

# SPECIFICATIONS & REFINEMENTS

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# General Concepts

$S$  set of (all possible) specifications

$\rightsquigarrow \subseteq S \times S$  refinement relation

REFL  $s \rightsquigarrow s$  — reflexive  
TRANS  $s \rightsquigarrow s' \wedge s' \rightsquigarrow s'' \Rightarrow s \rightsquigarrow s''$  — transitive
 } preorder relation

$\rightsquigarrow^+$  transitive closure of  $\rightsquigarrow$

$\rightsquigarrow^*$  reflexive and transitive closure of  $\rightsquigarrow$

$P$  set of (all possible) programs in some target programming language

$S \cap P \neq \emptyset$  if the specification language is a superset of a subset of the programming language

$C: S \xrightarrow{p} P$  code generation (partial function, indicated by  $\xrightarrow{p}$ , i.e. domain  $\mathcal{D}(C) \subseteq S$ )

$\mathcal{D}(C) = S \cap P \wedge C = id$  if  $S \cap P \neq \emptyset$  (case above)

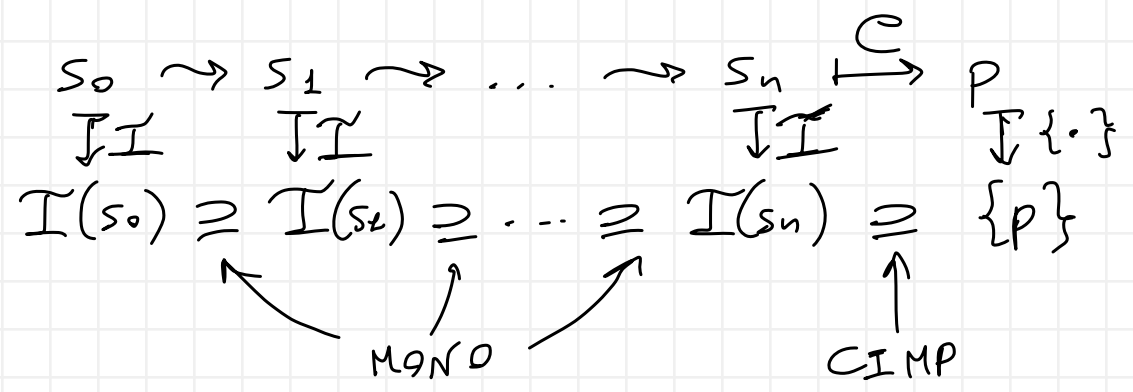
$s_0 \rightsquigarrow s_1 \rightsquigarrow \dots \rightsquigarrow s_n \xrightarrow{C} p$  derivation of  $p$  from requirements  $s_0$  via intermediate  $s_1, \dots, s_n$

$I: S \rightarrow 2^P$  possible implementations of specifications

$I(s) \triangleq \{p \in P \mid \exists s' \in \mathcal{D}(C). s \rightsquigarrow^* s' \wedge p = C(s')\} \subseteq P$

MONO  $\vdash s \rightsquigarrow s' \Rightarrow I(s) \supseteq I(s')$   
 $p \in I(s') \xrightarrow{I} \exists s'' \in \mathcal{D}(C). s' \rightsquigarrow^* s'' \wedge p = C(s'')$   
 $s \rightsquigarrow s' \xrightarrow{\text{TRANS}} s \rightsquigarrow^* s'' \xrightarrow{C} p = C(s'')$   
 $p \in I(s)$   
 QED

CIMP  $\vdash s \in \mathcal{D}(C) \Rightarrow C(s) \in I(s)$   
 $\text{REFL} \rightarrow s \rightsquigarrow^* s \rightarrow C(s) \in I(s)$   
 $C(s) = C(s) \rightarrow C(s) \in I(s)$   
 QED



derivation (see above)

monotonically decreasing sequence of sets of programs, ending in singleton

# Pop-Refinement

idea:  $S \triangleq 2^P$ ,  $\rightsquigarrow \triangleq \supseteq$ ,  $C \triangleq \{ \langle \tilde{p}, p \rangle \in 2^P \times P \mid \tilde{p} = \{p\} \}$

$\Rightarrow I = \text{id}$  — no indirection: the specification can constrain every aspect of the target program

more precisely, in a general-purpose logical language (especially, in a theorem prover):

$P$  consists of deeply embedded target programs

$S$  consists of predicates over  $P$

$\rightsquigarrow$  is (backward) logical implication

$s_0(p) \triangleq \dots$  — requirements (functional, non-functional, program-level, syntactic, etc.)

$s_i(p) \Rightarrow s_{i-1}(p)$  — refinement step

$s_n(p) \triangleq [p = \hat{p}]$  —  $p_0$  is a program in explicit syntactic form — the implementation

$C$  trivially turns  $[p = \hat{p}]$  into  $\hat{p}$  — without even pretty-printing if  $P$  consist of concrete syntax

$s_0(p) \Leftarrow s_1(p) \Leftarrow \dots \Leftarrow s_n(p) = [p = \hat{p}] \xrightarrow{C} \hat{p}$  — derivation — all expressed in the logic

$\vdash s_0(\hat{p})$  follows from the derivation

in ACL2, this can all fit in its first-order logic:

- formalize syntax and semantics of the target programming language
- $P$  is a set of ACL2 values
- each  $s_i$  is an ACL2 function (predicate) over  $P$
- the final implementation  $p_0$  is an ACL2 value

# Shallow Pop-Refinement

idea: functions in the logic can be regarded as shallowly embedded programs, given code generator  $\mathcal{C}$   
— sufficient to explicitly specify and refine functional constraints (only)

more precisely, in ACL2:

$f_1: \mathcal{U}^{n_1} \rightarrow \mathcal{U}^{m_1}, \dots, f_p: \mathcal{U}^{n_p} \rightarrow \mathcal{U}^{m_p}$  target functions ( $p \geq 1$ )

$S \subseteq (\mathcal{U}^{n_1} \rightarrow \mathcal{U}^{m_1}) \times \dots \times (\mathcal{U}^{n_p} \rightarrow \mathcal{U}^{m_p})$  specification (2<sup>nd</sup>-order — needs SOFT or apply\$)

$S_0(f_1, \dots, f_p) \triangleq \dots$  — requirements (functional only, but including hyperproperties)

$S_i(f_1, \dots, f_p) \Rightarrow S_{i-1}(f_1, \dots, f_p, f_{p+1}, \dots)$  — refinement step (may add function variables)

$S_n(f_1, \dots, f_p, \dots) \triangleq [f_1 = \hat{f}_1] \wedge \dots \wedge [f_p = \hat{f}_p] \wedge \dots$  — each  $\hat{f}_i \triangleq \dots$  is a defined function

implementation  $\left\{ \begin{array}{l} \{\hat{f}_1, \dots, \hat{f}_p, \dots\} \quad \text{— in (executable) ACL2} \\ \mathcal{C}(\{\hat{f}_1, \dots, \hat{f}_p, \dots\}) = \dots \quad \text{— in some other programming language} \end{array} \right.$

notation: above we use uppercase  $S$  instead of lowercase  $s$  for specification predicates, which is unambiguous also because in the context of shallow pop-refinement in ACL2 we do not explicitly reference the set of all possible such specification predicates

# Some Shallow Pop-Refinement Specification Forms

$$\boxed{\text{PP}} \quad S(f) \triangleq [\forall x. \Phi(x) \Rightarrow \Psi(x, f(x))]$$

$\Phi$  precondition,  $\Psi$  postcondition

generalizes from  $f: U \rightarrow U$  to  $f: U^n \rightarrow U^m$

$$\boxed{\text{Rf}} \quad S(f) \triangleq [\forall x. R(x, f(x))]$$

$R$  input/output relation

generalizes from  $f: U \rightarrow U$  to  $f: U^n \rightarrow U^m$

PP is special case of Rf:  $R(x, y) := [\Phi(x) \Rightarrow \Psi(x, y)]$

$$\boxed{\text{Rf}\alpha} \quad S(f) \triangleq [\forall x, \bar{x}. R(x, \bar{x}, f(x, \bar{\alpha}(\bar{x})))]$$

$x$  selected input — e.g. targeted by a transformation (not necessarily the first in  $x, x_1, \dots, x_n$ )

$\bar{x} = x_1, \dots, x_n$  additional inputs,  $n \geq 0$

$\alpha_1, \dots, \alpha_p: U^n \rightarrow U$  argument functions

$R \subseteq U^{1+n} \times U^m$  input/output relation, on  $f \circ \bar{\alpha}$

Rf is special case of Rf $\alpha$ :  $p := n$ ,  $\alpha_1 := \text{id}, \dots, \alpha_p := \text{id}$

more forms may be added here as needed