

Proof Reduction of Fair Stuttering Refinement of Asynchronous Systems and Applications

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Motivation

- ▶ Hardware/software implementation systems attempt to optimize task execution:
 - ▶ break-up tasks into more manageable chunks..
 - ▶ ..schedule chunks for execution over time and resources
- ▶ Intuitive specification:
 - ▶ all tasks eventually complete..
 - ▶ ..with results consistent with atomic (as possible) task execution
- ▶ Assume specification defined as simpler system and show that the behaviors of the implementation are consistent with the specification.
 - ▶ Additional theorems or properties could be proven about the simpler specification system as needed..

Fair Stuttering Refinement

- ▶ Assume implementation and specification defined as systems and prove:
 - ▶ all *fair* runs of implementation map to *valid* runs of specification upto finite stutter:
 1. a run is *fair* if every task is eventually selected.
 2. a run is *valid* if every task is eventually selected AND changes state.
 3. specification either matches implementation or stutters.
 - ▶ A task which is selected must change state unless it is *blocked*
- ▶ *Refinement* compactly encapsulates safety and progress properties of the implementation.
- ▶ Unwieldy to prove properties on infinite runs directly..
- ▶ ..define functions and properties over single steps of a small number of tasks and derive results relating infinite runs.

Example: Bakery Algorithm

Algorithm Bakery Task

```
1: choosing  $\leftarrow$  't
2: temp  $\leftarrow$  shared.max
3: pos  $\leftarrow$  temp + 1
4: if (shared.max  $\leq$  temp) shared.max  $\leftarrow$  pos
5: choosing  $\leftarrow$  'nil
6: for every task do
7:   wait if task.choosing
8:   wait if  $\text{lex} < (\textit{task.pos}, \textit{task.id}, \textit{pos}, \textit{id})$ 
9: ..critical section.. goto 1
```

Example: Bakery Specification

Algorithm Specification Task

- 1: $state \leftarrow \text{'interested}$
 - 2: $state \leftarrow \text{'go}$ **if** $task.state \neq \text{'go}$ for all $task$
 - 3: *..critical section..*
 - 4: $state \leftarrow \text{'idle}$ **goto** 1
-

- ▶ Ensures at most one task in critical section at any time..
 - ▶ A *fair run* does NOT ensure every task eventually reaches critical section.. BUT..
 - ▶ A *valid run* does ensure every task eventually reaches critical section!

Requirements for Refinement Proofs

1. Split step into an update function and blocking relation.
 2. Prove that specification can match implementation
 - ▶ Specification can stutter a finite amount between steps
 3. Prove that implementation has no deadlocks amongst tasks.
 4. Prove that implementation has no starvation of tasks.
 5. Prove sufficient conditions are invariant in implementation.
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- ▶ Primary contribution is a theory that demonstrates (*fair stuttering*) *refinement* as a result of defining the necessary functions and proving these properties.

Bakery Algorithm: Update and Blocking

- ▶ Split step into **update** function and **blocking** relation:

```
1: choosing ← 't
2: temp ← shared.max
3: pos ← temp + 1
4: if (shared.max ≤ temp) shared.max ← pos
5: choosing ← 'nil
6: for every task do
7:   wait if task.choosing
8:   wait if lex<(task.pos, task.id, pos, id)
9: ..critical section.. goto 1
```

Bakery Algorithm: Blocking Relation

for every *task* do

wait if *task.choosing*

wait if $\text{lex} < (\text{task.pos}, \text{task.id}, \text{pos}, \text{id})$

- ▶ Split task step into update and blocking relations..

```
(defun t-block (a b)
  (or (and (= (g :loc a) 5) (g :choosing b))
      (and (= (g :loc a) 6)
            (lex< (g :pos b) (ndx (g :id b))
                  (g :pos a) (ndx (g :id a))))))
```


Refinement Proof: Matching Specification-1

- ▶ Mapping Bakery Task states to 'idle', 'interested', and 'go':

```
1: choosing ← 't
2: temp ← shared.max
3: pos ← temp + 1
4: if (shared.max ≤ temp) shared.max ← pos
5: choosing ← 'nil
6: for every task do
7:   wait if task.choosing
8:   wait if lex<(task.pos, task.id, pos, id)
9: ..critical section.. goto 1
```

Refinement Proof: Matching Specification-2

- ▶ Define (t-map a) and (t-rank a):
 - ▶ (t-map a) maps a bakery task state to a specification task.
 - ▶ (t-rank a) returns ordinal decreases on bakery steps which are not matched in specification.
 - ▶ t-rank for 'interested states returns “distance” remaining to transition to 'go state
 - ▶ when specification match is blocked, then implementation must have been blocked..

```
(implies (and ... (t-next a b))
  (if (equal (t-map a) (t-map b))
      (o< (t-rank b) (t-rank a))
      (and (spec-next (t-map a) (t-map b))
           (implies (spec-block (t-map a) (t-map c))
                     (t-block a c)))))
```

Refinement Proof: Ensuring No Deadlocks

for every *task* do

wait if *task.choosing*

wait if $\text{lex} < (\text{task.pos}, \text{task.id}, \text{pos}, \text{id})$

- ▶ Ensuring lack of deadlock: define a rank which decreases when one task blocks another..

```
(defun t-nlock (a)
  (make-ord 2 (if (g :choosing a) 1 2)
    (make-ord 1 (1+ (nfix (g :pos a)))
      (ndx (g :id a))))))
```

....

```
(thm (implies (and ... (t-block a b))
  (o< (t-nlock b) (t-nlock a))))
```

Refinement Proof: Ensuring No Starvation - 1

for every *task* do

wait if *task.choosing*

wait if $\text{lex} < (\text{task.pos}, \text{task.id}, \text{pos}, \text{id})$

- ▶ Ensuring No Starvation: first define a predicate which defines when a task can no longer be blocked by another task..

```
(defun t-noblk (a b)
  (or (and (≠ (g :loc a) 5) (≠ (g :loc a) 6))
      (and (not (g :choosing b))
            (> (g :pos b) (g :pos a))))))
```

....

```
(thm (implies (and .. (t-next b c) (t-noblk a b))
              (and (not (t-block a b))
                    (t-noblk a c))))
```

Refinement Proof: Ensuring No Starvation - 2

for every *task* do

wait if *task.choosing*

wait if $\text{lex} < (\text{task.pos}, \text{task.id}, \text{pos}, \text{id})$

- ▶ Ensuring No Starvation: ..and then define a rank which decreases until we reach `t-noblk` state.

```
(defun t-nstrv (a b)
  ... "distance" from task state b to reach a state where
  ... b is no longer choosing and b.pos greater than a.pos)
```

....

```
(thm (implies (and .. (t-next b c)
                      (not (t-noblk a b))
                      (not (t-noblk a c)))
             (bnl< (t-nstrv a c) (t-nstrv a b) ..)))
```



Refinement Proof: Prove Sufficient Conditions are Invariant

- ▶ For the sake of this paper.. no magic here.. we have to define an invariant which:
 - ▶ Implies the conditions sufficient to prove the other properties..
 - ▶ ..and is *inductive* – holds on initial states and across steps.
- ▶ For the Bakery.. the invariants were fairly straightforward properties relating task positions, code locations, and the shared variables..
 - ▶ ..but nonetheless relatively substantial compared to the other definitions and proofs

Comparison to Previous Efforts..

- ▶ Previous efforts at proving concurrent program refinements:
‘‘Specification and Verification of Concurrent Programs Through Refinements’’
-- S. Ray and R. Sumners, J. Autom. Reasoning, 2013
- ▶ In comparison, the previous efforts...
 - ▶ Supported more general forms of system definition with less assumptions.
 - ▶ Required bolting definition of specific fairness and progress tracking apparatus onto the system state.
 - ▶ Used simpler refinement properties, but required more complex rank functions and more components in invariants.
 - ▶ Muddled correctness of specification by need to review correctness of measures for fairness and progress.
 - ▶ Did not facilitate efficient finite-state property checking.

Further Considerations, Questions.

- ▶ This is one step along the path.. to take it further:
 - ▶ Relaxing system definition requirements?
 - ▶ For example, allowing synchronous task updates?
 - ▶ Efficiently reducing to finite-state checks?
 - ▶ Can we break properties down into smaller theorems, GL/GLMC checks
 - ▶ Many other considerations...
- ▶ Rump Session: Efficient Checking of Fair Stuttering Refinements of Finite State Systems in ACL2!

Questions?