CS378 Autonomous Multiagent Systems Spring 2004

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Week 2b: Thursday, January 29th

Good Afternoon, Colleagues

Are there any questions?



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Are there any questions?

• Will there be a definition? Does it matter?



- How did it go?
- Do we need a C tutorial?
- (1 more in C, then C++)





• Next programming assignment: communication





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- Discussion list: Thomas, Ben





- Next programming assignment: communication
- Discussion list: Thomas, Ben
- Littman talk



Aashish Parekh on the future of Agent Intelligence



Environments

Environment \implies sensations, actions



Environments

${\sf Environment} \Longrightarrow {\sf sensations}, {\sf actions}$

- fully observable vs. partially observable (accessible)
- deterministic vs. non-deterministic
- episodic vs. non-episodic
- static vs. dynamic
- discrete vs. continuous
- single-agent vs. multiagent



Your Agent Examples



Your Agent Examples

Physical control: automoated lawn mower, vacuum cleaner, security system, cruise control (3), finless rocket



Software control: java garbage collector, pccardd, computer virus, popup blocker, popup generator, stockbroker



Software control: java garbage collector, pccardd, computer virus, popup blocker, popup generator, stockbroker

Human interaction: Book finder, Amazon.com recommender, telephone voice control operator, chatbot, car navigation system, domino game-player



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Human interaction: Book finder, Amazon.com recommender, telephone voice control operator, chatbot, car navigation system, domino game-player

Biological: dog, human heart, human body minus brain

Other: National government (foreign relations)



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Discrete? Accessible? Deterministic? Static? Episodic?



The Decision



• reactive vs. deliberative



- reactive vs. deliberative
- multiagent reasoning?



- reactive vs. deliberative
- multiagent reasoning?
- learning?



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• Standard agent:

 $action: \mathcal{S}^* \mapsto \mathcal{A}$



- $action : \mathcal{P} \mapsto \mathcal{A}$
- Decision based entirely on the present



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Reactive agents for today's assignment task?



Agents and Objects



- Autonomy
- Flexibility
- Own thread of control

