#### A FREE GROUP OF ROTATIONS OF RANK 2

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# Summary

- Define a set of 3D matrices
- Prove all the elements of the set are different from each other
- Formalize 3D rotations in ACL2(r)
- Prove every element of the set is a rotation



#### Motivation

- The Banach-Tarski theorem in ACL2(r)
- "The Banach-Tarski Paradox" by Tom Weston<sup>1</sup>



## Method

- Define a set of words of rank 2 example words: aa, bb, a<sup>-1</sup>b, ...
- Prove group properties for the set of words
- Associate a, b, a<sup>-1</sup>, b<sup>-1</sup> with specific 3D rotations
   For example:

$$A^{\pm} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{3} & \mp \frac{2\sqrt{2}}{3} \\ 0 & \pm \frac{2\sqrt{2}}{3} & \frac{1}{3} \end{bmatrix} \quad B^{\pm} = \begin{bmatrix} \frac{1}{3} & \mp \frac{2\sqrt{2}}{3} & 0 \\ \pm \frac{2\sqrt{2}}{3} & \frac{1}{3} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- Compose each word with matrix multiplication The 3D matrix we get with the word *aa* is A×A
- Prove these matrices are rotations and different from each other

### Outline

- 1. A Free Group of Reduced Words
- 2. A Free Group of 3D matrices
- 3. A Free Group of 3D Rotations of rank 2
- 4. Next steps



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#### Weak Word

(weak-wordp w) returns true if w is:

- An Empty list, or
- A list of characters that contains a or a<sup>-1</sup> or b or b<sup>-1</sup>
  - e.g., (), (a b b<sup>-1</sup>)
- In the ACL2(r) source files we have used characters
   #\a, #\b, #\c and #\d respectively



### Reduced Word

(reducedwordp w) returns true if w is:

- a weak-word, and
- a and a<sup>-1</sup> or b and b<sup>-1</sup> does not appear next to each other in the list
  - e.g., (), (a b b a<sup>-1</sup>)
  - (a a<sup>-1</sup>) is not a reduced word

A reduced word  $\Rightarrow$  it is a weak word

# Compose - Group operation

(compose x y) = (word-fix (append x y))
 where x and y are weak-words

- append operation appends two lists
- word-fix fixes the list so that the result is a reduced

word

- e.g., (compose (a b b a) (a<sup>-1</sup> b<sup>-1</sup> b))
  - = (word-fix ( $a b b a a^{-1} b^{-1} b$ ))



#### **Useful Lemmas**

- (reducedwordp x)  $\Rightarrow$  (weak-wordp x)
- (weak-wordp x)  $\Rightarrow$  (reducedwordp (word-fix x))
- (weak-wordp x)  $\land$  ((word-fix x) = x)

 $\Rightarrow$  (reducedwordp x)

- (weak-wordp x)  $\Rightarrow$  (weak-wordp (cdr x))
- (reducedwordp x)  $\Rightarrow$  ((word-fix x) = x)
- (reducedwordp x)  $\Rightarrow$  (reducedwordp (cdr x))



#### **Inverse Operation**

#### (word-inverse x) = (rev (word-flip x))

where x is a weak-word

- word-flip operation changes the characters a to a<sup>-1</sup>,
   b to b<sup>-1</sup>, a<sup>-1</sup> to a and b<sup>-1</sup> to b.
  - e.g., (word-flip (a b b)) = (a<sup>-1</sup> b<sup>-1</sup> b<sup>-1</sup>)



# The Identity Element

- Empty list is the identity element
- (reducedwordp x)  $\Rightarrow$  (word-fix (append () x)) = x

$$\Rightarrow$$
 (compose () x) = x

• (reducedwordp x)  $\Rightarrow$  (word-fix (append x ())) = x

$$\Rightarrow$$
 (compose x ()) = x



# **Closure Property**

#### **Intermediate Lemmas:**

(weak-wordp x) \lapha (weak-wordp y)

 $\Rightarrow$  (weak-wordp (append x y))

(reducedwordp x) \lapha (reducedwordp y)

 $\Rightarrow$  (weak-wordp (append x y))

#### **Closure:**

(reducedwordp x)  $\land$  (reducedwordp y)

 $\Rightarrow$  (reducedwordp (word-fix (append x y)))

[ $\because$  (weak-wordp x)  $\Rightarrow$  (reducedwordp (word-fix x))]

 $\Rightarrow$  (reducedwordp (compose x y))



# **Associative Property**

#### **Key Lemmas:**

• (weak-wordp x)  $\land$  (weak-wordp y)  $\land$  (weak-wordp z)

 $\Rightarrow$  (word-fix (append x y z))

= (word-fix (append x (word-fix (append y z))))

- (weak-wordp x)  $\Rightarrow$  (word-fix (rev x)) = (rev (word-fix x))

  - Proved by induction on x
    e.g., (word-fix (rev (a b b<sup>-1</sup>)) = (word-fix (b<sup>-1</sup> b a)) = (a)  $(rev (word-fix (a b b^{-1})) = (rev (a)) = (a)$



#### **Associative Property**

(reducedwordp x)  $\land$  (reducedwordp y)  $\land$  (reducedwordp z)  $\Rightarrow$ (compose (compose x y) z) = (compose x ( compose y z))



# **Inverse Property**

#### **Intermediate Lemmas:**

- (reducedwordp x)  $\Rightarrow$  (reducedwordp (word-inverse x))
  - (word-fix (rev x)) = (rev x)
  - (reducedwordp (word-flip x))
- (weak-wordp x)  $\Rightarrow$  (word-inverse (word-inverse x)) = x
  - n<sup>th</sup> values of (word-inverse (word-inverse x) and x are equal
  - Using equal-by-nths lemma

**Inverse exists** (using the above lemmas and the associativity) :

- (reducedwordp x)  $\Rightarrow$  (compose x (word-inverse x)) = ()
- (reducedwordp x)  $\Rightarrow$  (compose (word-inverse x) x) = ()



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### Matrix Algebra

1. Gamboa, Ruben, John Cowles, and J.V. Baalen. "Using ACL2 arrays to

formalize matrix algebra." Fourth International Workshop on the ACL2

Theorem Prover and Its Applications (ACL2'03). Vol. 1. 2003.

2. Lambán, Laureano, Francisco J. Martín-Mateos, Julio Rubio, and José-Luis

Ruiz-Reina. "Using abstract stobjs in ACL2 to compute matrix normal

forms." In International Conference on Interactive Theorem Proving, pp.

354-370. Springer, Cham, 2017.



# Matrix Algebra using array2p

- matrix equivalence
- matrix multiplication
- matrix transpose
- scalar multiplication
- Associativity of the matrix multiplication
- properties about dimensions of the matrices

#### Newly added:

- r3-matrixp (predicate for a 3D matrix in ACL2(r))
- r3-m-determinant (determinant of a 3D matrix)
- r3-m-inverse (Inverse of a 3D matrix)



#### A Set of 3D Matrices



(rotation w) = if w is an empty list then return *id-matrix* else if (car w) = a: return ( $A \times$  (rotation (cdr w)) else if (car w) = b: return ( $B \times$  (rotation (cdr w))) else if (car w) =  $a^{-1}$ : return ( $A^{-1} \times$  (rotation (cdr w))) else if (car w) =  $b^{-1}$ : return ( $B^{-1} \times$  (rotation (cdr w)))

set = { (rotation w) | (reducedwordp w) }



### A Free Group of 3D matrices

Let p = (0,1,0), then: If (reducedwordp w)  $\land$  ((len w) = n)  $\land$  (((rotation w)  $\times$  p) = q)  $\land$  n > 0 we have shown by induction: q is of the form  $(\frac{1}{3}^{n})(a\sqrt{2}, b, c\sqrt{2})$ where a, b and c are integers

If w is an empty list, then (rotation w) is an identity matrix, then  $q = p = (0,1,0) \Rightarrow a \equiv b \equiv c \equiv 0 \pmod{3}$ (This is not possible)



### A Free Group of 3D matrices

If w is a reduced word and let's say  $(n-mod3 w) = (a,b,c) \pmod{3}$ , then

 $\begin{array}{ll} (n-mod3 \ aw) &= (0, b - c, c - b) \ (mod \ 3) \\ (n-mod3 \ a^{-l}w) &= (0, b + c, c + b) \ (mod \ 3) \\ (n-mod3 \ bw) &= (a + b, a + b, 0) \ (mod \ 3) \\ (n-mod3 \ b^{-l}w) &= (a - b, b - a, 0) \ (mod \ 3) \end{array}$ 

By induction:

If w is a reduced word, and

if (car w) = a,then (n-mod3 w) = (0, 1, 2) or (0, 2, 1)if  $(car w) = a^{-1}$ ,then (n-mod3 w) = (0, 1, 1) or (0, 2, 2)if (car w) = b,then (n-mod3 w) = (1, 1, 0) or (2, 2, 0)if  $(car w) = b^{-1}$ ,then (n-mod3 w) = (2, 1, 0) or (1, 2, 0)

 $\therefore$  (n-mod3 w)  $\neq$  (0,0,0)  $\land$  ((len w) > 0)  $\Rightarrow$  (rotation w)  $\neq$  I



### A Free Group of 3D Matrices

Key lemma:

if  $w_1, w_2$ , are reduced words then (rotation  $w_1$ ) × (rotation  $w_2$ ) = (rotation (compose  $w_1, w_2$ )

Since (rotation w)  $\neq I$ , using the above lemma: if  $w_1, w_2$ , are two different reduced words having length > 1 then (rotation  $w_1$ )  $\neq$  (rotation  $w_2$ )



# Modular addition and subtraction

 $(A + B) \mod C = (A \mod C + B \mod C) \mod C$ 

 $(A - B) \mod C = (A \mod C - B \mod C) \mod C$ 

Proved using properties from the book:

workshops/1999/embedded/Exercises/Exercise1-2/Exercise1.2



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#### **3D Rotations**

M is a 3D rotation if:

- M is a 3D matrix
- $\mathbf{M}^{-1} = \mathbf{M}^{\mathrm{T}}$
- det(M) = 1



### **Properties of 3D Rotations**

- 1. (r3-matrixp  $m_1$ )  $\land$  (r3-matrixp  $m_2$ )  $\Rightarrow$  (r3-matrix ( $m_1 \times m_2$ ))
- 2. (r3-matrixp  $m_1$ )  $\land$  (r3-matrixp  $m_2$ )  $\Rightarrow$  det( $m_1 \times m_2$ )) = det( $m_1$ )  $\times$  det( $m_2$ )
- 3. (r3-matrixp  $m_1$ )  $\land$  (r3-matrixp  $m_2$ )  $\land$  det( $m_1$ )  $\neq$  0  $\land$  det( $m_2$ )  $\neq$  0

 $(m_1 \times m_2)^{-1} = m_2^{-1} \times m_1^{-1}$ 

- 4. (r3-rotationp m)  $\Rightarrow$  (r3-rotationp m<sup>-1</sup>)
- 5. (r3-rotation  $m_1$ )  $\land$  (r3-rotation  $m_2$ )  $\Rightarrow$  (r3-rotation  $(m_1 \times m_2)$ )
- 6. Rotations preserve distance

If 
$$p_1 = (x_1, y_1, z_1)$$
 and  $p_2 = R \times pl = (x_2, y_2, z_2)$ , then  
 $x_1^2 + y_1^2 + z_1^2 = x_2^2 + y_2^2 + z_2^2$ 



### A Free Group of Rotations

By induction, if w is a reduced word, then by using the properties:

• (rotation w) is a 3D rotation



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#### The Banach-Tarski Theorem

# Any Solid ball B in $R^3$ can be cut into finitely many pieces which can be rotated to form 2 copies of B<sup>1</sup>





#### The Hausdorff Paradox

- There is a countable set  $D \subseteq S^2$  such that
- $S^2 D$  can be divided into 5 pieces which can be rotated to form 2 copies of  $S^2 - D$ .<sup>1</sup>



#### The Hausdorff Paradox

For the set of reduced words W(a,b):

- $W(a,b) = () \square W(a) \square W(a^{-1}) \square W(b) \square W(b^{-1})$
- W(a,b) =  $a^{-1}W(a) \square W(a^{-1})$
- $W(a,b) = b^{-1}W(b) \square W(b^{-1})$

If R(a,b) is the free group, an orbit of a point p on  $S^2 = \{ \rho(p) \mid \rho \in R(a,b) \}$ , then

- $S^2$ -D = R(a,b)C = C  $\square$  R(a)C  $\square$  R(a<sup>-1</sup>)C  $\square$  R(b)C  $\square$  R(b<sup>-1</sup>)C
- $S^2$ -D =  $A^{-1}(R(a)C) \square R(a^{-1})C$
- $S^2-D = B^{-1}(R(b)C) \square R(b^{-1})C$

where  $\boldsymbol{C}$  is the choice set



#### References

- Weston, T.. "THE BANACH-TARSKI PARADOX." (2003).
- Gamboa, Ruben, John Cowles, and J. V. Baalen. "Using ACL2 arrays to formalize matrix algebra." Fourth International Workshop on the ACL2 Theorem Prover and Its Applications (ACL2'03). Vol. 1. 2003.
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Thank You

