}$$

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$$\frac{\Gamma \vdash_{\mathbf{k}} M : \sigma \rightsquigarrow \Gamma_0 \vdash \bar{M} : \exists \vec{t}_0 :: \hat{k}_0. \Pi \bar{\Gamma}. \exists \vec{t}_1 :: \hat{k}_1. \bar{\sigma} \vec{t} \quad \Gamma, s : \sigma \vdash_{\mathbf{k}} N : \rho \rightsquigarrow \Gamma_0 \vdash \bar{N} : \exists \vec{t}'_0 :: \hat{k}'_0. \Pi \bar{\Gamma}. \forall \vec{s} :: \hat{\sigma}. \bar{\sigma} \vec{s} \rightarrow \exists \vec{t}'_1 :: \hat{k}'_1}{M, N) : \Sigma s : \sigma. \rho \rightsquigarrow \Gamma_0 \vdash \text{open } \bar{M} \text{ as } \langle \vec{t}_0, x \rangle. \text{open } \bar{N} \text{ as } \langle \vec{t}'_0, y \rangle. \Lambda \bar{\Gamma}. \text{open } x \bar{\Gamma} \text{ as } \langle \vec{t}_1, z \rangle. \text{open } y \bar{\Gamma} \vec{t} z \text{ as } \langle \vec{t}'_1, w \rangle. \langle z : \exists \vec{t}_0 :: \hat{k}_0. \exists \vec{t}'_0 :: \hat{k}'_0. \Pi \bar{\Gamma}. \exists \vec{t}_1 :: \hat{k}_1. \exists \vec{t}'_1 :: \hat{k}'_1. (\lambda \vec{s} :: \hat{\sigma}. \lambda \vec{t}' :: \hat{\rho}. \bar{\sigma} \vec{s} \times \bar{\rho} \vec{t}') \vec{t}}$$

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$$\frac{\Gamma \vdash e : \langle \sigma \rangle \rightsquigarrow \Gamma_0, \bar{\Gamma} \vdash \bar{e} : \exists \bar{\sigma}}{\Gamma \vdash_{\mathbf{s}} \text{unpack } e \text{ as } \sigma : \sigma \rightsquigarrow \Gamma_0 \vdash \Lambda \bar{\Gamma}. \bar{e} : \Pi \bar{\Gamma}. \exists \bar{\sigma}}$$

$$\frac{\Gamma \vdash_{\mathbf{k}} M : \sigma \rightsquigarrow \Gamma_0 \vdash \bar{M} : \exists \vec{t}_0 :: \hat{k}_0. \Pi \bar{\Gamma}. \exists \vec{t}_1 :: \hat{k}_1. \bar{\sigma} \vec{t}}{\Gamma \vdash_{\mathbf{kLID}} (M :: \sigma) : \sigma \rightsquigarrow \Gamma_0 \vdash \text{open } \bar{M} \text{ as } \langle \vec{t}_0, x \rangle. \langle \vec{t} = \lambda \bar{\Gamma}. \lambda \vec{t}_1 :: \hat{k}_1. \vec{t}, x : \Pi \bar{\Gamma}. \exists \vec{t}_1 :: \hat{k}_1. \bar{\sigma} (\bar{\Gamma} \vec{t}_1) \rangle : \exists \vec{t}_0 :: \hat{k}_0. \exists \vec{t}' :: \bar{\Gamma} \Rightarrow \hat{k}_1 \Rightarrow \hat{\sigma}. \Pi \bar{\Gamma}. \exists \vec{t}_1 :: \hat{k}_1. \bar{\sigma} (\bar{\Gamma} \vec{t}_1)}$$

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$$\frac{\Gamma \vdash_{\mathbf{p}} M : \llbracket T \rrbracket \rightsquigarrow \Gamma_0 \vdash \bar{M} : \Pi \bar{\Gamma}. \bar{\Upsilon} y \bar{t}}{\Gamma \vdash_{\mathbf{p}} M : \mathfrak{S}(M) \rightsquigarrow \Gamma_0 \vdash \bar{M} : \Pi \bar{\Gamma}. \bar{\Upsilon} y \bar{t}}$$

$$\frac{\Gamma \vdash_{\mathbf{p}} \lambda s : \sigma. M s : \Pi^{\text{tot}} s : \sigma. \rho \rightsquigarrow \Gamma_0 \vdash \bar{M} : \bar{\tau}}{\Gamma \vdash_{\mathbf{p}} M : \Pi^{\text{tot}} s : \sigma. \rho \rightsquigarrow \Gamma_0 \vdash \bar{M} : \bar{\tau}} \quad 54$$

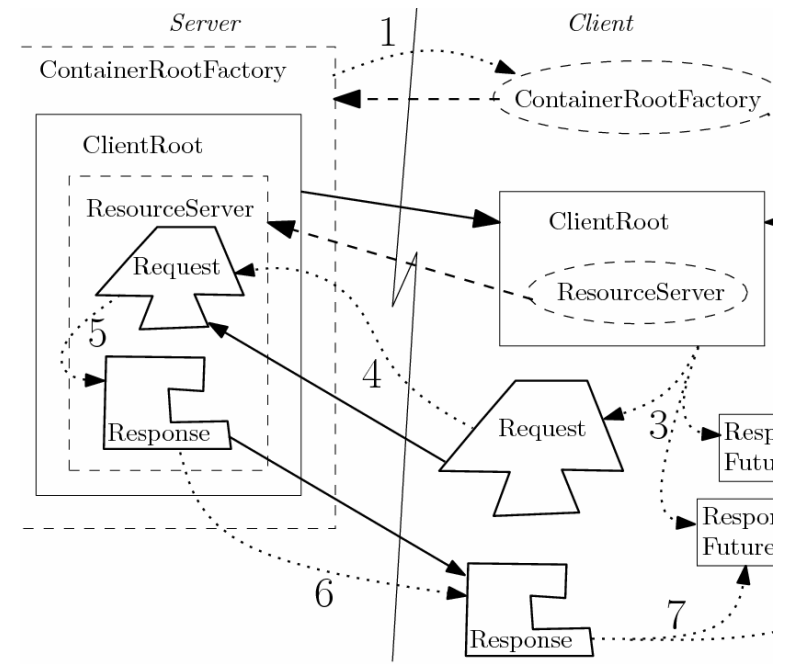
$$\frac{\Gamma \vdash_{\mathbf{p}} \langle s = \pi_1 M, \pi_2 M \rangle : \Sigma s : \sigma. \rho \rightsquigarrow \Gamma_0 \vdash \bar{M} : \bar{\tau}}{\Gamma \vdash_{\mathbf{p}} M : \Sigma s : \sigma. \rho \rightsquigarrow \Gamma_0 \vdash \bar{M} : \bar{\tau}} \quad 55$$

Mechanical Proof Checking

- **Theorem provers**
 - Isabelle/HOL
 - Twelf
 - ACL2
 - PVS
- **Specification languages**
 - Alloy, Maude, Z
- **POPLMark Challenge**
 - Challenge problems for “mechanizing meta-theory”

Practical Tools

- **Latex**
 - Inference Rules: Pierce's "bcprules.sty"
 - Presentations: PP or Latex??
- **Graphics**
 - OpenOffice → eps, IPE → esp
- **Use CVS for collaboration**
 - Latex too --- 5 author papers
 - Eclipse interface
- **Unison file sync**
- **Shell script!**
 - running tests
 - gathering results



Learn new skills

**You are here because
you are good at something**

**To be successful,
need to be good
at a range of skills**

Tasks

- Managing a small business
- Presenting your work
- Get funding
- Starting projects
- Accounting
- How to really dig into unfamiliar territory
- Finding topics to work on
- How to skim
- Managing a team

**Understand your work
style**

~~

**Compensate for
deficiencies**

my profile

- Quick thinking, sometimes too quick
- A programmer at heart
- Use theory as a tool
- Relentless, creative, intuitive
- Know what can be proven
- Proofs themselves are not easy
- Struggle with email (time management)
- Not a “born” writer, bad spelling
- How do you think I compensate?

What do you
have to produce
to get a
PhD?

**No,
it's not your thesis**

It is you