REINFORCEMENT LEARNING: THEORY AND PRACTICE Ch. 2: Gradient Bandits

Profs. Amy Zhang and Peter Stone



Reading Response Questions

Sam Ziegelbein: "Why do we use the softmax distribution in gradient bandit algorithms, as opposed to some other method of converting preference values into probabilities? The exponentials sure seem nice to work with, but intuitively why is this distribution better than some other one?"

Gradient Bandits: Arm Preferences

$$\Pr\{A_t = a\} \doteq \frac{e^{H_t(a)}}{\sum_{b=1}^k e^{H_t(b)}} \doteq \pi_t(a)$$

Gradient Bandits: Arm Preferences

$$\Pr\{A_t = a\} \doteq \frac{e^{H_t(a)}}{\sum_{b=1}^k e^{H_t(b)}} \doteq \pi_t(a) \qquad \text{Differentiable}$$

Gradient Bandits: Arm Preferences

$$\Pr\{A_t = a\} \doteq \frac{e^{H_t(a)}}{\sum_{b=1}^k e^{H_t(b)}} \doteq \pi_t(a) \qquad \text{Differentiable}$$

$$H_{t+1}(A_t) \doteq H_t(A_t) + \alpha \left(R_t - \bar{R}_t \right) \left(1 - \pi_t(A_t) \right), \quad \text{and} \\ H_{t+1}(a) \doteq H_t(a) - \alpha \left(R_t - \bar{R}_t \right) \pi_t(a), \quad \text{for all } a \neq A_t$$

Updates can be high variance

Exact Gradient Ascent

$$H_{t+1}(a) \doteq H_t(a) + \alpha \frac{\partial \mathbb{E}[R_t]}{\partial H_t(a)}$$

Where expected reward is
$$\mathbb{E}[R_t] = \sum_x \pi_t(x)q_*(x)$$

Exact Performance Gradient

$$\frac{\partial \mathbb{E}[R_t]}{\partial H_t(a)} = \frac{\partial}{\partial H_t(a)} \left[\sum_x \pi_t(x) q_*(x) \right]$$
$$= \sum_x q_*(x) \frac{\partial \pi_t(x)}{\partial H_t(a)}$$
$$= \sum_x \left(q_*(x) - B_t \right) \frac{\partial \pi_t(x)}{\partial H_t(a)},$$

q doesn't depend on H

B can be an arbitrary scalar as long as it doesn't depend on x

Gradient Bandits: Baseline

How does expected return change w.r.t. prefs?

$$\frac{\partial \mathbb{E}[R_t]}{\partial H_t(a)} = \frac{\partial}{\partial H_t(a)} \left[\sum_x \pi_t(x) q_*(x) \right]$$
$$= \sum_x q_*(x) \frac{\partial \pi_t(x)}{\partial H_t(a)}$$
$$= \sum_x \left(q_*(x) - B_t \right) \frac{\partial \pi_t(x)}{\partial H_t(a)},$$

Gradient Bandits: Baseline

How does expected return change w.r.t. prefs?



Why are we allowed to subtract a baseline?

How does expected return change w.r.t. prefs?



Claim: a good baseline reduces variance of gradient and improves convergence

Theory: upper bounds on convergence rate of SGD are directly related to the variance of gradient estimates

Theory: upper bounds on convergence rate of SGD are directly related to the variance of gradient estimates

$$H_{t+1}(A_t) \doteq H_t(A_t) + \alpha \left(R_t - \bar{R}_t \right) \left(1 - \pi_t(A_t) \right), \quad \text{and} \\ H_{t+1}(a) \doteq H_t(a) - \alpha \left(R_t - \bar{R}_t \right) \pi_t(a), \quad \text{for all } a \neq A_t$$



Theory: upper bounds on convergence rate of SGD are directly related to the variance of gradient estimates

$$H_{t+1}(A_t) \doteq H_t(A_t) + \alpha \big(R_t - \bar{R}_t \big) \big(1 - \pi_t(A_t) \big), \quad \text{and} \\ H_{t+1}(a) \doteq H_t(a) - \alpha \big(R_t - \bar{R}_t \big) \pi_t(a), \quad \text{for all } a \neq A_t$$



Theory: upper bounds on convergence rate of SGD are directly related to the variance of gradient estimates

$$H_{t+1}(A_t) \doteq H_t(A_t) + \alpha \left(R_t - \bar{R}_t \right) \left(1 - \pi_t(A_t) \right), \quad \text{and} \\ H_{t+1}(a) \doteq H_t(a) - \alpha \left(R_t - \bar{R}_t \right) \pi_t(a), \quad \text{for all } a \neq A_t$$



Theory: upper bounds on convergence rate of SGD are directly related to the variance of gradient estimates

$$H_{t+1}(A_t) \doteq H_t(A_t) + \alpha \left(R_t - \bar{R}_t \right) \left(1 - \pi_t(A_t) \right), \quad \text{and} \\ H_{t+1}(a) \doteq H_t(a) - \alpha \left(R_t - \bar{R}_t \right) \pi_t(a), \quad \text{for all } a \neq A_t$$







