

Proving Skipping Refinement with ACL2s

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ACL2 2015

Motivation



Motivation



- ▶ Property-based
e.g., Temporal logics

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- ▶ Property-based
e.g., Temporal logics
- ▶ Refinement-based

Refinement

Specification

Instruction Set Architecture

- ▶ *add rd, ra, rb*
- ▶ *sub rd, ra, rb*
- ▶ *jnz imm*
- ▶ ...

High-level abstract system (\mathcal{A})

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High-level abstract system (\mathcal{A})

Implementation



Lower-level concrete system (\mathcal{C})

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High-level abstract system (\mathcal{A})

Implementation



Lower-level concrete system (\mathcal{C})

\mathcal{C} refines \mathcal{A} if every behavior of \mathcal{C} is a behavior of \mathcal{A} .

Refinement in ACL2 community

- ▶ Linking Theorem Proving and Model-Checking with Well-Founded Bisimulation, Manolios, Namjoshi, Sumners, 1999
- ▶ Verification of Pipelined Machines in ACL2, Manolios, 2000
- ▶ An Incremental Stuttering Refinement Proof of a Concurrent Program in ACL2, Sumners, 2000
- ▶ Proving Preservation of Partial Correctness with ACL2: A Mechanical Compiler Source Level Correctness Proof, Goerigk, Wolfgang, 2000
- ▶ Deductive Verification of Pipelined Machines Using First-Order Quantification, Sandip, Warren, 2004
- ▶ Verification of Executable Pipelined Machines with Bit-Level Interfaces, Manolios, Srinivasan, 2005
- ▶ ...

Superscalar Microprocessor

IF	ID	RF	EX	WB		
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Superscalar Microprocessor

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- ▶ Pipelining
- ▶ Superscalar Execution

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- ▶ Pipelining \rightsquigarrow Stuttering
Many concrete steps \approx One abstract step
Well-founded stuttering simulation and bisimulation
- ▶ Superscalar Execution

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Many concrete steps \approx One abstract step
Well-founded stuttering simulation and bisimulation
- ▶ Superscalar Execution \rightsquigarrow Skipping
One concrete step \approx Many abstract steps

Existing notions of refinement do not account for “skipping”

Skipping Refinement

- ▶ Skipping refinement¹, a notion of refinement that directly accounts for **finite stuttering and finite skipping**

¹CAV 2015

Skipping Refinement

- ▶ Skipping refinement¹, a notion of refinement that directly accounts for **finite stuttering and finite skipping**
- ▶ Sound and complete proof method that is amenable for **automated reasoning**

¹CAV 2015

Skipping Refinement

We develop the notion in the framework of labeled transition systems $\mathcal{M} = \langle S, \rightarrow, L \rangle$, where:

- ▶ S is a set of states
- ▶ $\rightarrow \subseteq S \times S$ is the transition relation
- ▶ L is the labeling function
Its domain is S , and tells us what is observable in a state.

Skipping Refinement

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\lesssim_r

Instruction Set Architecture

- ▶ `add rd, ra, rb`
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\mathcal{M}_C is a *skipping refinement* of \mathcal{M}_A with respect to a refinement map $r : S_C \rightarrow S_A$, if there exists a relation $B \subseteq S_C \times S_A$ such that the following holds.

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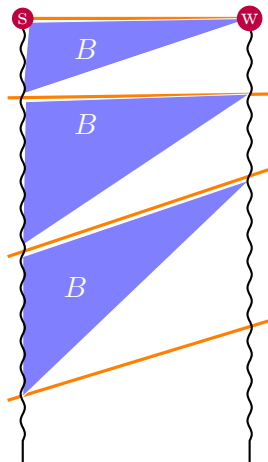
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- ▶ $\langle \forall s \in S_C :: sBr.s \rangle$ and
- ▶ B is a skipping simulation relation on the disjoint union of \mathcal{M}_C and \mathcal{M}_A

Skipping Simulation (SKS)

$B \subseteq S \times S$ is an SKS on \mathcal{M} iff for all s, w , such that sBw following holds.

- ▶ $L.s = L.w$ and
- ▶ $\langle \forall \sigma : fp.\sigma.s : \langle \exists \delta : fp.\delta.w : \underline{match}(B, \sigma, \delta) \rangle \rangle$

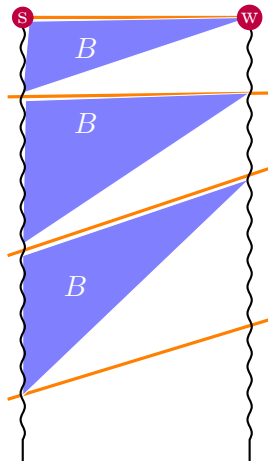


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Reason about **infinite** behaviors.

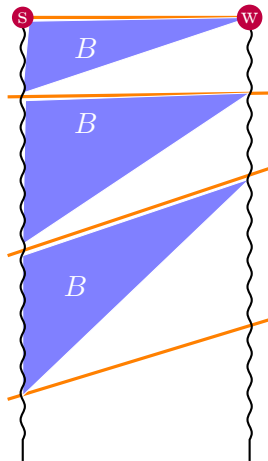


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Define an alternate characterization

Well-founded Skipping Simulation (WFSK)

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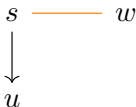
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- ▶ There exist functions, $rankT : S \times S \rightarrow W$,
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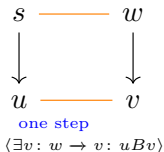
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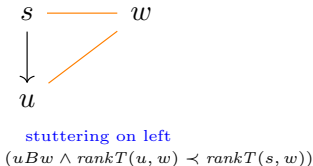
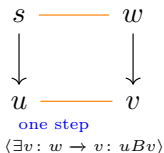
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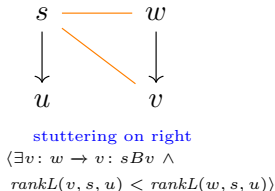
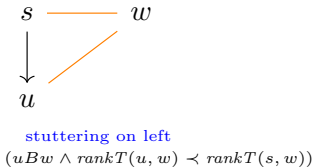
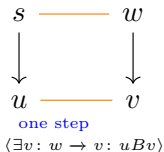
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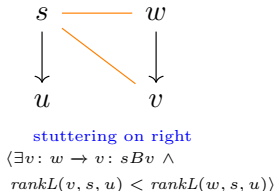
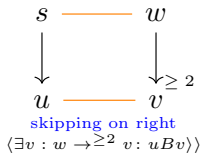
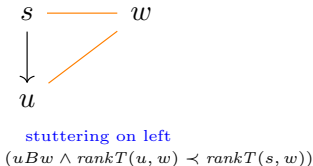
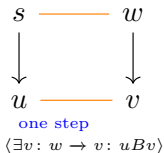
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Case Studies

- ▶ **Optimized Memory controller**
Buffers read/write requests to the memory and updates multiple memory location in a page simultaneously
- ▶ **JVM-inspired (buffered) Stack Machine**
Buffers instructions and eliminates redundant operations on stack
- ▶ **Vectorizing compiler transformation**
Vectorizes a sequence of scalar instructions to a Single Instruction Multiple Data (SIMD) instruction

Vectorizing compiler transformation

Analyze the source program and when possible replace scalar instructions with SIMD instructions.

$$\begin{array}{rcl} a & = & b + c \\ d & = & e + f \end{array} \rightarrow \begin{bmatrix} a \\ d \end{bmatrix} = \begin{bmatrix} b \\ e \end{bmatrix} +_{SIMD} \begin{bmatrix} c \\ f \end{bmatrix}$$

- ▶ Correctness of the transformation:

Given a scalar program, the target program generated by the transformation is equivalent to the scalar program.

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Proof of correctness by input-output equivalence can be tedious.

Skipping refinement gives a “local” proof method.

Scalar Machine: Operational semantics

State

```
(defdata scalar-op (enum '(add sub mul ...)))  
  
(defdata scalar-prog (listof scalar-inst))  
  
(defdata sprg-state (record (pc . program-counter)  
                             (regs . register-file)  
                             (sprg . scalar-prog)))
```

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Transition relation for deterministic scalar machine

```
(defun step-sprg (s)  
  (let* ((inst (nth (sprg-state-pc s) (sprg-state-sprg s)))  
         (op (inst-scalar-op inst))  
         ...)   
    (case op  
      (add (execute-add ... ))  
      ... )))
```

Vector Machine: Operational semantics

State

```
(defdata vector-ops (enum '(vadd vsub vmul ...)))  
  
(defdata inst (oneof scalar-inst vector-inst))  
  
(defdata vector-prog (listof inst))  
  
(defdata vprg-state (record (pc . program-counter)  
                             (regs . register-file)  
                             (vprg . vector-prog)))
```

Transition relation for deterministic vector machine

```
(defun step-vprg (s)  
  (let* ((inst (nth (vprg-state-pc s) (vprg-state-vprg s)))  
         (op (get-op inst))  
         ... )  
    (case op  
      (add (execute-add ...))  
      (vadd (execute-vadd ...))  
      ... )))
```

Vector machines refines scalar machine

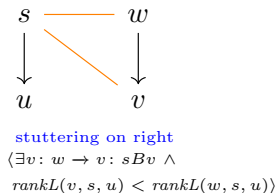
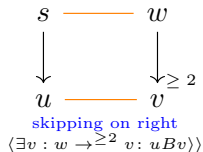
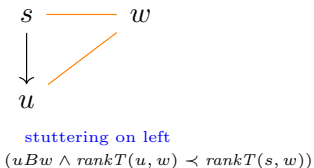
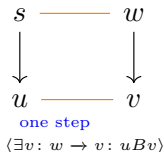
Refinement map

```
(defun ref-map (s)
  (let* ((rf (vprg-state-regs s))
         (vprg (vprg-state-vprg s))
         (vprg-pc (vprg-state-pc s))
         (sprg-pc (pcT (1- vprg-pc) vprg)))
    (sprg-state sprg-pc
                rf
                (scalarize-vprg vprg))))
```

pcT maps value of the vector machine's program counter to the corresponding value of the scalar machine's program counter.

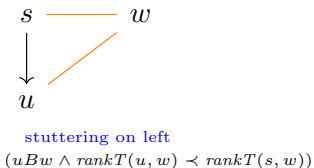
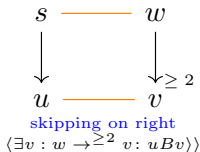
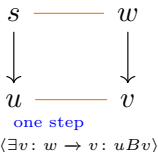
Vector Machines Refines Scalar Machine

Define $B = \{(s, w) \mid w = (\text{ref-map } s)\}$.



Vector Machines Refines Scalar Machine

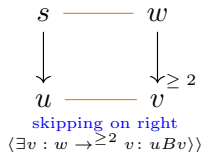
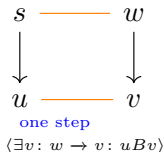
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sprg does not stutter

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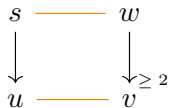
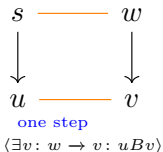


vprg does not stutter

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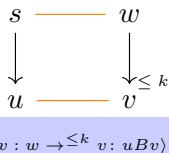
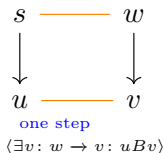
$\langle \exists v : w \rightarrow_{\geq 2} v : uBv \rangle$

vprg does not stutter

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vprg does not stutter

sprg does not stutter

An upper bound on skipping (k)

Maximum width of a vector instruction

Vector Machines Refines Scalar Machine

Final Theorem

$$\begin{array}{ccc} s & \xrightarrow{\quad} & w \\ \downarrow & & \downarrow \leq k \\ u & \xrightarrow{\quad} & v \end{array}$$

bounded skipping on right
 $\langle \exists v : w \rightarrow^{\leq k} v : uBv \rangle$

```
(defthm vprg-skip-refines-sprg
  (implies (and (vprg-statep s)
                (equal w (ref-map s))
                (equal u (step-vprg s))))
  (step-sprg-k-skip-rel w (ref-map u))))
```

Main lemmas

Let \mathbf{s} be a `vprg-state`, `vpc` be the program counter in \mathbf{s} and `inst` be the instruction pointed by `vpc` in `vprg`.

Let $\mathbf{w} = (\text{ref-map } \mathbf{s})$ and `spc` be the program counter in \mathbf{w} .

- ▶ Lemma 1: If `inst` is a scalar instruction, then the corresponding instruction pointed by `spc` in \mathbf{w} is also `inst`.
- ▶ Lemma 2: If `inst` is a vector instruction composed of k scalar instructions, say s_0, \dots, s_{k-1} , then the corresponding instruction pointed by `spc + i` in \mathbf{w} is s_i , for $i \in [0, k - 1]$.

Skipping refinement is amenable for mechanical reasoning.

- ▶ An a priori knowledge of upper bound on skipping avoids reasoning about unbounded reachability.
- ▶ The proof obligations can often be simplified based on domain specific knowlege.

Other case studies

► Optimized Memory Controller

```
(defthm optmemc-skip-refines-memc
  (implies (and (good-statep s)
                (equal w (ref-map s))
                (equal u (impl-step s))
                (not (and (equal w (ref-map u))
                          (< (rank u) (rank s))))))
            (spec-step-k-skip-rel w (ref-map u))))
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► JVM-inspired stack machine

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- Same WFSK to analyze correctness of systems.
- ACL2s automatically proves the theorem with *no additional lemmas* for buffer depth upto 3.

Conclusion

- ▶ A notion of refinement that directly accounts for skipping behavior in optimized reactive systems.
- ▶ A sound and complete proof method for reasoning about skipping refinement.
- ▶ Validated the proof method by mechanically reasoning correctness of three optimized systems with ACL2s.

Future Work

- ▶ Complete local characterization of skipping refinement.
- ▶ Compositionality of skipping refinement.
- ▶ Use GL-framework for finite state models of systems.
- ▶ Refinement-based testing framework.

Thank You