

Evolution of Neural Networks

Risto Miikkulainen

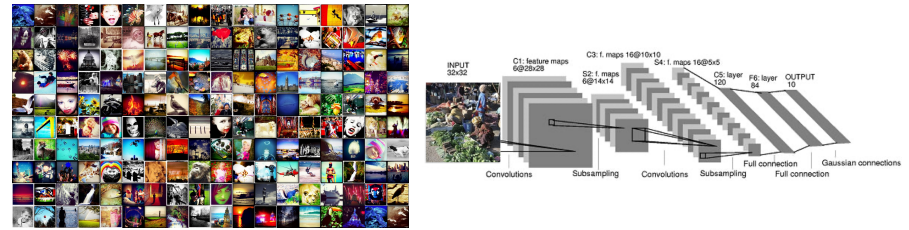
The University of Texas at Austin
and Cognizant AI Labs

Permission to make digital or hard copies of part or all of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for third-party components of this work must be honored. For all other uses, contact the Owner/Author.

GECCO '24 Companion, July 14-18, 2024, Melbourne, VIC, Australia
© 2024 Copyright is held by the owner/author(s).
ACM ISBN 979-8-4007-0495-6/24/07.
<https://doi.org/10.1145/3638530.3648407>

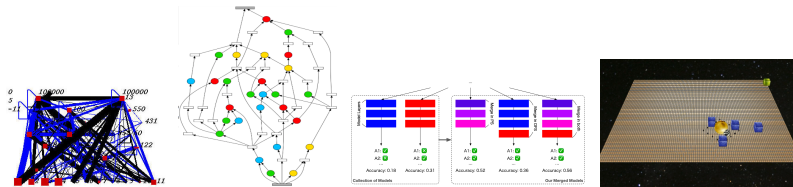


Why Use Neural Networks?



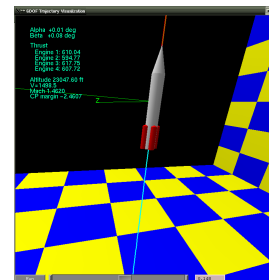
- ▶ Neural nets powerful in many statistical domains
 - ▶ E.g. vision, language, control, prediction, decision making
 - ▶ Where no good domain theory, but plenty of examples
- ▶ Good supervised training algorithms exist
 - ▶ Learn a nonlinear function that matches the examples
 - ▶ Utilize big datasets, big compute

Why Evolve Neural Networks?



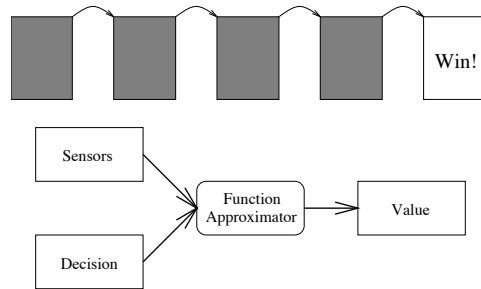
- ▶ **I. Original role (since 1990s): RL Tasks & especially POMDP**
 - ▶ Both the structure and the weights evolved (no training)
 - ▶ Power from recurrency; behavior
- ▶ **II. A new role (since 2016): Optimization of Deep Learning Nets**
 - ▶ Architecture, hyperparameters, functions evolved; weights trained
 - ▶ Power from complexity
- ▶ **III. A possible future role: Optimizing LLMs**
 - ▶ Orchestration of multiple LLMs
 - ▶ Evolution of prompts & fine-tuning
- ▶ **IV. A possible future role: Emergence of intelligence**
 - ▶ Body/brain co-evolution; Competitive co-evolution
 - ▶ Evolution of memory, language, learning

I. Reinforcement Learning / POMDP Tasks



- ▶ A sequence of decisions creates a sequence of states
 - ▶ States are only partially known
 - ▶ Optimal outputs are not known
 - ▶ We can only tell how well we are doing
- ▶ Exist in many important real-world domains
 - ▶ Robot/vehicle/traffic control
 - ▶ Computer/manufacturing/process optimization
 - ▶ Game playing; Artificial Life; Biological Behavior

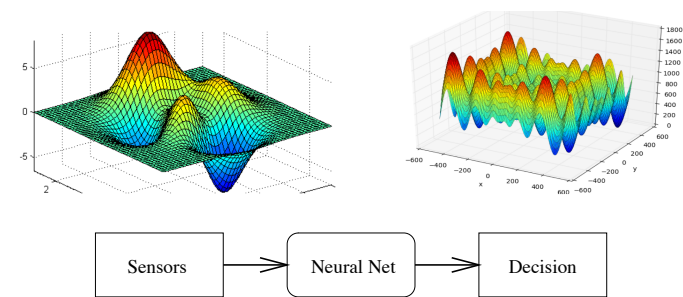
Value-Function Reinforcement Learning



- ▶ E.g. Q-learning, Temporal Differences
 - ▶ Generate targets through prediction errors
 - ▶ Learn when successive predictions differ
- ▶ Predictions represented as a value function
 - ▶ Values of alternatives at each state
- ▶ Difficult with large/continuous state and action spaces
- ▶ Difficult with hidden states

5/61

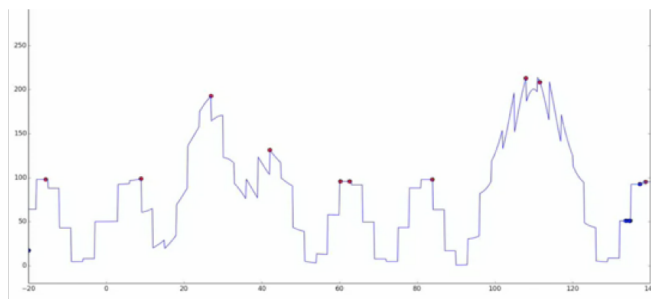
Policy-Search Reinforcement Learning



- ▶ E.g. REINFORCE, policy gradients
- ▶ The policy is optimized directly through hill climbing
- ▶ Works well in simple cases
 - ▶ Large/continuous states and actions possible
 - ▶ Hidden states (in POMDP) disambiguated through memory
 - ▶ Does not scale well

6/61

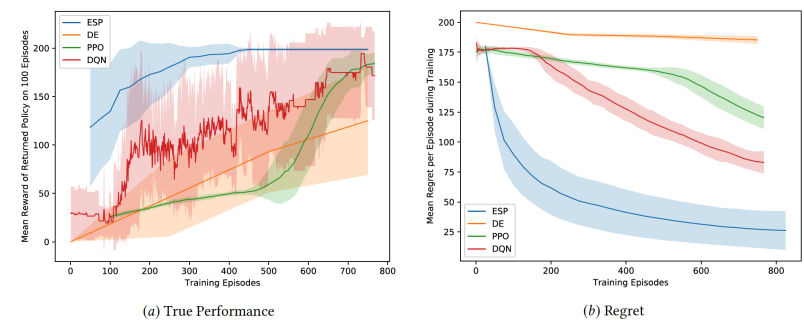
Neuroevolution Reinforcement Learning



- ▶ Takes advantage of population-based search
 - ▶ In essence, multiple interacting searches
 - ▶ Each discover building blocks that are combined
 - ▶ Extensive exploration possible
- ▶ Makes it possible to scale up:
 - ▶ to large spaces (e.g. 2^{270} states⁵⁶)
 - ▶ to high dimensionality (e.g. up to $1B^{12}$)
 - ▶ to deceptive landscapes (with e.g. multiobj and novelty⁸⁴)

7/61

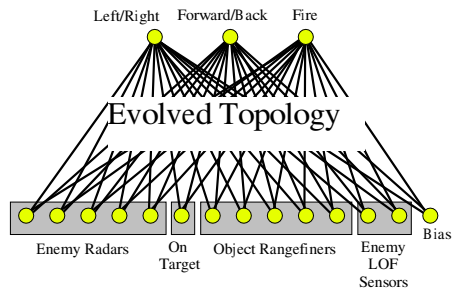
How Well Does It Work?



- ▶ In the OpenAI Gym CartPole-v0 benchmark vs. PPO, DQN
 - ▶ NE converges faster, has lower variance, lower regret
 - ▶ NE is more efficient, reliable, and safer¹⁸
- ▶ In a double-pole benchmark vs. Sarsa, Q-MLP, etc.
 - ▶ The only method that can find solutions to 1m, 0.1m, POMDP²³
- ▶ The fundamental difference is exploration
 - ▶ Evolution provides more exploration than gradients do^{35,78,92}

8/61

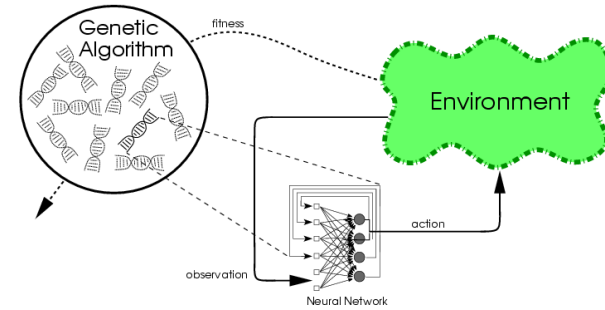
Neuroevolution for RL/POMDP



- ▶ Input variables describe the state observed through sensors
- ▶ Output variables describe actions
- ▶ Network between input and output:
 - ▶ Recurrent connections implement memory
 - ▶ Memory helps with POMDP

9/61

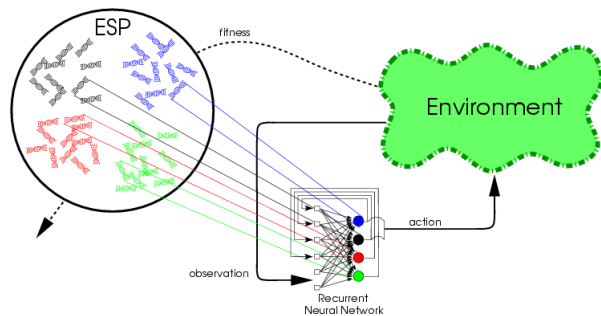
Basic Neuroevolution



- ▶ Evolving connection weights in a population of networks ^{62,79,103,104}
- ▶ Chromosomes are strings of connection weights (bits or real)
 - ▶ E.g. 10010110101100101111001
 - ▶ Usually fully connected, fixed, initially random topology
- ▶ A natural mapping between genotype and phenotype
 - ▶ GA and NN are a good match!

10/61

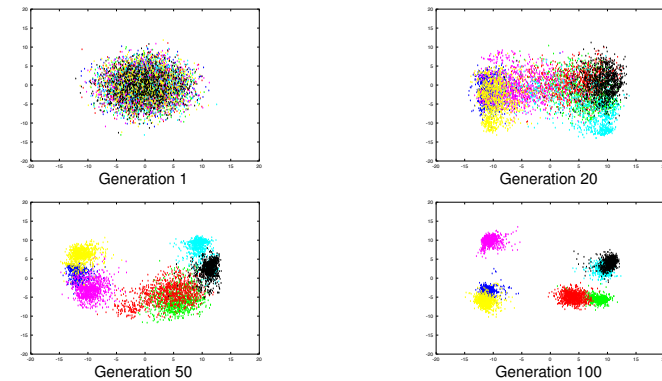
Advanced NE 1: Evolving Partial Networks



- ▶ Evolving individual neurons to cooperate in networks ^{1,63,66}
- ▶ E.g. Enforced Sub-Populations (ESP²¹)
 - ▶ Each (hidden) neuron in a separate subpopulation
 - ▶ Fully connected; weights of each neuron evolved
- ▶ Can be applied at the level of weights, and modules²³

11/61

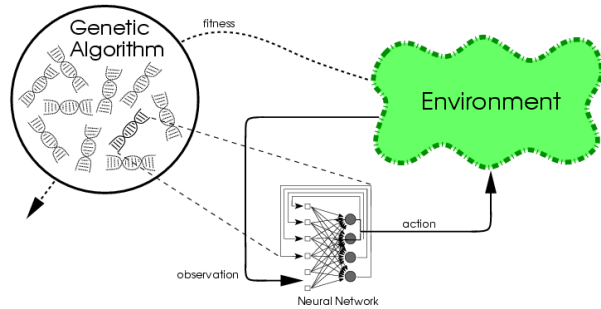
Why Is It a Good Idea?



- ▶ E.g. evolving neurons for robotic control
 - ▶ Simulated Kheperas running a maze
- ▶ Subpopulations discover & optimize compatible subtasks
 - ▶ E.g. slow down with obstacle on front
 - ▶ veer left with obstacle at right, etc.
- ▶ Each neuron part of 2-3 subtasks
 - ▶ Robust coding of behavior during search

12/61

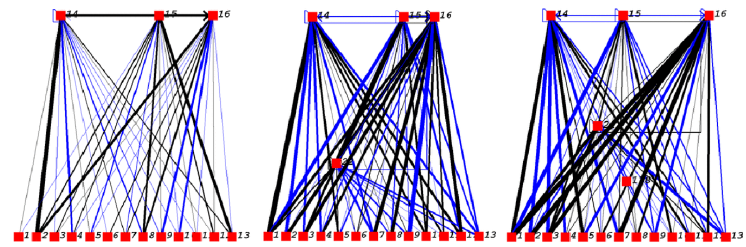
Advanced NE 2: Evolutionary Strategies



- ▶ Evolving complete networks with ES (CMA-ES³¹)
- ▶ Small populations, no crossover
- ▶ Instead, intelligent mutations
 - ▶ Adapt covariance matrix of mutation distribution
 - ▶ Take into account correlations between weights
- ▶ Why is it a good idea?
 - ▶ Discovers good weight combinations → CM

13/61

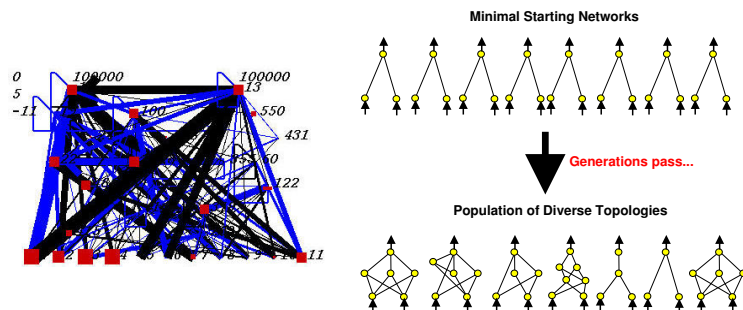
Advanced NE 3: Evolving Network Structure



- ▶ Optimizing connection weights and network topology^{3,15,19,105}
- ▶ E.g. Neuroevolution of Augmenting Topologies (NEAT^{86,89})
- ▶ Based on *Complexification*
- ▶ Of networks:
 - ▶ Mutations to add nodes and connections
- ▶ Of behavior:
 - ▶ Elaborates on earlier behaviors

14/61

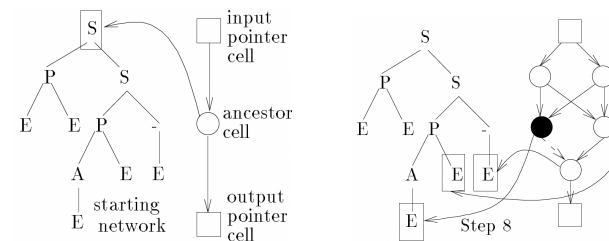
Why Is It a Good Idea?



- ▶ NN search space is complex with nonlinear interactions
- ▶ Complexification keeps the search tractable
 - ▶ Start simple, add more sophistication
- ▶ Incremental discovery of complex solutions

15/61

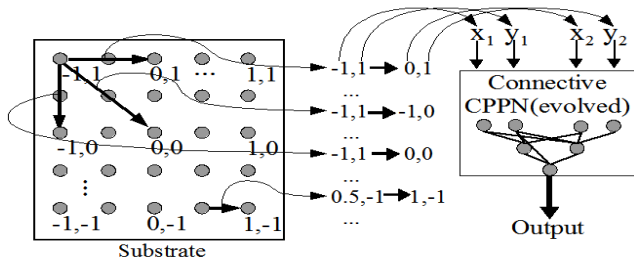
Advanced NE 4: Indirect Encodings (1)



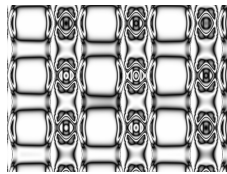
- ▶ Instructions for constructing the network evolved
 - ▶ Instead of specifying each unit and connection^{3,15,61,85,105}
- ▶ E.g. Cellular Encoding (CE²⁷)
- ▶ Grammar tree describes construction
 - ▶ Sequential and parallel cell division
 - ▶ Changing thresholds, weights
 - ▶ A “developmental” process that results in a network

16/61

Indirect Encodings (2)

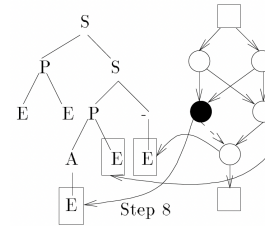


- ▶ Encode the networks as spatial patterns
- ▶ E.g. Hypercube-based NEAT (HyperNEAT¹⁰)
- ▶ Evolve a neural network (CPPN) to generate spatial patterns
 - ▶ 2D CPPN: (x, y) input \rightarrow grayscale output
 - ▶ 4D CPPN: (x_1, y_1, x_2, y_2) input $\rightarrow w$ output
 - ▶ Connectivity and weights can be evolved indirectly
 - ▶ Works with very large networks (millions of connections)

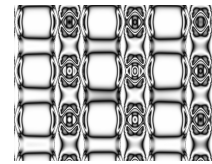


17/61

Why Is It a Good Idea?

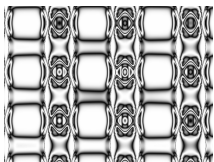
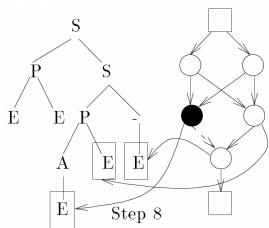


- ▶ Describes structure efficiently
 - ▶ Recurrency symbol in CE: XOR \rightarrow parity
 - ▶ Repetition with variation in CPPNs
- ▶ Useful for evolving topology
 - ▶ E.g. large structured networks
 - ▶ E.g. repetition of motifs



18/61

Future Opportunities



- ▶ Several possible directions
 - ▶ More general L-systems; developmental codings; embryogeny⁹⁰
 - ▶ Scaling up spatial coding^{11,20}
 - ▶ Genetic Regulatory Networks⁷⁵
 - ▶ Evolution of symmetries⁹⁹
- ▶ Theory starting to emerge
 - ▶ Expressive Encodings⁵⁵: Simple GAs are universal probability approximators

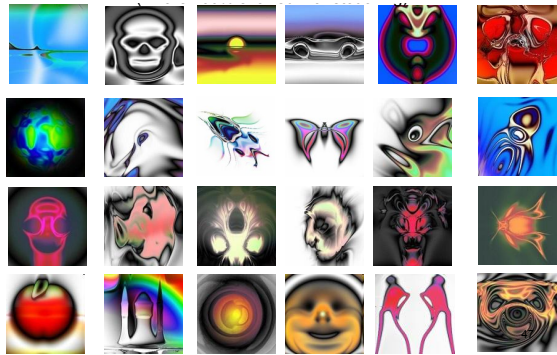
19/61

Further NE Techniques

- ▶ Incremental and multiobjective evolution^{22,82,98,104}
- ▶ Utilizing population culture^{4,47,95}
- ▶ Utilizing evaluation history⁴⁶
- ▶ Evolving NN ensembles and modules^{33,45,65,76,101}
- ▶ Evolving transfer functions and learning rules^{8,77,91}
- ▶ Bilevel optimization of NE⁴³
- ▶ Evolving LSTMs for strategic behavior³⁹
- ▶ Extrapolation with Context+Skill modules⁹⁷
- ▶ Combining learning and evolution^{7,16,47,64,87,95,102}
- ▶ Evolving for novelty

20/61

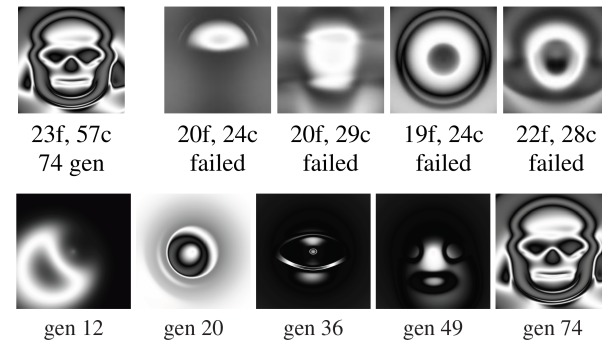
Evolving for Novelty



- ▶ Motivated by humans as fitness functions
- ▶ E.g. picbreeder.com, endlessforms.com⁸³
 - ▶ CPPNs evolved; Human users select parents
- ▶ No specific goal
 - ▶ Interesting solutions preferred
 - ▶ Similar to biological evolution?

21/61

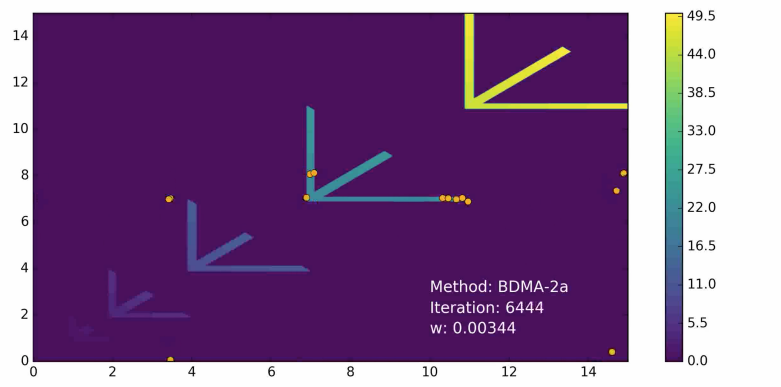
Novelty Search



- ▶ Evolutionary algorithms maximize a performance objective
 - ▶ But sometimes hard to achieve it step-by-step
- ▶ Novelty search rewards candidates that are simply different^{37,88}
 - ▶ Stepping stones for constructing complexity

22/61

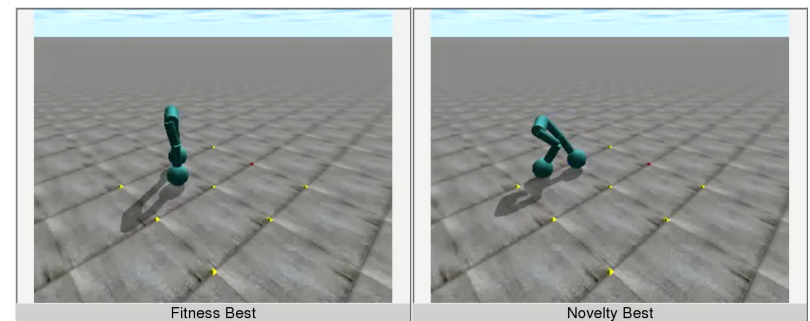
Novelty Search Demo (1)



- ▶ Illustration of stepping stones^{49,50}
 - ▶ Nonzero fitness on “feet” only; stepwise increase
 - ▶ Top and right “toes” are stepping stones to next “foot”
 - ▶ Difficult for fitness based search; novelty can do it
- ▶ DEMO

23/61

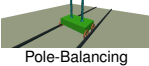
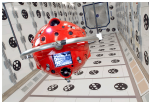
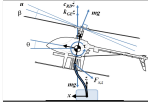
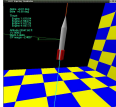
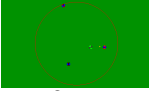
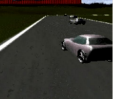
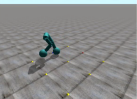

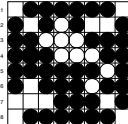



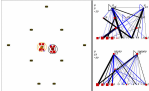

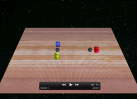
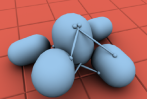
Novelty Search Demo (2)



- ▶ Fitness-based evolution is rigid
 - ▶ Requires gradual progress
- ▶ Novelty-based evolution is more innovative, natural^{37,88}
 - ▶ Allows building on stepping stones
- ▶ How to guide novelty search towards useful solutions?
 - ▶ Quality Diversity methods^{17,67}
- ▶ DEMO

24/61

Neuroevolution Applications

Control	 Pole-Balancing	 Satellite Asst.	 Helicopter	 Rocket
Robotics	 Soccer	 Driving	 Bipedal	 Multilegged
Games	 Othello	 NERO	 Pac-Man	 Unreal
Alife	 Duel	 Predators	 Hyenas/Zebbras	 Virtual Creatures

25/61

Example 1: Evolving Humanlike Behavior



- ▶ Botprize competition, 2007-2012
 - ▶ Turing Test for game bots (\$10,000 prize)
- ▶ Three players in Unreal Tournament 2004:
 - ▶ Human confederate: tries to win
 - ▶ Software bot: pretends to be human
 - ▶ Human judge: tries to tell them apart!

26/61

Evolving an Unreal Bot



- ▶ Wandering, unstuck etc. based on scripts & learning from humans
- ▶ Evolve effective fighting behavior⁸¹
- ▶ Persistent gap: 30% vs. 80% human
 - ▶ Evolving to win results in unnatural behaviors
 - ▶ Human judges do not understand their expertise

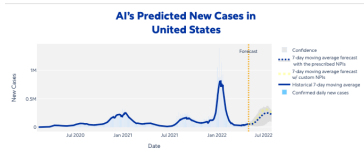
27/61

After Five Years, Success!!!

- ▶ Human-like behavior with resource limitations (speed, accuracy...
 - ▶ Best bot better than 50% of the humans
 - ▶ Two teams human 50% of the time
- ▶ Fascinating challenges remain:
 - ▶ Judges can still differentiate in seconds
 - ▶ Judges lay cognitive, high-level traps
 - ▶ Team competition: collaboration as well
- ▶ DEMO

28/61

Example 2: Optimizing COVID-19 NPIs

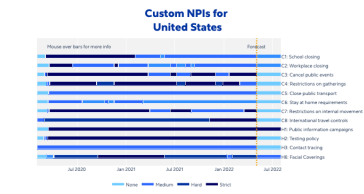


- Train a NN to predict COVID-19 cases
- Based on number of cases in different countries over time
 - And non-pharmaceutical interventions (NPIs) over time

Using the predictive model as a surrogate, evolve a NN to recommend NPIs

- Resulting in smallest number of cases
- With minimal economic cost

Not just what will happen, but what we should do about it!



29

Cognizant

COVID-19 Predictions and Prescriptions

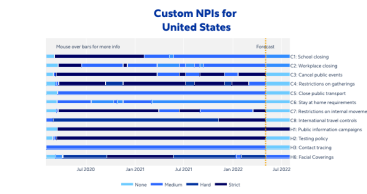


Retrained daily since May 2020⁵⁸

- Based on data from Oxford University²⁸
- Adapting to the different stages of the pandemic
- Generalizing from experiences across the world

Recommendations about two weeks in advance, e.g.

- May 2020: Focus on schools and workplaces (i.e. indoors)
- Sept 2020: Focus on gatherings, travel restrictions
- March 2021: Delta surge; India lockdown
- Dec 2021: Missed omicron surge; everywhere at once
- March 2022: Masking to avoid a second omicron surge



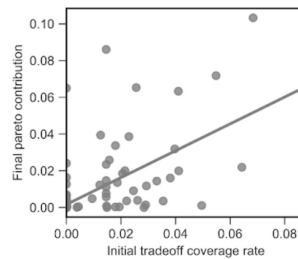
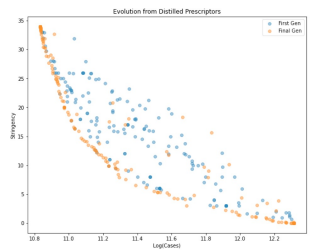
Interactive demo:

- <https://evolution.ml/demos/npidashboard>

30

Cognizant

Using Neuroevolution to Leverage Human Insight



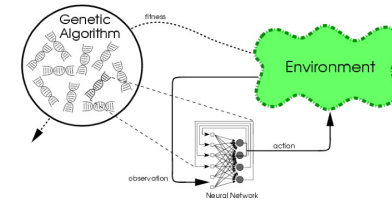
XPRIZE Pandemic Response Challenge 2021

- 169 expert-designed prescriptors
- Distill into neural networks and evolve further⁴⁸
- Improve upon expert-designed entries
- Improve upon evolution from scratch
- Can realize latent potential hidden in poor entries
- Technology to bring the community effort together

31

Cognizant

Part I Conclusion: Neuroevolution RL

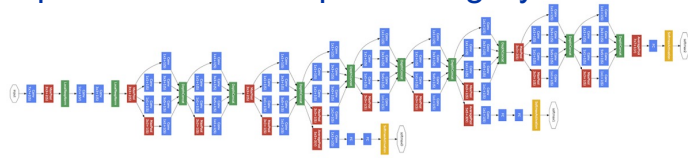


- A powerful way to train networks when gradients not available
 - E.g. recurrency in POMDP domains
- Many evolutionary techniques are a good match with NE
 - Partial solutions, CMA, Complexification, Indirect, Novelty, Constrained
- Can discover surprising, believable, effective solutions

32

Cognizant

II. Optimization of Deep Learning Systems



Szegedy et al. 2015⁹⁴

Deep learning systems operate at a much larger scale

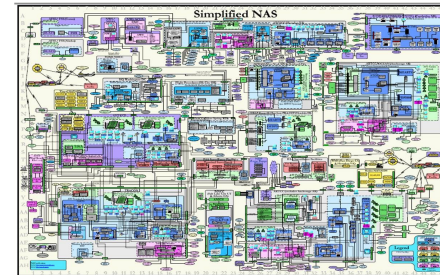
- 10^6 - 10^{12} parameters
- Overparameterized; trained by gradient descent

A new problem: How to configure such systems?

33

Cognizant

Configuring Complex Systems



A new general approach to engineering

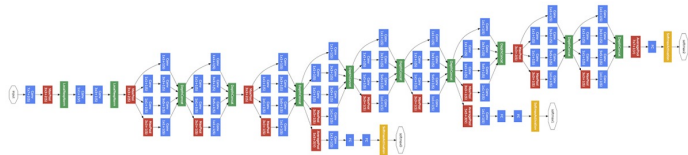
- ▶ Humans design just the framework
- ▶ Machines optimize the details

Programming by optimization³⁰

34

Cognizant

Configuring Deep Learning with Evolution



(A) Fundamental: Neural Architecture Search

- Optimizing structure and hyperparameters
- Takes advantage of exploration in EC

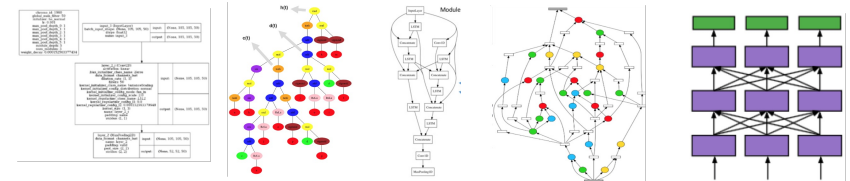
(B) Extended: Data and training

- Loss functions, activation functions, data augmentation, initialization, learning algorithm
- Takes advantage of flexibility of EC

35

Cognizant

Evolutionary NAS



Evolution is a natural fit:

- Population-based search covers the space
- Crossover between structures discovers principles

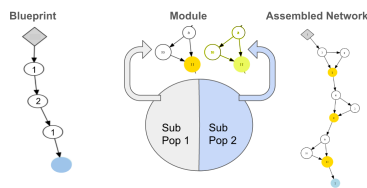
Moreover,

- Can build on Neuroevolution work since the 1990s: partial solutions, complexification, indirect encoding, novelty search
- Applies to continuous values; discrete choices; graph structures; combinations
- Can evolve hyperparameters; nodes; modules; topologies; multiple tasks

36

Cognizant

E.G. NAS with CoDeepNEAT



Evolution at three levels⁵⁹

- Module subpopulations optimize building blocks
- Blueprint population optimizes their combinations
- Hyperparameter evolution optimizes their instantiation

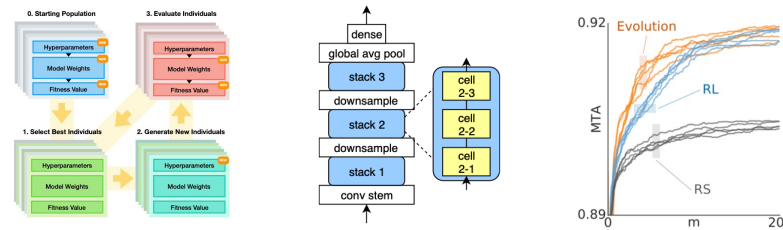
Fitness of the complete network drives evolution

- Candidates need to be evaluated through training
- Expensive; use partial training, surrogates...

37

Cognizant

Making NAS Evaluations Practical



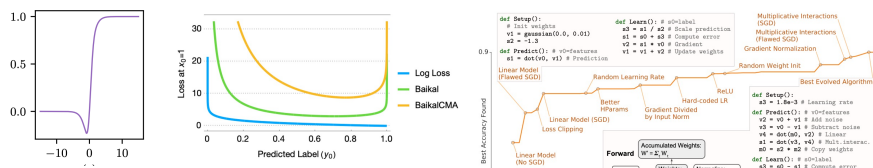
Population-based training (DeepMind, Cognizant)^{32,40}

- Continual training and evolution
- NAS benchmarks created to help evaluate (Google, Baidu, Freiburg)^{13,106,107}
- Collections of known architecture evaluations, surrogates
- Scaling and regularization (Google, Uber)^{73,92}
- State-of-the-art at the time in CIFAR-10, CIFAR-100, ImageNet
- Specialized crossover operators (Cognizant)⁶⁸

38

Cognizant

Optimizing Other Aspects of Deep Learning Design



Optimizing activation functions and loss functions (Cognizant)^{5,6,24,25,26,40}

- Regularization and refinement

Designing machine learning algorithms with GP (Google)^{44,74}

- Adapts to different task types
- Discovering new layer types

Coevolution of multiple aspects of network design?

39

Cognizant

Evolutionary AutoML

Current AutoML: Mostly hyperparameter optimization

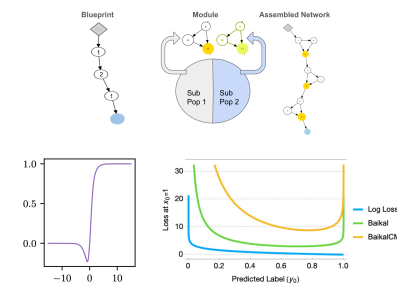
Future Evolutionary AutoML: Many design aspects

Performance

1. Improve state of the art
- With sufficient compute

Applicability

2. Improve over naïve baseline
- Service makes broadly available
3. Minimize network resources
- Train and run networks faster
4. Extend small datasets
- Multitasking with related datasets



40

Cognizant

1 & 2 in Evolving Age-Estimation Networks

Parameter	Possible Values	Type	Class
Algorithm	[adam, rmsprop]	Enum	Opt
Initial Learning Rate (LR)	[1e-5, 1e-3]	Float	Opt
Momentum	[0.7, 0.99]	Float	Opt
(Weight Decay) / LR [26]	[1e-7, 1e-3]	Float	Opt
Patience (Epochs)	[1, 20]	Int	Opt
SWA Epochs [21]	[1, 20]	Int	Opt
Rotation Range (Degrees)	[1, 60]	Int	Aug
Width Shift Range	[0.01, 0.3]	Float	Aug
Height Shift Range	[0.01, 0.3]	Float	Aug
Shear Range	[0.01, 0.3]	Float	Aug
Zoom Range	[0.01, 0.3]	Float	Aug
Horizontal Flip	[True, False]	Bool	Aug
Vertical Flip	[True, False]	Bool	Aug
Cutout Probability [7]	[0.01, 0.999]	Float	Aug
Cutout Max Proportion [7]	[0.05, 0.5]	Float	Aug
Pretrained Base Model	Keras App. [5]	Enum	Arch
Base Model Output Blocks	[B0, B1, B2, B3]	Subset	Arch
Loss function λ in Eq. 5	[0, 1]	Float	Arch



Estimate age from a facial image

Evolving multiple design aspects⁶⁰

- Learning, data augmentation hyperparameters
- Seeded architecture search
- Loss-function optimization: Combination of MAE and CE

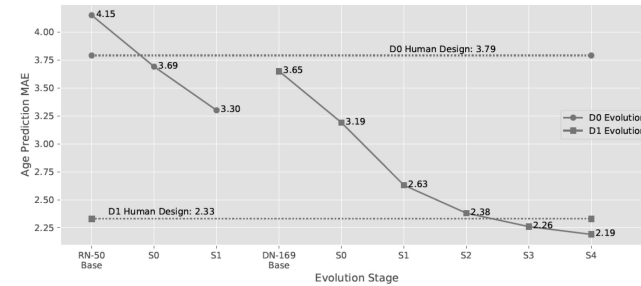
Also

- Population-based training
- Ensembling of evolved solutions

41

Cognizant

Age-Estimation Results



• D0 stages:
ResNet-50,
DenseNet-121

• D1 stages:
DenseNet-169,
DenseNet-201,
more epochs.
EfficientNet-B6,
ensembling

• Human optimization
of ResNet-50 (D0),
EfficientNet-B6 (D1)

Evolution improves significantly over SotA image models

- Fit the design to the task
 - Optimizes better than humans can
 - Many more parameters simultaneously
- Performance exceeds that of humans: 2.19 vs. 3-4 years

42

Cognizant

3. Minimize Network Resources

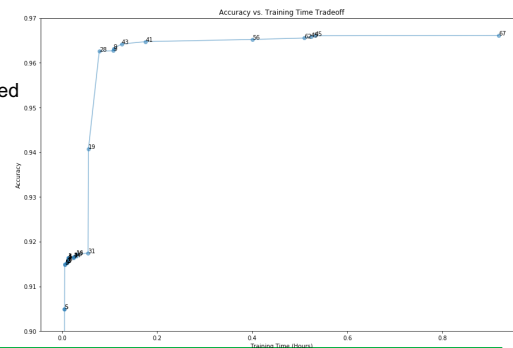
Evolution adds complexity only if needed

- Favors minimal solutions
- Over evolution a range of sizes explored
- Approximation of the Pareto front

Small networks found that perform well⁴¹

- Minimization with little cost
- E.g. 0.38% drop with 1/12th of the size

Could we optimize for size directly?



43

Cognizant

Multiobjective Minimization

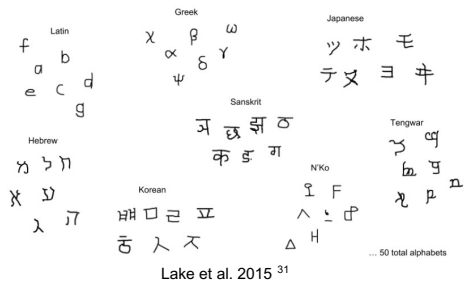


- Animation: Pareto front by generation for single-objective (green) vs. multi-objective (blue)
- Single-objective focuses on improving *largest networks*
- Multi-objective focuses on improving the *entire curve*
- Result: Multi-objective finds much smaller models for the majority of performance values³⁶
- Evolution can find solutions that fit design constraints

44

Cognizant

4. Extend Small Datasets



Recognize handwritten characters in a given alphabet

- Not enough samples to learn well
- A common problem in deep learning

Could we learn from multiple alphabets at once?

- More generalizable embeddings ^{42,52,53}
- Can learn each task better

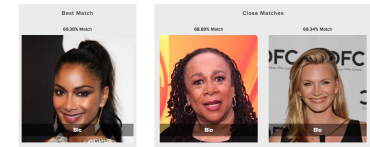
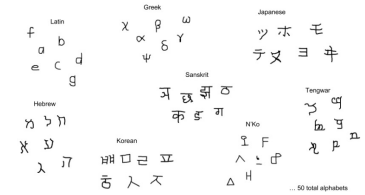
Evolve architecture to combine multiple tasks

- Network architecture can have a large effect
- A good domain for NAS

Multitasking Benchmarks

State-of-the-art in two ML benchmarks:

- Omniglot multialphabet character recognition ⁴²
 - Improved state-of-the-art 31%
 - Demo: evolution.ml/demos/omnidraw
- CelebA multiattribute face classification ⁵¹
 - Improved state-of-the-art 0.75%
 - Demo: evolution.ml/demos/celebmatch

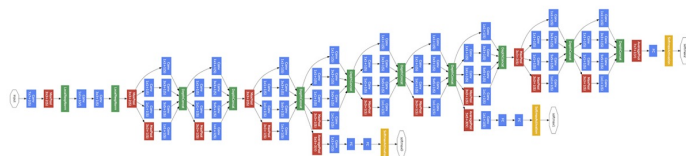


Improves learning in each task

- Even when little data available

Extend small datasets with multiple tasks

Part II Conclusion: Optimizing Deep Learning Designs



- Deep learning designs are too complex for humans to optimize
- Evolutionary techniques are a good fit
 - Large, structured space; continuous, discrete, and structured
- Can be applied to multiple aspects of the design
 - How to utilize their interactions?
 - How to evaluate candidates efficiently?

III. Future: Neuroevolution through Large Language Models

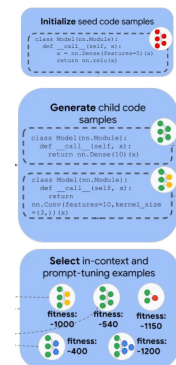
LM prompt (Parents)	<pre>11101111 11101111 10100111</pre>	$x^2 + 2.1 * x$ $\sin x^2 + 7$ $3 * \sin x + 6.6$	the moon is bad the moon is boring the moon is cold
LM output (Children)	<pre>11111111 11111111 10110111</pre>	$x^2 \sin x + 6$ $\cos x^2 + 2.1 * x$	the moon is zen the sky has a moon

Better evolution through LLMs?

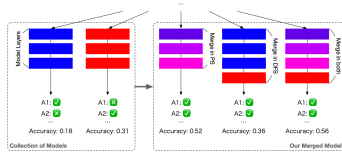
- Evolution through large models (ELM) ³⁵
- Language model crossover (LMX) ⁵⁴
- Level generation for Mario (MarioGPT) ⁹³

E.g. Evolutionary prompting for NAS (EvoPrompting) ⁹

- Existing architectures as prompts; generate new
- Tune the prompts based on performance

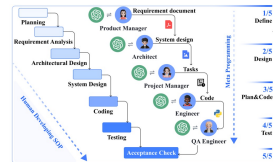
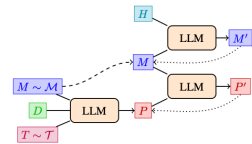


Future: Neuroevolution of Large Language Models



Better LLMs through evolution?

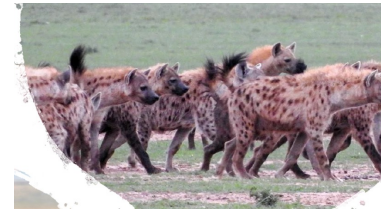
- Model merging: combine multiple fine-tuned LLMs to one
 - E.g. Japanese LLM with Math²
- Evolving prompts: Promptbreeder
 - Evolving mutation prompts to improve task prompts¹⁴
- Evolving multi-LLM interactions
 - E.g. roles for collaborative problem solving²⁹



49

Cognizant

IV. Emergence of Intelligence



Evolved Virtual Creatures

- Neuroevolution of intelligent behavior
- Useful e.g. for video games

Can such experiments lead to insights in biology?

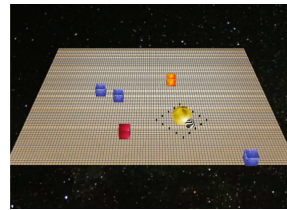
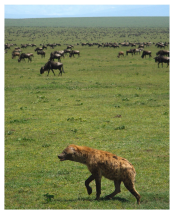
Collaboration with Kay Holekamp's lab (MSU)

- Studying hyenas in Masai Mara since 1982

50

Cognizant

Evaluating Biological Hypotheses



In simulation^{69,70,71,72}

- Manipulate constraints, observe outcomes, analyze trajectory of discovery

Computational support for hypotheses

- Reward structure: Emergence of cooperation in hunting
- Lethality of conflicts: Emergence of a hierarchical society
- Signaling in mate selection vs. hunting: Origins of communication

51

Cognizant

Example: Evolution of Intelligent Coordinated Behavior

Stealing a kill from lions

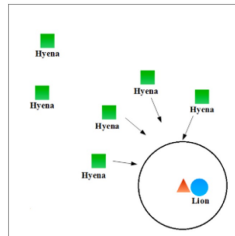
- Succeeds in an otherwise impossible task (sometimes)
- More sophisticated than other hyena behaviors
- Highly rewarding compared to normal hunting
- Largely genetically determined
- A breakthrough in evolution of intelligence?



52

Cognizant

Simulation Setup

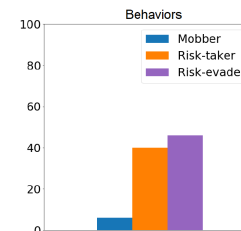


- Lion at a kill, with an interaction circle around it⁶⁹
 Ten hyenas chosen and placed randomly in the field
 If 4 or more hyenas enter the circle simultaneously, they get the kill
- Otherwise they die
- Does mobbing behavior evolve?
- What are the stepping stones for it?

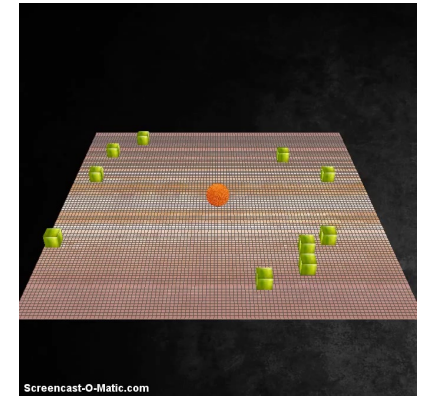
53

Cognizant

Initial Behaviors



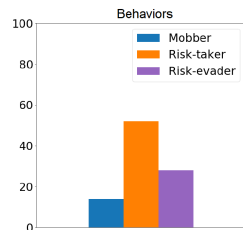
- Risk evasion is common
- Never reach the circle; Medium fitness
- Risk taking is common
- Charge the circle; Frequent low fitness
 - Occasional high fitness by accident



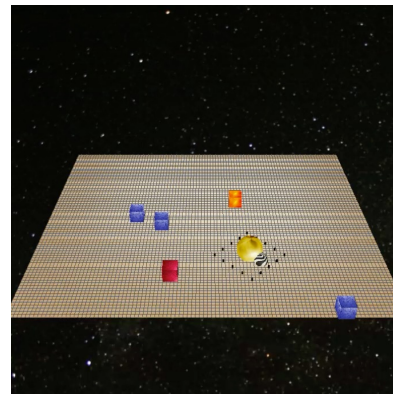
54

Cognizant

Early Behaviors



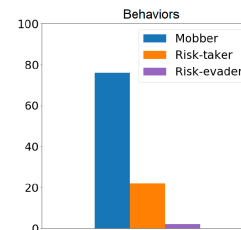
- Risk taking grows
- As long as it is successful often enough
- Risk evasion also persists
- Evasion at the circle starts to emerge
- Is mostly detrimental, but an important stepping stone



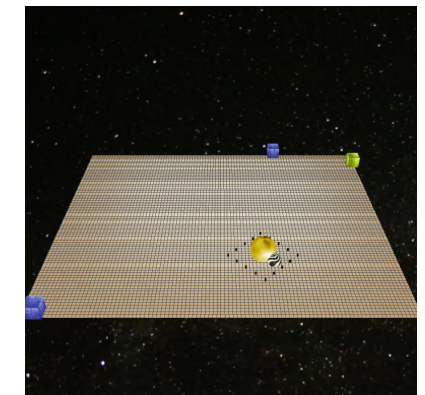
55

Cognizant

Later Behaviors



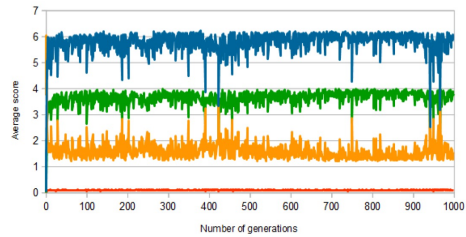
- Mobbing emerges
- Not just coincidence of risk takers
 - Hyenas wait until there's enough of them
- Risk-evaders evolve into latecomers
- Simple risk-taking and risk-evasion still exist



56

Cognizant

These Behaviors Persist in Prolonged Evolution



Risk taking and risk evasion never go away completely

- They serve a role in maintaining the mobbing behavior
- If mobbing starts to get lost, it can be reintroduced

57

Cognizant

Insight into Real-life Behaviors



These behaviors are observed in real-life hyenas as well³⁸

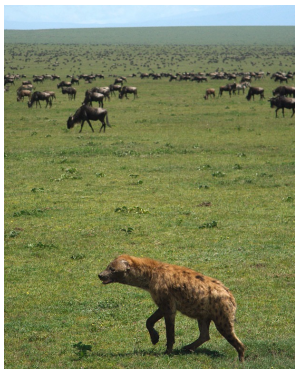
A computational explanation of why they are there:

- Stepping stones in discovery
- Safeguards in maintaining

58

Cognizant

Constructing Intelligent Systems

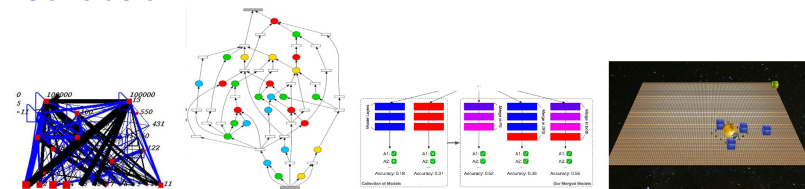


- Believable, complex behavior in embedded environments
 - Open-ended "arms race"⁷²
- Similar to self-play e.g. in AlphaGo Zero
 - Complexity beyond human ability to design it
- If we can build open-ended environments, we should be able to build more complex solutions
 - Co-evolve environments and behaviors? (e.g. POET,¹⁰⁰ EUREQA⁸⁰)
 - Evolution of memory, learning, language
- Challenge: Establish major transitions⁵⁷

59

Cognizant

Conclusion



Neuroevolution is a powerful approach for POMDPs

- Discovers surprising, believable, effective behavior
- Games, robotics, control, alife, decision-making...

Makes complex DL architectures possible

- Structure, components, hyperparameters, etc. fit to the task
- Automatic design of learning machines

A possible future focus: Emergence of intelligence

- Body/brain co-evolution; Competitive co-evolution
- Evolution of memory, language, learning; AGI

60

Cognizant

Further Material

- Neuroevolution sessions at GECCO!
- www.cs.utexas.edu/users/risto/talks/enn-tutorial
 - Slides and references
 - Demos
 - A step-by-step neuroevolution exercise (evolving behavior in the NERO game)
- nn.cs.utexas.edu/?miikkulainen:encyclopedia20-ne
 - A short summary of neuroevolution
- www.nature.com/articles/s42256-018-0006-z
 - Nature Machine Intelligence survey on neuroevolution
- Risi, Ha, Tang, and Miikkulainen (2024): [Neuroevolution](#). New York: Springer
 - Forthcoming textbook/monograph in Fall 2024
 - Extensive online exercises

61

Cognizant

References I

- [1] A. Agogino, K. Tumer, and R. Miikkulainen, Efficient credit assignment through evaluation function decomposition, in: *Proceedings of the Genetic and Evolutionary Computation Conference* (2005).
- [2] T. Akiba, M. Shing, Y. Tang, Q. Sun, and D. Ha, Evolutionary optimization of model merging recipes, *arXiv:2403.13187* (2024).
- [3] P. J. Angeline, G. M. Saunders, and J. B. Pollack, An evolutionary algorithm that constructs recurrent neural networks, *IEEE Transactions on Neural Networks*, 5:54–65 (1994).
- [4] R. K. Belew, Evolution, learning and culture: Computational metaphors for adaptive algorithms, *Complex Systems*, 4:11–49 (1990).
- [5] G. Bingham, W. Macke, and R. Miikkulainen, Evolutionary optimization of deep learning activation functions, in: *Proceedings of the Genetic and Evolutionary Computation Conference*, 289–296 (2020).
- [6] G. Bingham and R. Miikkulainen, Discovering parametric activation functions, *Neural Networks*, 148:48–65 (2022).
- [7] B. D. Bryant and R. Miikkulainen, Acquiring visibly intelligent behavior with example-guided neuroevolution, in: *Proceedings of the Twenty-Second National Conference on Artificial Intelligence*, AAAI Press, Menlo Park, CA (2007).
- [8] D. J. Chalmers, The evolution of learning: An experiment in genetic connectionism, in: Touretzky et al. ⁹⁶, 81–90.
- [9] A. Chen, D. M. Dohan, and D. R. So, EvoPrompting: Language models for code-level neural architecture search, *arXiv:2302.14838* (2023).
- [10] D. B. D'Ambrosio and K. O. Stanley, A novel generative encoding for exploiting neural network sensor and output geometry, in: *Proceedings of the 9th Annual Conference on Genetic and Evolutionary Computation (GECCO '07)*, 974–981, ACM, New York, NY, USA (2007).
- [11] D. B. D'Ambrosio and K. O. Stanley, Generative encoding for multiagent learning, in: *Proceedings of the Genetic and Evolutionary Computation Conference* (2008).
- [12] K. Deb and C. Myburgh, A population-based fast algorithm for a billion-dimensional resource allocation problem with integer variables, *European Journal of Operational Research*, 261:460–474 (2017).

62/61

References II

- [13] X. Dong and Y. Yang, NAS-Bench-201: Extending the scope of reproducible neural architecture search, in: *8th International Conference on Learning Representations (ICLR 2020)* (2020).
- [14] C. Fernando, D. Banarse, H. Michalewski, S. Osindero, and T. Rocktäschel, Promptbreeder: Self-referential self-improvement via prompt evolution, *arXiv:2309.16797* (2023).
- [15] D. Floreano, P. Dür, and C. Mattiussi, Neuroevolution: From architectures to learning, *Evolutionary Intelligence*, 1:47–62 (2008).
- [16] D. Floreano and J. Urzelai, Evolutionary robots with on-line self-organization and behavioral fitness, *Neural Networks*, 13:431–4434 (2000).
- [17] M. Fontaine and S. Nikolaidis, Differentiable quality diversity, in: *Advances in Neural Information Processing Systems*, M. Ranzato, A. Beygelzimer, Y. Dauphin, P. Liang, and J. W. Vaughan, eds., volume 34, 10040–10052, Curran Associates, Inc. (2021).
- [18] O. Francon, S. Gonzalez, B. Hodjat, E. Meyerson, R. Miikkulainen, X. Qiu, and H. Shahrzad, Effective reinforcement learning through evolutionary surrogate-assisted prescription, in: *Proceedings of the Genetic and Evolutionary Computation Conference (GECCO-2020)*, 814–822 (2020).
- [19] B. Fullmer and R. Miikkulainen, Using marker-based genetic encoding of neural networks to evolve finite-state behaviour, in: *Toward a Practice of Autonomous Systems: Proceedings of the First European Conference on Artificial Life*, F. J. Varela and P. Bourguine, eds., 255–262, MIT Press, Cambridge, MA (1992).
- [20] J. J. Gauci and K. O. Stanley, A case study on the critical role of geometric regularity in machine learning, in: *Proceedings of the Twenty-Third National Conference on Artificial Intelligence*, AAAI Press, Menlo Park, CA (2008).
- [21] F. Gomez, *Robust Non-Linear Control Through Neuroevolution*, Ph.D. thesis, Department of Computer Sciences, The University of Texas at Austin (2003).
- [22] F. Gomez and R. Miikkulainen, Incremental evolution of complex general behavior, *Adaptive Behavior*, 5:317–342 (1997).
- [23] F. Gomez, J. Schmidhuber, and R. Miikkulainen, Accelerated neural evolution through cooperatively coevolved synapses, *Journal of Machine Learning Research*, 9:937–965 (2008).

63/61

References III

- [24] S. Gonzalez, M. Kant, and R. Miikkulainen, Evolving gan formulations for higher quality image synthesis, in: *Artificial Intelligence in the Age of Neural Networks and Brain Computing (second edition)*, R. Kozma, C. Alippi, Y. Choe, and F. C. Morabito, eds., Elsevier, New York (2023).
- [25] S. Gonzalez and R. Miikkulainen, Improved training speed, accuracy, and data utilization through loss function optimization, in: *Proceedings of the 2020 IEEE Congress on Evolutionary Computation (CEC)*, 1–8 (2020).
- [26] S. Gonzalez and R. Miikkulainen, Optimizing loss functions through multivariate Taylor polynomial parameterization, in: *Proceedings of the Genetic and Evolutionary Computation Conference*, 305–313 (2021).
- [27] F. Gruau and D. Whitley, Adding learning to the cellular development of neural networks: Evolution and the Baldwin effect, *Evolutionary Computation*, 1:213–233 (1993).
- [28] T. Hale, S. Webster, A. Petherick, T. Phillips, and B. Kira, Oxford COVID-19 government response tracker, Blavatnik School of Government (2020). <https://www.bsg.ox.ac.uk/research/research-projects/coronavirus-government-response-tracker>, accessed 5/26/2020.
- [29] S. Hong, M. Zhuge, J. Chen, X. Zheng, Y. Cheng, C. Zhang, J. Wang, Z. Wang, S. K. S. Yau, Z. Lin, L. Zhou, C. Ran, L. Xiao, C. Wu, and J. Schmidhuber, Metagpt: Meta programming for a multi-agent collaborative framework, *arXiv:2308.00352* (2023).
- [30] H. Hoos, Programming by optimization, *Communications of the ACM*, 55:70–80 (2012).
- [31] C. Igel, Neuroevolution for reinforcement learning using evolution strategies, in: *Proceedings of the 2003 Congress on Evolutionary Computation*, R. Sarker, R. Reynolds, H. Abbass, K. C. Tan, B. McKay, D. Essam, and T. Gedeon, eds., 2588–2595, IEEE Press, Piscataway, NJ (2003).
- [32] M. Jaderberg, V. Dalibard, S. Osindero, W. M. Czarnecki, J. Donahue, A. Razavi, O. Vinyals, T. Green, I. Dunning, K. Simonyan, C. Fernando, and K. Kavukcuoglu, Population based training of neural networks, *arXiv:1711.09846* (2017).
- [33] A. Jain, A. Subramoney, and R. Miikkulainen, Task decomposition with neuroevolution in extended predator-prey domain, in: *Proceedings of Thirteenth International Conference on the Synthesis and Simulation of Living Systems*, East Lansing, MI, USA (2012).

64/61

References IV

- [34] B. M. Lake, R. Salakhutdinov, and J. B. Tenenbaum, Human-level concept learning through probabilistic program induction, *Science*, 350:1332–1338 (2015).
- [35] J. Lehman, J. Chen, J. Clune, and K. O. Stanley, ES is more than just a traditional finite-difference approximator, *arXiv:1712.06568* (2017).
- [36] J. Lehman, J. Gordon, S. Jain, K. Ndousse, C. Yeh, and K. O. Stanley, Evolution through large models, *arXiv:2207.04857* (2022).
- [37] J. Lehman and K. O. Stanley, Abandoning objectives: Evolution through the search for novelty alone, *Evolutionary Computation*, 19:189–223 (2010).
- [38] K. D. Lehmann, T. M. Montgomery, S. M. MacLachlan, J. M. Parker, O. S. Spagnuolo, K. J. VandeWetering, P. S. Bills, and K. E. Holekamp, Lions, hyenas and mobs (oh my!), *Current Zoology*, 63:313–322 (2016).
- [39] X. Li and R. Miikkulainen, Evolving adaptive poker players for effective opponent exploitation, in: *AAAI-17 Workshop on Computer Poker and Imperfect Information Games*, San Francisco, CA, USA (2017).
- [40] J. Liang, S. Gonzalez, H. Shahrzad, and R. Miikkulainen, Regularized evolutionary population-based training, in: *Proceedings of the Genetic and Evolutionary Computation Conference*, 323–331 (2021).
- [41] J. Liang, E. Meyerson, B. Hodjat, D. Fink, K. Mutch, and R. Miikkulainen, Evolutionary neural AutoML for deep learning, in: *Proceedings of the Genetic and Evolutionary Computation Conference (GECCO-2019)*, 401–409 (2019).
- [42] J. Liang, E. Meyerson, and R. Miikkulainen, Evolutionary architecture search for deep multitask networks, in: *Proceedings of the Genetic and Evolutionary Computation Conference*, 466–473 (2018).
- [43] J. Z. Liang and R. Miikkulainen, Evolutionary bilevel optimization for complex control tasks, in: *Proceedings of the Genetic and Evolutionary Computation Conference (GECCO 2015)*, 871–878 (July 2015).
- [44] H. Liu, A. Brock, K. Simonyan, and Q. V. Le, Evolving normalization-activation layers, *arXiv:2004.02967* (2020).
- [45] Y. Liu, X. Yao, and T. Higuchi, Evolutionary ensembles with negative correlation learning, *IEEE Transactions on Evolutionary Computation*, 4:380–387 (2000).

65/61

References V

- [46] A. Lockett and R. Miikkulainen, Neuroannealing: Martingale-driven learning for neural network, in: *Proceedings of the Genetic and Evolutionary Computation Conference* (2013).
- [47] P. McQuesten, *Cultural Enhancement of Neuroevolution*, Ph.D. thesis, Department of Computer Sciences, The University of Texas at Austin, Austin, TX (2002). Technical Report AI-02-295.
- [48] E. Meyerson, O. Francon, D. Sargent, B. Hodjat, and R. Miikkulainen, Unlocking the potential of global human expertise with AI (2023). In preparation.
- [49] E. Meyerson, J. Lehman, and R. Miikkulainen, Learning behavior characterizations for novelty search, in: *Proceedings of the Genetic and Evolutionary Computation Conference (GECCO 2016)*, ACM, New York, NY (2016).
- [50] E. Meyerson and R. Miikkulainen, Discovering evolutionary stepping stones through behavior domination, in: *Proceedings of the Genetic and Evolutionary Computation Conference (GECCO 2017)*, 139–146, Berlin, Germany (2017).
- [51] E. Meyerson and R. Miikkulainen, Pseudo-task augmentation: From deep multitask learning to intratask sharing—and back, in: *Proceedings of the 35th International Conference on Machine Learning*, 739–748 (2018).
- [52] E. Meyerson and R. Miikkulainen, Modular universal reparameterization: Deep multi-task learning across diverse domains, in: *Advances in Neural Information Processing Systems 32*, H. Wallach, H. Larochelle, A. Beygelzimer, F. d Alche-Buc, E. Fox, and R. Garnett, eds. (2019).
- [53] E. Meyerson and R. Miikkulainen, The traveling observer model: Multi-task learning through spatial variable embeddings, in: *International Conference on Learning Representations* (2021).
- [54] E. Meyerson, M. J. Nelson, H. Bradley, A. Moradi, A. K. Hoover, and J. Lehman, Language model crossover: Variation through few-shot prompting, *arXiv:2302.12170* (2023).
- [55] E. Meyerson, X. Qiu, and R. Miikkulainen, Simple genetic operators are universal approximators of probability distributions (and other advantages of expressive encodings), in: *Proceedings of the Genetic and Evolutionary Computation Conference*, 739–748 (2022).

66/61

References VI

- [56] R. Miikkulainen, Creative AI through evolutionary computation, in: *Evolution in Action: Past, Present and Future*, W. Banzhaf, B. Cheng, K. Deb, K. Holekamp, R. E. Lenski, C. Ofria, R. Pennock, B. Punch, and D. Whittaker, eds., Springer, New York (2020).
- [57] R. Miikkulainen and S. Forrest, A biological perspective on evolutionary computation, *Nature Machine Intelligence*, 3:9–15 (2021).
- [58] R. Miikkulainen, O. Francon, E. Meyerson, X. Qiu, D. Sargent, E. Canzani, and B. Hodjat, From prediction to prescription: Evolutionary optimization of non-pharmaceutical interventions in the COVID-19 pandemic, *IEEE Transactions on Evolutionary Computation*, 25:386–401 (2021).
- [59] R. Miikkulainen, J. Liang, E. Meyerson, A. Rawal, D. Fink, O. Francon, B. Raju, H. Shahrzad, A. Navruzyan, N. Duffy, and B. Hodjat, Evolving deep neural networks, in: *Artificial Intelligence in the Age of Neural Networks and Brain Computing (second edition)*, R. Kozma, C. Alippi, Y. Choe, and F. Morabito, eds., 269–287, Elsevier, New York (2023).
- [60] R. Miikkulainen, E. Meyerson, X. Qiu, U. Sinha, R. Kumar, K. Hofmann, Y. M. Yan, M. Ye, J. Yang, D. Caiazza, and S. M. Brown, Evaluating medical aesthetics treatments through evolved age-estimation models, in: *Proceedings of the Genetic and Evolutionary Computation Conference*, 1009–1017 (2021).
- [61] E. Mjolsness, D. H. Sharp, and B. K. Alpert, Scaling, machine learning, and genetic neural nets, *Advances in Applied Mathematics*, 10:137–163 (1989).
- [62] D. J. Montana and L. Davis, Training feedforward neural networks using genetic algorithms, in: *Proceedings of the 11th International Joint Conference on Artificial Intelligence*, 762–767, San Francisco: Morgan Kaufmann (1989).
- [63] D. E. Moriarty and R. Miikkulainen, Forming neural networks through efficient and adaptive co-evolution, *Evolutionary Computation*, 5:373–399 (1997).
- [64] S. Nolfi and D. Parisi, Good teaching inputs do not correspond to desired responses in ecological neural networks, *Neural Processing Letters*, 1(2):1–4 (1994).
- [65] D. Pardoe, M. Ryoo, and R. Miikkulainen, Evolving neural network ensembles for control problems, in: *Proceedings of the Genetic and Evolutionary Computation Conference* (2005).

67/61

References VII

- [66] M. A. Potter and K. A. D. Jong, Cooperative coevolution: An architecture for evolving coadapted subcomponents, *Evolutionary Computation*, 8:1–29 (2000).
- [67] J. K. Pugh, L. B. Soros, and K. O. Stanley, Quality diversity: A new frontier for evolutionary computation, *Frontiers in Robotics and AI*, 3 (2016).
- [68] X. Qiu and R. Miikkulainen, Shortest edit path crossover: A theory-driven solution to the permutation problem in evolutionary neural architecture search, in: *Proceedings of the International Conference on Machine Learning (ICML-2023)* (2023).
- [69] P. Rajagopalan, K. E. Holekamp, and R. Miikkulainen, Evolution of complex coordinated behavior, in: *2020 IEEE Congress on Evolutionary Computation (CEC)* (2020).
- [70] P. Rajagopalan, A. Rawal, R. Miikkulainen, M. A. Wiseman, and K. E. Holekamp, The role of reward structure, coordination mechanism and net return in the evolution of cooperation, in: *Proceedings of the IEEE Conference on Computational Intelligence and Games (CIG 2011)*, Seoul, South Korea (2011).
- [71] A. Rawal, J. Boughman, and R. Miikkulainen, Evolution of communication in mate selection, in: *Proceedings of The Fourteenth International Conference on the Synthesis and Simulation of Living Systems (ALIFE 14)*, New York, USA (2014).
- [72] A. Rawal, P. Rajagopalan, and R. Miikkulainen, Constructing competitive and cooperative agent behavior using coevolution, in: *IEEE Conference on Computational Intelligence and Games (CIG 2010)*, Copenhagen, Denmark (2010).
- [73] E. Real, A. Aggarwal, Y. Huang, and Q. V. Le, Regularized evolution for image classifier architecture search, in: *Proceedings of the AAAI Conference on Artificial Intelligence*, 4780–4789 (2019).
- [74] E. Real, C. Liang, D. So, and Q. V. Le, AutoML-Zero: Evolving machine learning algorithms from scratch, in: *Proceedings of the 37th International Conference on Machine Learning*, H. D. III and A. Singh, eds., 8007–8019 (2020).
- [75] J. Reisinger and R. Miikkulainen, Acquiring evolvability through adaptive representations, in: *Proceedings of the Genetic and Evolutionary Computation Conference*, 1045–1052 (2007).
- [76] J. Reisinger, K. O. Stanley, and R. Miikkulainen, Evolving reusable neural modules, in: *Proceedings of the Genetic and Evolutionary Computation Conference* (2004).

68/61

References VIII

- [77] T. P. Runarsson and M. T. Jonsson, Evolution and design of distributed learning rules, in: *Proceedings of The First IEEE Symposium on Combinations of Evolutionary Computation and Neural Networks*, 59–63, IEEE, Piscataway, NJ (2000).
- [78] T. Salimans, J. Ho, X. Chen, and I. Sutskever, Evolution strategies as a scalable alternative to reinforcement learning, *arXiv:1703.03864* (2017).
- [79] J. D. Schaffer, D. Whitley, and L. J. Eshelman, Combinations of genetic algorithms and neural networks: A survey of the state of the art, in: *Proceedings of the International Workshop on Combinations of Genetic Algorithms and Neural Networks*, D. Whitley and J. Schaffer, eds., 1–37, IEEE Computer Society Press, Los Alamitos, CA (1992).
- [80] M. Schmidt and H. Lipson, Distilling free-form natural laws from experimental data, *Science*, 324:81–85 (2009).
- [81] J. Schrum, I. Karpov, and R. Miikkulainen, Humanlike combat behavior via multiobjective neuroevolution, in: *Believable Bots*, P. Hingston, ed., Springer, New York (2012).
- [82] J. Schrum and R. Miikkulainen, Evolving agent behavior in multiobjective domains using fitness-based shaping, in: *Proceedings of the Genetic and Evolutionary Computation Conference* (2010).
- [83] J. Secretan, N. Beato, D. B. D'Ambrosio, A. Rodriguez, A. Campbell, J. T. Folsom-Kovarik, and K. O. Stanley, Picbreeder: A case study in collaborative evolutionary exploration of design space, *Evolutionary Computation*, 19:345–371 (2011).
- [84] H. Shahrzad, B. Hodjat, C. Dolle, A. Denissov, S. Lau, D. Goodhew, J. Dyer, and R. Miikkulainen, Enhanced optimization with composite objectives and novelty pulsation, in: *Genetic Programming Theory and Practice XVII*, W. Banzhaf, E. Goodman, L. Sheneman, L. Trujillo, and B. Worzel, eds., 275–293, Springer, New York (2020).
- [85] A. A. Siddiqi and S. M. Lucas, A comparison of matrix rewriting versus direct encoding for evolving neural networks, in: *Proceedings of IEEE International Conference on Evolutionary Computation*, 392–397, IEEE, Piscataway, NJ (1998).
- [86] K. O. Stanley, *Efficient Evolution of Neural Networks Through Complexification*, Ph.D. thesis, Department of Computer Sciences, The University of Texas at Austin, Austin, TX (2003).

69/61

References IX

- [87] K. O. Stanley, B. D. Bryant, and R. Miikkulainen, Evolving adaptive neural networks with and without adaptive synapses, in: *Proceedings of the 2003 Congress on Evolutionary Computation*, IEEE, Piscataway, NJ (2003).
- [88] K. O. Stanley and J. Lehman, *Why Greatness Cannot Be Planned: The Myth of the Objective*, Springer, Berlin (2015).
- [89] K. O. Stanley and R. Miikkulainen, Evolving Neural Networks Through Augmenting Topologies, *Evolutionary Computation*, 10:99–127 (2002).
- [90] K. O. Stanley and R. Miikkulainen, A taxonomy for artificial embryogeny, *Artificial Life*, 9(2):93–130 (2003).
- [91] D. G. Stork, S. Walker, M. Burns, and B. Jackson, Preadaptation in neural circuits, in: *International Joint Conference on Neural Networks* (Washington, DC), 202–205, IEEE, Piscataway, NJ (1990).
- [92] F. P. Such, V. Madhavan, E. Conti, J. Lehman, K. O. Stanley, and J. Clune, Deep neuroevolution: Genetic algorithms are a competitive alternative for training deep neural networks for reinforcement learning, *arXiv:1712.06567* (2017).
- [93] S. Sudhakaran, M. Gonzalez-Duque, C. Glanois, M. Freiberger, E. Najarro, and S. Risi, Mariogpt: Open-ended text2level generation through large language models, *arXiv:2302.05981* (2023).
- [94] C. Szegedy, W. Liu, Y. Jia, P. Sermanet, S. Reed, D. Anguelov, D. Erhan, V. Vanhoucke, and A. Rabinovich, Going deeper with convolutions, in: *2015 IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 1–9 (2015).
- [95] W. Tansley, E. Feasley, and R. Miikkulainen, Accelerating evolution via egalitarian social learning, in: *Proceedings of the 14th Annual Genetic and Evolutionary Computation Conference (GECCO 2012)* (2012).
- [96] D. S. Touretzky, J. L. Elman, T. J. Sejnowski, and G. E. Hinton, eds., *Proceedings of the 1990 Connectionist Models Summer School*, San Francisco: Morgan Kaufmann (1990).
- [97] C. C. Tutum, S. Abdulquddos, and R. Miikkulainen, Generalization of agent behavior through explicit representation of context, in: *Proceedings of the 3rd IEEE Conference on Games (COG-2021)* (2021).
- [98] J. Urzelai, D. Floreano, M. Dorigo, and M. Colombetti, Incremental robot shaping, *Connection Science*, 10:341–360 (1998).

70/61

References X

- [99] V. K. Valsalam and R. Miikkulainen, Evolving symmetric and modular neural networks for distributed control, in: *Proceedings of the Genetic and Evolutionary Computation Conference (GECCO) 2009*, 731–738, ACM, New York, NY, USA (2009).
- [100] R. Wang, J. Lehman, J. Clune, and K. O. Stanley, POET: open-ended coevolution of environments and their optimized solutions, in: *Proceedings of the Genetic and Evolutionary Computation Conference, GECCO 2019, Prague, Czech Republic, July 13-17, 2019*, 142–151 (2019).
- [101] S. Whiteson, N. Kohl, R. Miikkulainen, and P. Stone, Evolving keepaway soccer players through task decomposition, *Machine Learning*, 59:5–30 (2005).
- [102] S. Whiteson and P. Stone, Evolutionary function approximation for reinforcement learning, *Journal of Machine Learning Research*, 7:877–917 (2006).
- [103] D. Whitley, S. Dominic, R. Das, and C. W. Anderson, Genetic reinforcement learning for neurocontrol problems, *Machine Learning*, 13:259–284 (1993).
- [104] A. P. Wieland, Evolving controls for unstable systems, in: Touretzky et al. ⁹⁶, 91–102.
- [105] X. Yao, Evolving artificial neural networks, *Proceedings of the IEEE*, 87(9):1423–1447 (1999).
- [106] C. Ying, A. Klein, E. Christiansen, E. Real, K. Murphy, and F. Hutter, NAS-Bench-101: Towards reproducible neural architecture search, in: *Proceedings of the 36th International Conference on Machine Learning*, volume 97, 7105–7114 (2019).
- [107] A. Zela, J. N. Siems, L. Zimmer, J. Lukasik, M. Keuper, and F. Hutter, Surrogate NAS benchmarks: Going beyond the limited search spaces of tabular NAS benchmarks, in: *International Conference on Learning Representations (ICLR 2022)* (2022).

71/61