

CS354P

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OVERVIEW: AI

ARTIFICIAL INTELLIGENCE (AI)

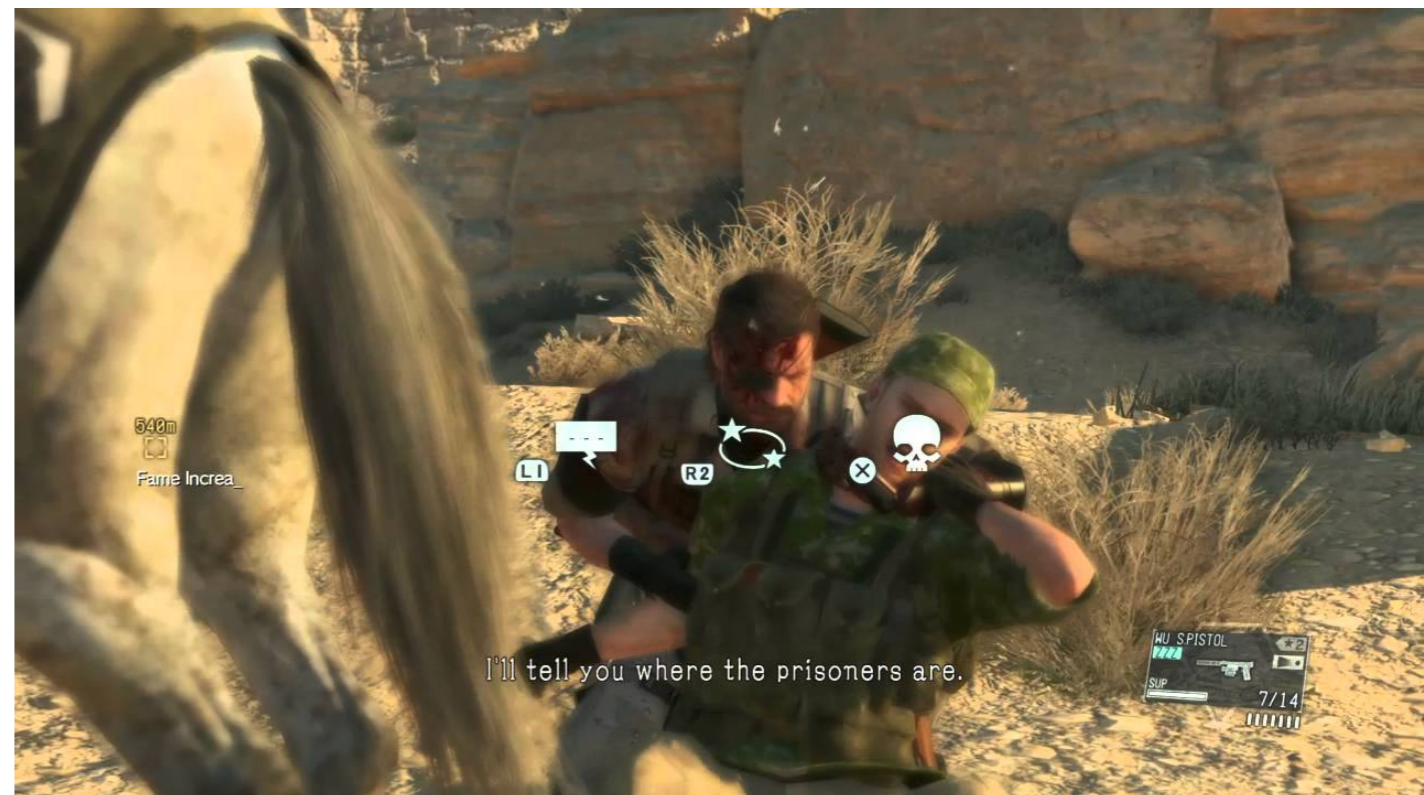
- ▶ Broad category of non-player-controller agents in the game that follow some set of rules
 - ▶ Bots in an arena shooter
 - ▶ Other cars in a racing game
 - ▶ Ally NPCs in an open world game
 - ▶ Enemies in an RPG
 - ▶ Computer-controlled opponents in board and card games

A FINE LINE...

- ▶ The distinction between a scripted event and an AI system is a fine one
 - ▶ Very primitive AI can be hand-scripted
 - ▶ Limitations in technology make earlier AI much more simplistic than modern AI



Metal Gear



Metal Gear Solid V

THEN WHAT MAKES IT INTELLIGENT?

- ▶ Awareness of the state of the world
 - ▶ Understands concepts such as terrain, player state, and own current state
- ▶ Ability to react in a way that reflects this understanding
 - ▶ Reacts in a way that the player can interpret as intelligent



Detroit: Become Human

AI REQUIRES AT LEAST SOME COMPLEXITY OF BEHAVIORS



THREE STAGES OF AI LOOP

- ▶ Sensing
 - ▶ Taking in information about the world state
- ▶ Thinking
 - ▶ Determining best course of action based on the world state
 - ▶ Note that “best” is not necessarily mathematically optimal even in cases where we can calculate optimal
- ▶ Acting
 - ▶ Performing the necessary steps to complete the chosen action
 - ▶ If action is not completable, agent may have to sense and think to determine new best action

AI SENSING

- ▶ Agent retrieves information from the world
 - ▶ When to retrieve?
 - ▶ What to retrieve?
 - ▶ How to retrieve?

AI POLLING AND EVENTS

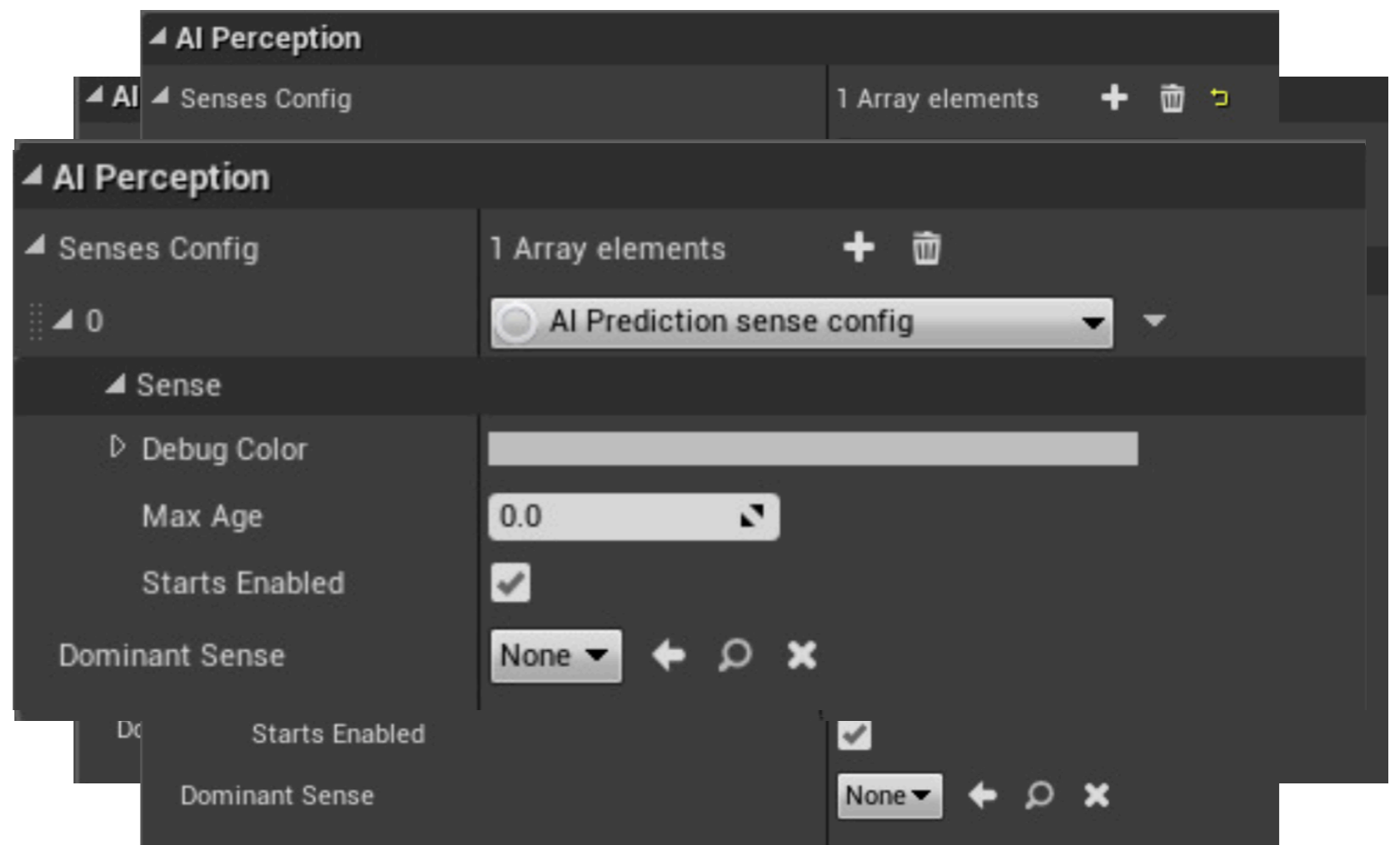
- ▶ In polling model, agent examines the world state at a fixed rate
 - ▶ Looks for changes in the world and updates working knowledge accordingly
- ▶ In event-driven model, agent receives information based on changes in the world state
 - ▶ Notified when a change in the world occurs and updates working knowledge accordingly
- ▶ Can use a combination of both as necessary

UNREAL: AI PERCEPTION COMPONENT

- ▶ Component that can be attached to a Pawn
- ▶ Defines:
 - ▶ What the sense to listen for
 - ▶ Sensor parameterization
 - ▶ How to respond
- ▶ Response handled through events

UNREAL: AI PERCEPTION COMPONENT SENSES

- ▶ Multiple senses can be added to a component
 - ▶ Choose subset based on project requirements
- ▶ Senses are:
 - ▶ Damage
 - ▶ Hearing
 - ▶ Sight
 - ▶ Touch
 - ▶ Team
 - ▶ Prediction



UNREAL: ENVIRONMENTAL QUERY SYSTEM (EQS)

- ▶ Experimental system for collecting data from the environment to inform agent decision-making
 - ▶ Generator nodes collect information about the world state
 - ▶ Test nodes define how to process that information
 - ▶ Results of tests inform agent how to react
- ▶ Example: Teammate AI looks for health pick-ups when the player's health is low while remaining out of enemy's line of sight

AI SENSING CONSIDERATIONS

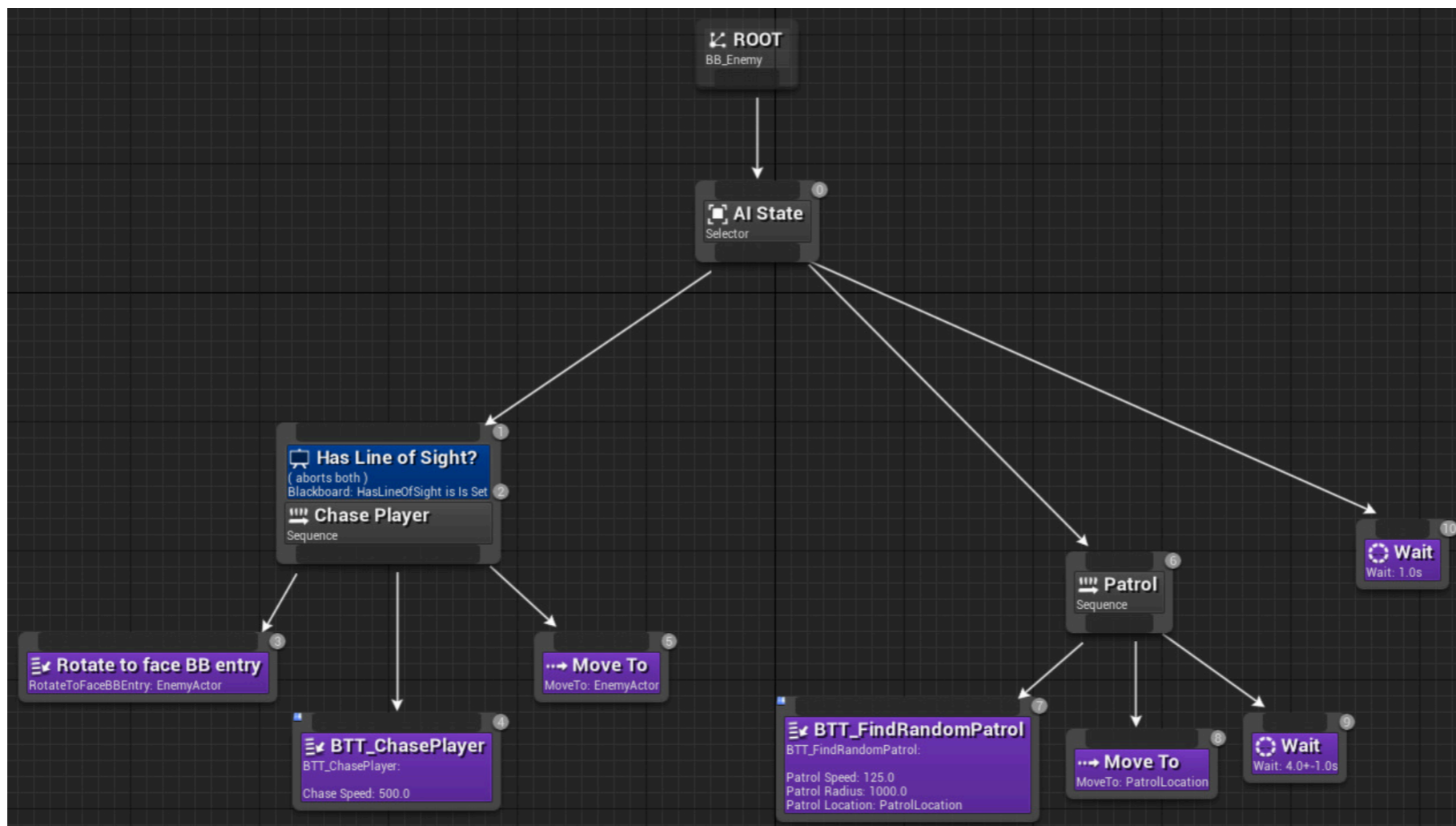
- ▶ The world state of even smallish games is very large
- ▶ Too expensive to poll frequently or query too much information
- ▶ Determine what is important for the agent to know to create a compelling experience
- ▶ Try to access this information only when necessary
 - ▶ e.g. When the player is on the other side of the map, turn off agents' sensors

AI THINKING

- ▶ Agent takes working knowledge about the world state and determines next action
 - ▶ What is the action?
 - ▶ Does this action require secondary actions?
 - ▶ How much time to process?
 - ▶ How to process?

BEHAVIOR TREES

- ▶ Current industry standard data structure for working with AI
 - ▶ Hierarchical tree that encapsulates all possible behaviors based on world and agent state



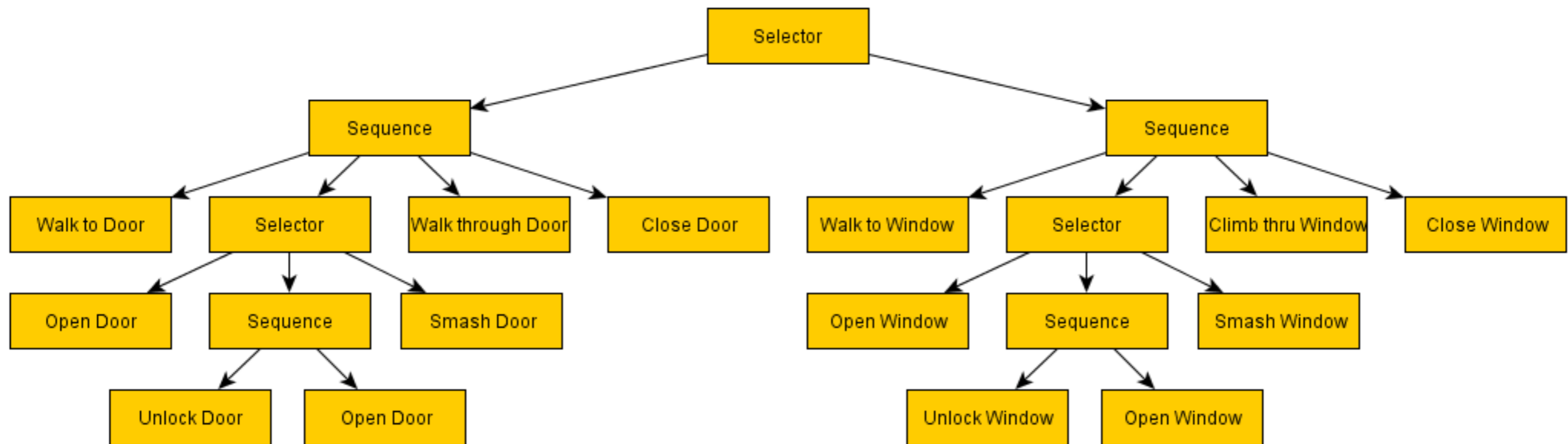
BEHAVIOR TREES NODES

- ▶ Nodes can be in the following states:
 - ▶ Succeeded, Failed, Running
- ▶ Parent node executes child nodes in a given order
 - ▶ While a child is being processed, it and its parent are in the Running state
 - ▶ When a child fails or succeeds based on conditionals, it passes this information to its parent
- ▶ Note that we are **not** completely traversing the tree in a time step
 - ▶ Can remain in a running sub-node for as long as it takes to resolve

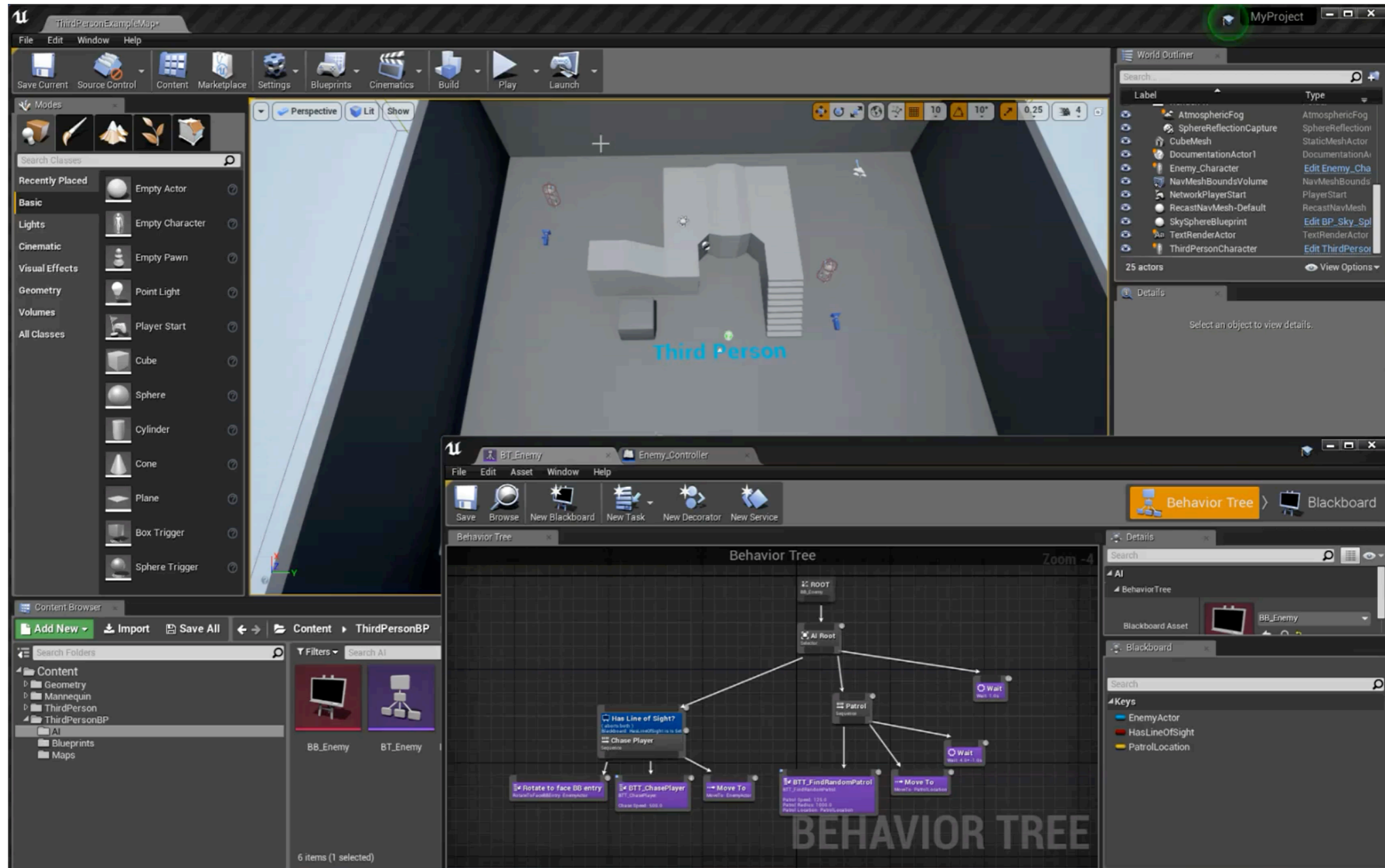
NODE TASKS

- ▶ Each node has a task or tasks, which define its behavior
- ▶ **Actions** define what the agent can do, including playing animations, moving, interacting, etc
- ▶ **Conditionals** determine if world/agent properties are in a specific state (often determine success or failure state of nodes)
- ▶ **Composites** are parent nodes that have 1 or more child nodes
 - ▶ Can check conditionals, and determine what order to execute child nodes in, etc
- ▶ **Decorators** can have one child
 - ▶ Modifies child behavior in some way (executes child multiple times, provides interrupts, continues to run child until it is successful, etc)

BEHAVIOR TREE EXAMPLE



UE4 DEMO



<https://www.youtube.com/watch?v=I60i4YLwqD8>

UNREAL BEHAVIOR TREES

- ▶ Nomenclature and structure is a little different from the “standard” behavior trees
- ▶ Composite nodes are branch nodes
 - ▶ Determine basic rules of the tree
- ▶ Task nodes are leaf nodes
 - ▶ Perform actions
- ▶ Decorator nodes are *attached* to other nodes and determine if branch can be executed (functionally conditional nodes)
- ▶ Service nodes are *attached* to composite nodes and can update agent’s world knowledge and can execute children in parallel

UNREAL: BLACKBOARD

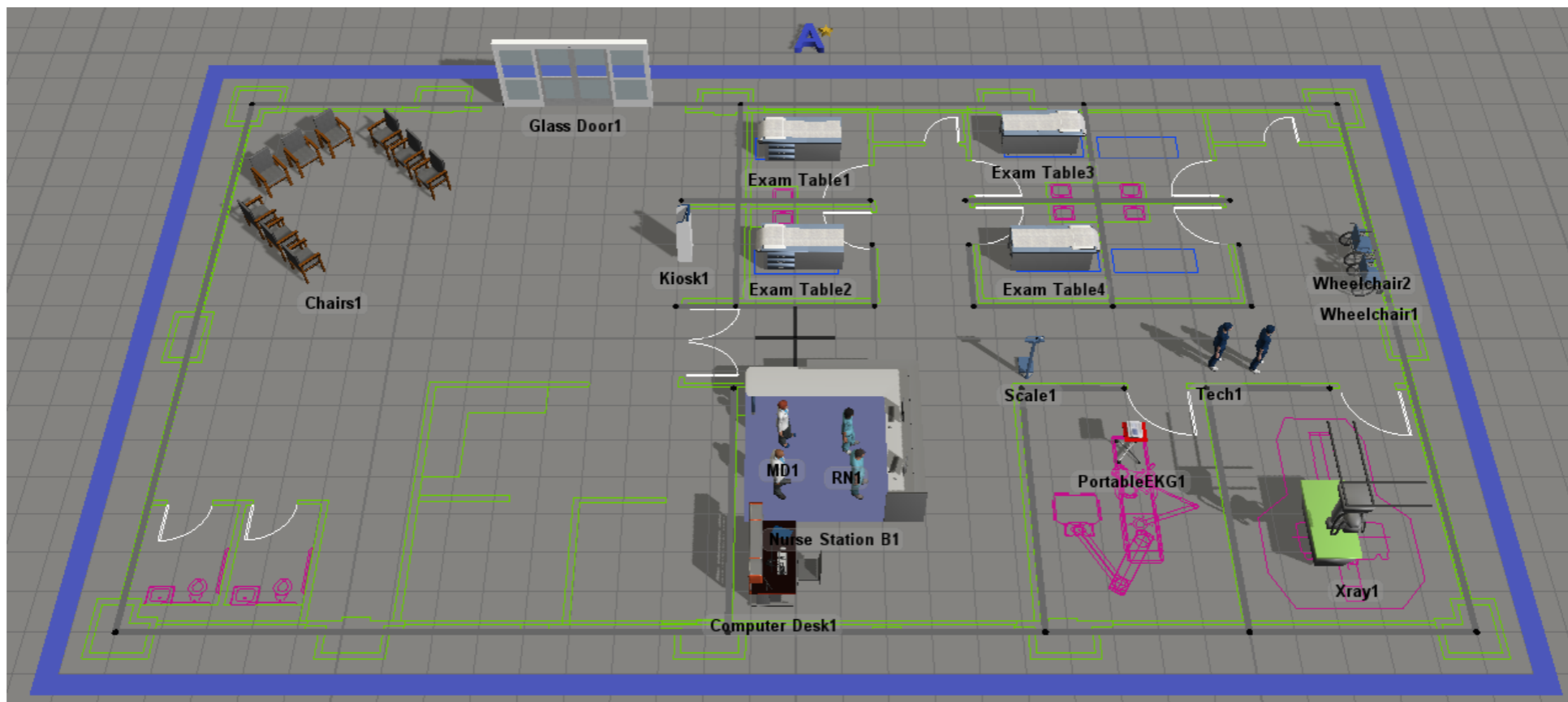
- ▶ World knowledge is everything that the agent knows
- ▶ Knowledge can be stored in a Blackboard as keys for accessible reading and writing
 - ▶ Knowledge can be local to one agent or a squad of agents
- ▶ Changes in keys can trigger events
 - ▶ Behavior trees in UE5 are event driven rather than tick-based
- ▶ Calculations can be cached for better responsiveness
- ▶ Centralized location of data results in fewer levels of indirection to access data

AI ACTIONS

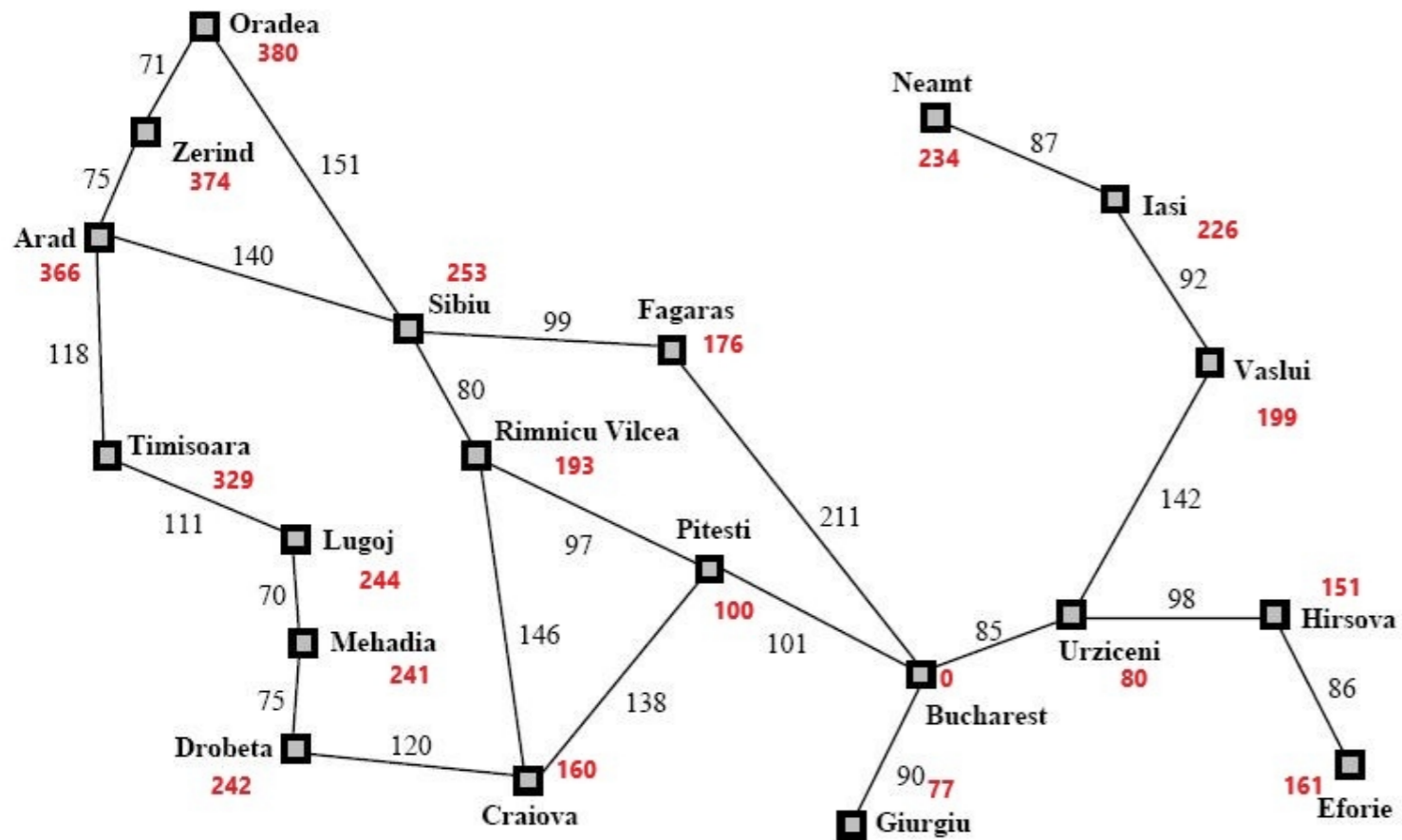
- ▶ Once a decision has been reached, the agent must perform the action
 - ▶ Update agent state
 - ▶ Play associated agent animation
 - ▶ Perform associated agent action
- ▶ One important action is navigation
 - ▶ How do we *convincingly* move the AI throughout the world?

NAVIGATION

- ▶ Agents use pathing algorithms to navigate through the world
- ▶ Problem: how do I get from point A to point B?
 - ▶ Constraints: respect obstacles and emulate human choices

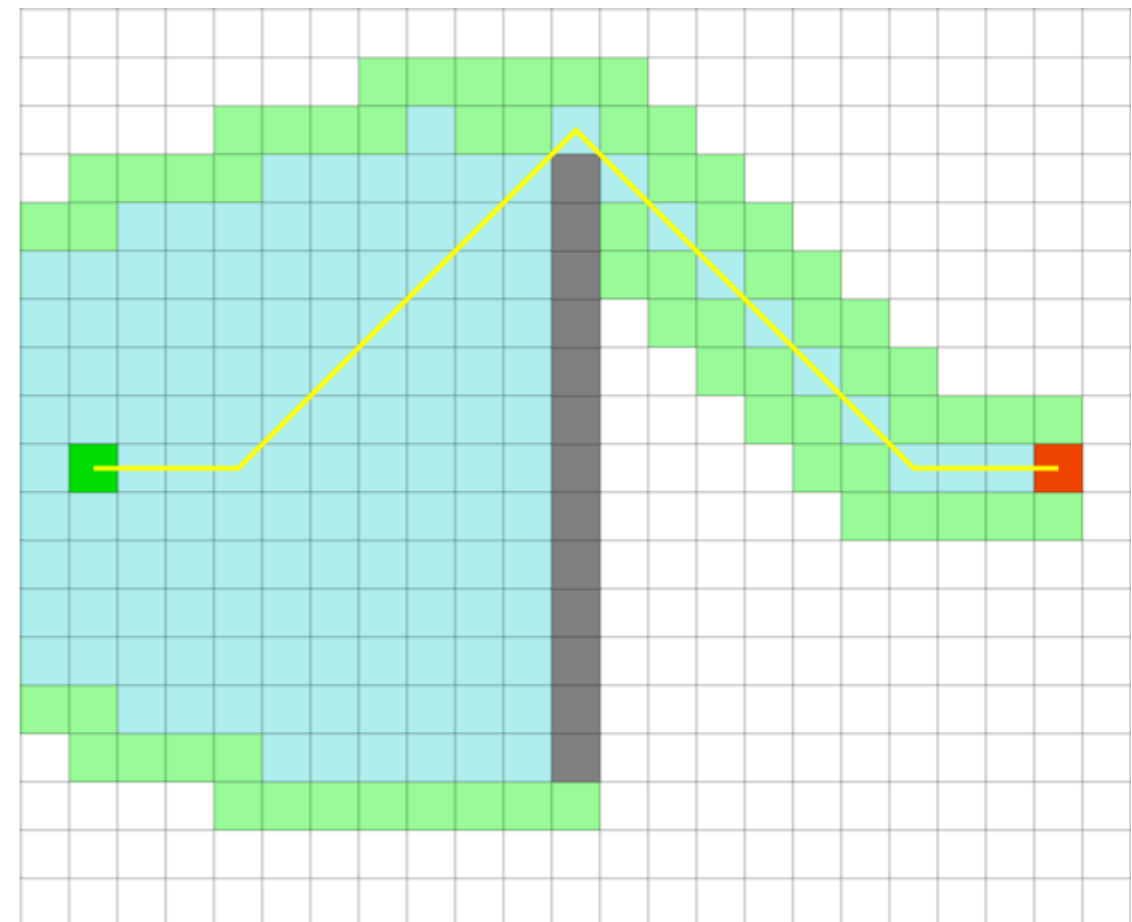


A TYPE OF GRAPH PROBLEM



Node-based

Grid-based



A* PATHFINDING

- ▶ De facto algorithm for agent navigation in games
- ▶ Considers two functions to optimize:
 - ▶ $g(n)$: Current best **cost** for getting **to** a node from the start
 - ▶ $h(n)$: Current best **estimate** for how much more it will cost to reach the goal **from** a node
- ▶ Heuristic used for $h(n)$ determines optimality and efficiency

A* CHALLENGES

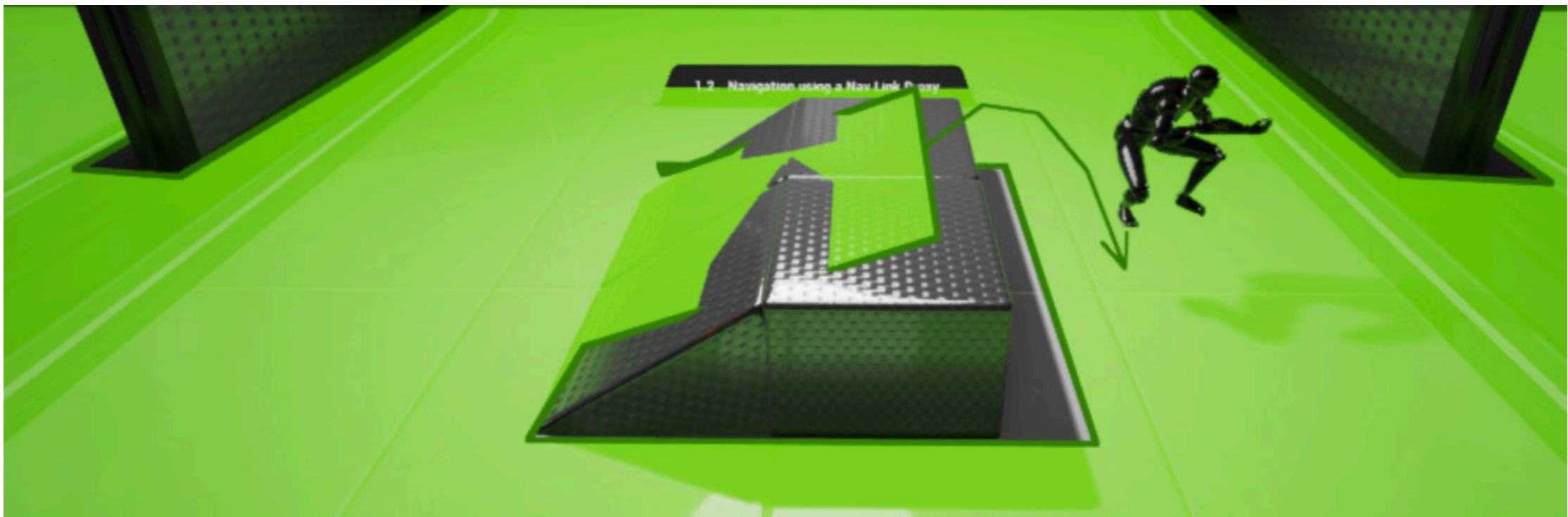
- ▶ Expensive to do across large areas
 - ▶ Use of waypoints and hierarchical planning to reduce state complexity
- ▶ Must consider how to replan if world state changes
 - ▶ Player or other agents change position
 - ▶ World contains dynamic or destructible obstacles
- ▶ Must store data efficiently to handle multiple agents

NAVMESHES

- ▶ Navigation meshes (navmeshes) aid in the computation of paths for AI agents
- ▶ Create a polygon mesh that defines where agents can walk
 - ▶ Polygons provide nodes for calculating A*
 - ▶ Can traverse the polygon itself along a linear path
- ▶ Simplifies collision detection (if placed properly, ensures agent will not collide with geometry)
- ▶ Generated automatically or hand-created by designer

UE5 NAVMESHERS

- ▶ Provides all basic features for agent traversal
- ▶ Can be placed in editor (no need for lower level programming)
- ▶ Challenge is for the designer to make it compelling and functional



CROWD SIMULATION

- ▶ Large number of agents navigating world, avoiding each other and player, and engaging in different goals
 - ▶ Often treated as a “particle system” using rules and forces



FURTHER READING

- ▶ What is a Behavior Tree? <<https://opsive.com/support/documentation/behavior-designer/what-is-a-behavior-tree/>>
- ▶ Behavior Trees for AI: How they work<https://www.gamasutra.com/blogs/ChrisSimpson/20140717/221339/Behavior_trees_for_AI_How_they_work.php>
- ▶ UE4 Behavior Tree Documentation <<https://docs.unrealengine.com/en-US/Engine/ArtificialIntelligence/BehaviorTrees/index.html>>
- ▶ UE4 NavMeshes <<https://docs.unrealengine.com/en-US/Resources/ContentExamples/NavMesh/index.html>>