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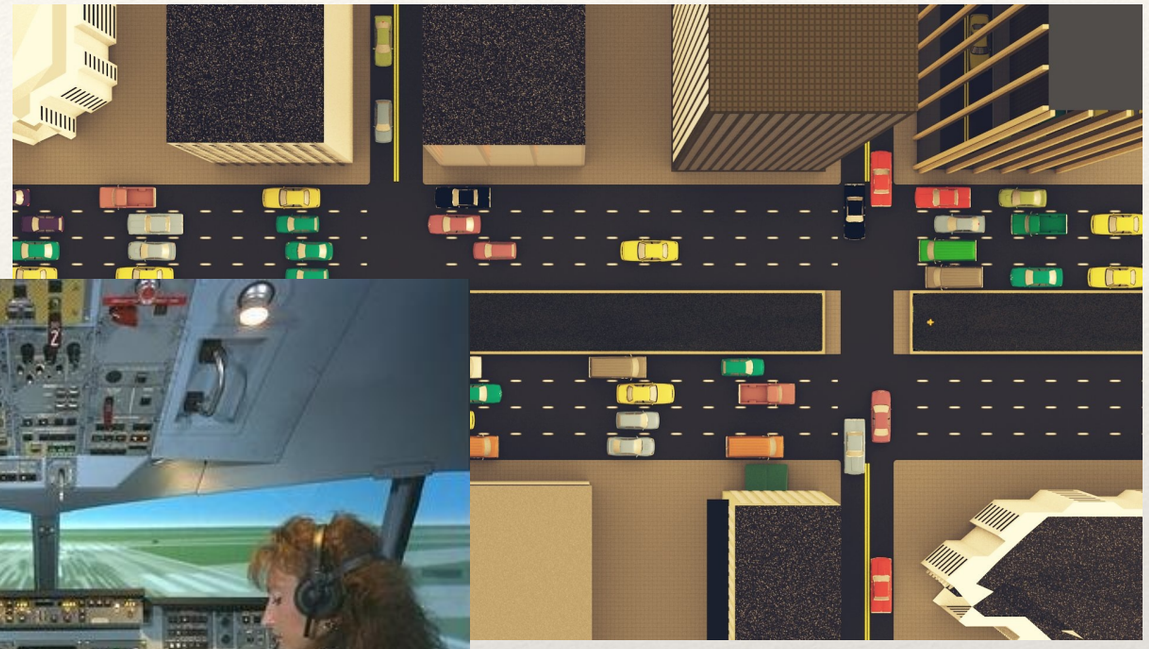
# Simulation and Particle Systems

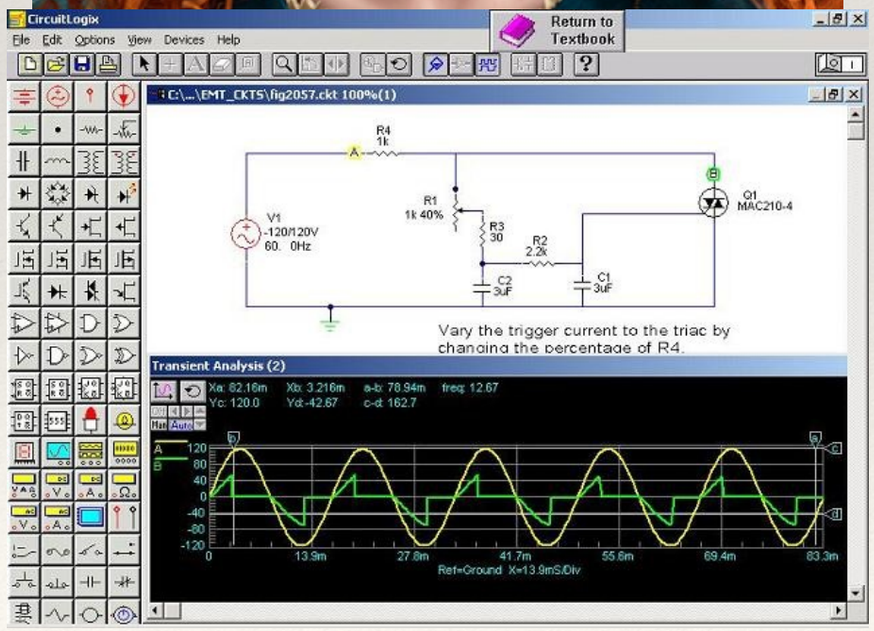
Elements of Graphics
CS324e

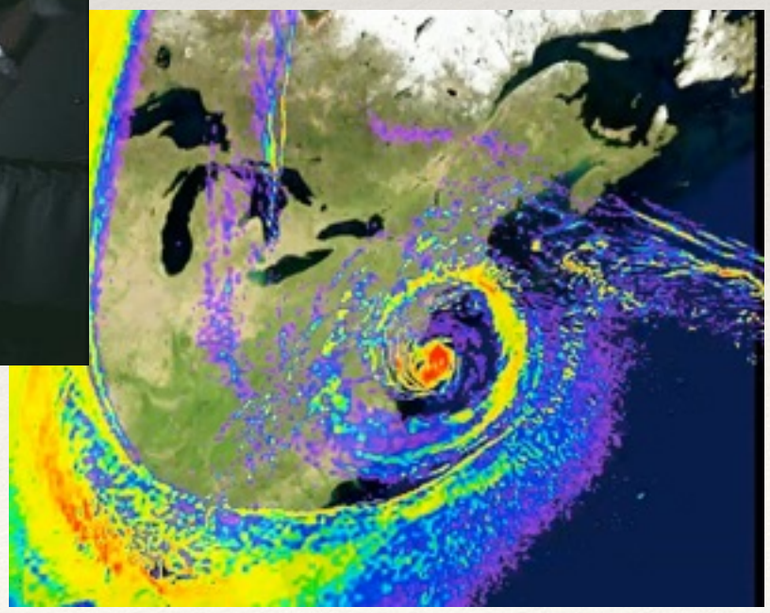
# What is Simulation?

- The capture of behaviors based on rules over time
- Physical simulation
  - Models natural phenomena
    - Physics, chemistry, astronomy, climatology etc
- Operational simulation
  - Models processes and human interactions
  - Economics, manufacturing, engineering etc

# Uses for Simulation



And many, many more…

# Physical Simulation

- Classical mechanics is the study of forces on bodies
- Well understood physical laws
- Velocity is the rate of change in position (m/s)
- Acceleration is the rate of change in velocity ($m/s^2$)

# Vectors

- Velocity and acceleration can both be represented as vectors
- Vectors have:
  - Direction
  - Magnitude


(Mathinsight)

- Positive and negative values in the x and y axes determine the direction
- Magnitude determines the rate of change

# Velocity and Acceleration

- We can set rules/relationships between position, velocity and acceleration to model physical behavior
- For now, we'll work with an intuitive approximation of Newton's laws of motion:
  - Velocity increments position
  - Acceleration increments velocity

# Velocity and Acceleration Example

```
float y = 0.0;

float r = 30.0;

float vel = 0.0;

float accel = 0.03;


void setup() {
  size(500, 500);
}

void draw() {
 ellipse(250, y, r, r);
  vel += accel;
  y += vel;
  if (y > height) {
    y = 0.0;
  }
}
```

# Observations

- Changes in position are initially small but increase throughout the simulation
- The object's speed will increase indefinitely (there is no limit on either acceleration or velocity)
- There is no concept of object mass so we are not conserving momentum (F != ma in our example)
- We need more rules to create more interesting behavior

# Question

- What are additional forces we can apply to our object?

# Other Forces

- Gravity is a downward force
- Friction is an opposing force (vector points in the opposite direction of the velocity)
- Spring compression is the force needed to compress a spring (Hooke's Law)
- Coefficient of restitution describes the loss of energy upon collision

# Adding Restitution

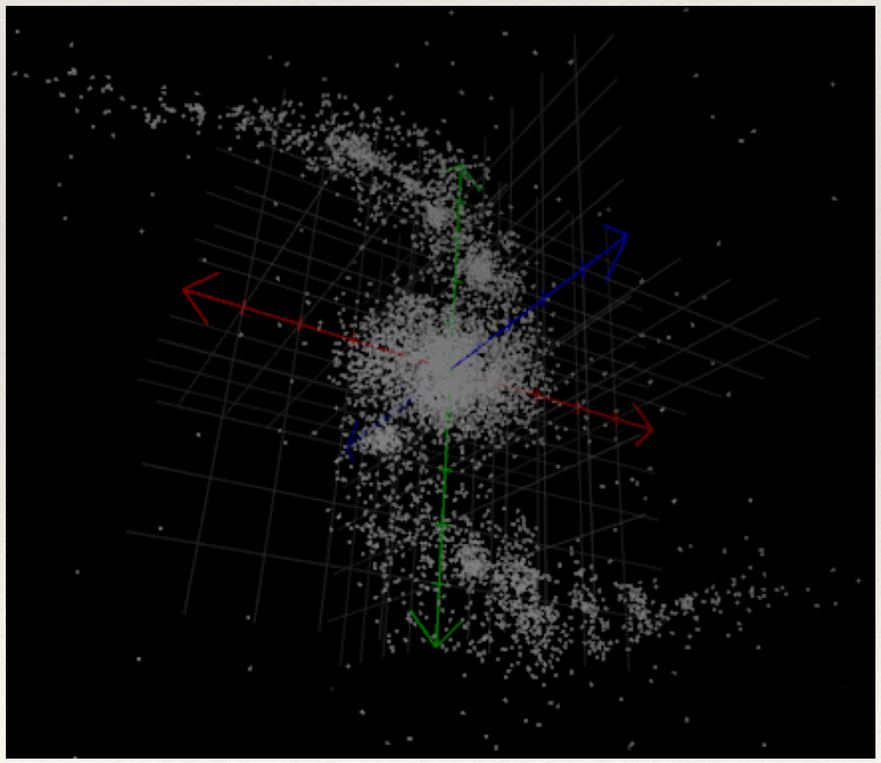
```
float y = 50.0;
float r = 15.0;
float vel = 0.0;
float accel = 0.03;
float friction = 0.995;

void setup() {
  size(500, 500);
  ellipseMode(RADIUS);
}

void draw() {
  background(210);
  ellipse(250, y, r, r);
  vel += accel;
  vel *= friction;
  y += vel;
  if (y > (height - r)) {
    vel = -vel;
  }
}
```

# Particle Systems

- System dictating movement of particles within the world
- Simulation of water, smoke, fire, clouds, dust, cloth, crowds, galaxies etc



(PyParticles)

(Houdini)

# Example Particle Class

```
class Particle {

  PVector pos;

  PVector vel;

  float r;


  Particle(float x, float y,
float vx, float vy, float r) {

    pos = new PVector(x, y);

    vel = new PVector(vx, vy);

    this.r = r;

  }
```

```
  void applyForces(float fx,
float fy) {

    vel.x += fx;

    vel.y += fy;

    pos.x += vel.x;

    pos.y += vel.y;

  }


  void display() {

    ellipse(pos.x, pos.y, r, r);

  }

}
```

# Discuss…

- What properties do Particle objects have?
- How can we use Particle objects in our main draw loop?

# Extending the Particle Class

- Additional rules can create increasingly complex behaviors and visualizations:
  - Continuous generation of particles
  - Changes to particle appearance
  - Application of additional forces or functions on the particles
- Note that these things don't have to be physically-based!

# Instapoll Question: Forces

- Name at least 2 forces that affect particle movement

# Hands-on: Forces and Particle Systems

- Today's activities:

1. Implement the base Particle class. Create a single particle that moves according to the `applyForces` method

2. Extend the particle class to create one of the following behaviors: 1) a fountain of particles that continuously "respawns" after they are off the screen, or 2) a fountain of particles that bounce against the sides of the screen